

System of Simultaneous Linear Equations.

5.10.16

Example:

$$\begin{cases} \frac{dx}{dt} + \frac{dy}{dt} + 2x + y = 0 \\ \frac{dy}{dt} + 5x + 3y = 0. \end{cases}$$

Sol:

$$D = \frac{d}{dt}.$$

$$\rightarrow \begin{cases} (D+2)x + (D+1)y = 0. \\ 5x + (D+3)y = 0. \end{cases}$$

$$5(D+2)x + 5(D+1)y = 0.$$

$$5(D+2)x + (D+2)(D+3)y = 0.$$

$$(D^2+1)y = 0.$$

$$m = \pm i$$

$$\boxed{y = A \cos t + B \sin t,}$$

A, B arb. const.

$$\rightarrow x = -\frac{1}{5}(D+3)y$$

$$= -\frac{1}{5} [\dots]$$

Example:

$$\frac{dx}{x^2 - y^2 - z^2} = \frac{dy}{2xy} = \frac{dz}{2xz}$$

$$\frac{dy}{dx} = \frac{2xy}{x^2 - y^2 - z^2}$$

$$\frac{dz}{dx} = \frac{2xz}{x^2 - y^2 - z^2}$$

$$= \frac{x dx + y dy + z dz}{x(x^2 - y^2 - z^2) + y(2xy) + z(2xz)}$$

$$= \frac{\frac{1}{2} d(x^2 + y^2 + z^2)}{x[x^2 - y^2 - z^2 + 2y^2 + 2z^2]}$$

$$= \frac{d(x^2 + y^2 + z^2)}{2x(x^2 + y^2 + z^2)}$$

$$\frac{dy}{y} = \frac{dz}{z} \Rightarrow \log y = \log z + \log c \quad \text{①}$$

$$y = cz, \quad c \text{ const.}$$

$$\frac{dz}{2xz} = \frac{d(x^2 + y^2 + z^2)}{2x(x^2 + y^2 + z^2)}$$

$$\log z = \log(x^2 + y^2 + z^2) + \log c' \quad c' \text{ const.} \quad \text{②}$$

$$\Rightarrow \boxed{x^2 + y^2 + z^2 = \frac{z}{c'}} \quad \text{--- ②}$$

①, ② gives the complete solⁿ.

Exercin.

$$\left. \begin{aligned} \frac{d^2 x}{dt^2} - 3x - 4y &= 0 \\ \frac{d^2 y}{dt^2} + x + y &= 0 \end{aligned} \right\}$$

or

$$\left. \begin{aligned} (D^2 - 3)x - 4y &= 0 \\ x + (D^2 + 1)y &= 0 \end{aligned} \right\} \quad D \equiv \frac{d}{dt}$$

Exercin

$$\frac{dx}{mx - ny} = \frac{dy}{nx - ly} = \frac{dz}{ly - mx}$$

Example:

①

$$\left\{ \begin{aligned} \frac{dx}{dt} &= y + z \\ \frac{dy}{dt} &= x + z \\ \frac{dz}{dt} &= x + y \end{aligned} \right.$$

Try to reduce the system of eqnⁿ.
① to a single eqnⁿ with const. coefficients in single variable

$$\rightarrow \frac{d^2x}{dt^2} = \frac{dy}{dt} + \frac{dz}{dt}.$$

$$= x + z + x + y.$$

$$= 2x + (z + y)$$

$$= 2x + \frac{dx}{dt}$$

$$\frac{d^2x}{dt^2} - \frac{dx}{dt} - 2x = 0.$$

$$(D^2 - D - 2)x = 0.$$

$$x = e^{mt}.$$

$$m^2 - m - 2 = 0.$$

$$m = -1, 2.$$

$$x = C_1 e^{-t} + C_2 e^{2t},$$

C_1, C_2 arb. const.

