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# Matchings and Factors

# Matchings

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- A *matching* of size  $k$  in a graph  $G$  is a set of  $k$  pairwise disjoint edges.
  - The vertices belonging to the edges of a matching are *saturated* by the matching; the others are *unsaturated*.
  - If a matching saturates every vertex of  $G$ , then it is a *perfect matching* or *1-factor*.

# Alternating Paths

- Given a matching  $M$ , an  *$M$ -alternating path* is a path that alternates between the edges in  $M$  and the edges not in  $M$ .
  - An  $M$ -alternating path  $P$  that begins and ends at  $M$ -unsaturated vertices is an  *$M$ -augmenting