$$\frac{dx}{dt} = -C_1 e^{-t} + 2C_2 e^{2t}.$$

$$y + z = -C_1 e^{-t} + 2C_2 e^{2t}.$$

$$y = -(C_1 + C_2) e^{-t} + C_2 e^{2t}.$$

$$z = C_3 e^{-t} + C_2 e^{2t}$$

Exerim. Find the general solⁿ of the following system of DEs.

$$\left. \begin{aligned} \frac{d^2 y}{dx^2} &= z \\ \frac{dz}{dx} &= y \end{aligned} \right\}$$

highest derivative
having deg. 1

System of homogeneous Linear DE with const. coefficients.

$$\textcircled{1} \quad \begin{cases} \frac{dx_1}{dt} = a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ \frac{dx_2}{dt} = a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n \\ \vdots \\ \frac{dx_n}{dt} = a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n \end{cases}$$

- n eqns. in n unknowns $x_1, \dots, x_n$
- a_{ij} are const.

Approach I. Reducing ① to a single eqn. of order n in single variable $\swarrow$ which is linear hom. eqn. with const. coefficients.

Solve it $\rightarrow$

Approach II. (Without reducing ① to an eqn. of n -th. order).

- Seek for a particular soln. of ① in the following form.

$$x_1 = \alpha_1 e^{kt}, x_2 = \alpha_2 e^{kt}, \dots, x_n = \alpha_n e^{kt} \quad \text{②}$$

$$\begin{cases} k x_1 e^{kt} = (a_{11} x_1 + a_{12} x_2 + \dots + a_{1n} x_n) e^{kt} \\ k x_2 e^{kt} = (a_{21} x_1 + a_{22} x_2 + \dots + a_{2n} x_n) e^{kt} \\ \vdots \\ k x_n e^{kt} = (a_{n1} x_1 + a_{n2} x_2 + \dots + a_{nn} x_n) e^{kt}. \end{cases}$$

$$\textcircled{3} - \begin{cases} (-k + a_{11}) x_1 + a_{12} x_2 + \dots + a_{1n} x_n = 0 \\ a_{21} x_1 + (-k + a_{22}) x_2 + \dots + a_{2n} x_n = 0 \\ \vdots \\ a_{n1} x_1 + a_{n2} x_2 + \dots + (a_{nn} - k) x_n = 0. \end{cases}$$

$$\begin{pmatrix} -k + a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & -k + a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & -k + a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$\Delta(k) = \begin{vmatrix} -k+a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & -k+a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{n1} & a_{n2} & \dots & -k+a_{nn} \end{vmatrix}$$

• $\Delta(k) \neq 0 \Rightarrow$ ③ has only trivial solⁿ. $d_1 = d_2 = \dots = d_n = 0$

$x_1(t) = 0 = x_2(t) = \dots = x_n(t)$
only trivial solⁿ.

• ③ has non-trivial solⁿ only for k s.t. $\Delta(k) = 0$.

④.

auxiliary eqⁿ.

✓
real, distinct

Complex, distinct

equal.
(Real / complex)

A) The roots of the auxiliary eqn. are real & distinct.

• $\Delta(k) = 0 \rightarrow k_1, k_2, \dots, k_n$
(all distinct, real).

$(k_i) \rightarrow \alpha_1^{(i)}, \alpha_2^{(i)}, \dots, \alpha_n^{(i)}$

$$(\Delta(k)) \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}.$$

$$\rightarrow \begin{cases} x_1 = \alpha_1^{(i)} e^{k_i t}, & x_2 = \alpha_2^{(i)} e^{k_i t}, \dots \\ x_n = \alpha_n^{(i)} e^{k_i t} \end{cases}$$

General soln. of ①.

$$x_1 = \sum_{i=1}^n C_i \alpha_1^{(i)} e^{k_i t}$$

$$x_2 = \sum_{i=1}^n C_i \alpha_2^{(i)} e^{k_i t}$$

$$\vdots$$
$$x_n = \sum_{i=1}^n C_i \alpha_n^{(i)} e^{k_i t}$$

$C_1, C_2, \dots, C_n$
arb. const.

Example:

$$\left. \begin{aligned} \frac{dx_1}{dt} &= 2x_1 + 2x_2 \\ \frac{dx_2}{dt} &= x_1 + 3x_2 \end{aligned} \right\} - \textcircled{1}.$$

Solve using eigen-value approach.
Without reducing $\textcircled{1}$ to an eqn.
of higher order in a single
variable.

$$\Delta(k) = 0.$$

finds $\downarrow$
roots

$\downarrow$
find $\lambda_1, \dots, \lambda_n$
Cor. to each k .

~~$$\Delta(k) = -k+2$$~~

$$\Delta(k) = \begin{vmatrix} 2-k & 2 \\ 1 & 3-k \end{vmatrix} = 0.$$

$$k = 1, 4.$$

$$\underline{k_1 = 4}$$

$$\begin{pmatrix} 2-4 & 2 \\ 1 & 3-4 \end{pmatrix} \begin{pmatrix} x_1^{(1)} \\ x_2^{(1)} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

$$-2x_1^{(1)} + 2x_2^{(1)} = 0.$$

$$x_1^{(1)} - x_2^{(1)} = 0 \Rightarrow x_1^{(1)} = x_2^{(1)}.$$

Take $x_1^{(1)} = 1.$ → Can be set any arb. const.

$$\Rightarrow x_2^{(1)} = 1.$$

$$\therefore \boxed{x_1^{(1)} = x_1^{(1)} e^{k_1 t} = e^{4t}}, \quad x_2^{(1)} = x_2^{(1)} e^{k_1 t} = e^{4t}.$$

$$\underline{k_2 = 1} \rightarrow$$

$$\begin{pmatrix} 2-1 & 2 \\ 1 & 3-1 \end{pmatrix} \begin{pmatrix} x_1^{(2)} \\ x_2^{(2)} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

$$\boxed{x_1^{(2)} = e^t}$$

$$x_2^{(2)} = -\frac{1}{2} e^t.$$

$\therefore$ General solⁿ. of (1) is

$$x_1 = C_1 e^{4t} + C_2 e^t.$$

$$x_2 = C_1 e^{4t} + \frac{C_2}{2} e^t.$$

Example:

$$\frac{dx}{dt} = a_{11}x + a_{12}y$$

$$\frac{dy}{dt} = a_{21}x + a_{22}y.$$

auxiliary eqn.

$$\begin{vmatrix} a_{11}-k^2 & a_{12} \\ a_{21} & a_{22}-k^2 \end{vmatrix} = 0.$$

using sol^{ns}. of the type.

$$x = \alpha e^{kt}, \quad y = \beta e^{kt}.$$

Case B. Complex, ~~and~~ ~~unequal~~ unequal roots.

$$k_1 = \alpha + i\beta, \quad k_2 = \alpha - i\beta.$$

↓ cor. solⁿ.

$$k_1 \rightarrow x_j^{(1)} = \alpha_j^{(1)} e^{(\alpha + i\beta)t}$$

$$k_2 \rightarrow x_j^{(2)} = \alpha_j^{(2)} e^{(\alpha - i\beta)t}.$$

$\alpha_j^{(1)}, \alpha_j^{(2)}$ are determined from the system

$$\begin{pmatrix} \Delta(k) \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$$

↓ general sol.

$$e^{\alpha t} \left(\lambda_j^{(1)} \cos \beta t + \lambda_j^{(2)} \sin \beta t \right)$$

$$e^{\alpha t} \left(\overline{\lambda_j^{(1)}} \cos \beta t + \overline{\lambda_j^{(2)}} \sin \beta t \right)$$

$$\lambda_j^{(1)}, \lambda_j^{(2)}, \overline{\lambda_j^{(1)}}, \overline{\lambda_j^{(2)}} \rightarrow \text{const.}$$

Exercise

$$\frac{dx_1}{dt} = -7x_1 + x_2$$

$$\frac{dx_2}{dt} = -2x_1 - 5x_2$$

$$\kappa = -6 \pm i$$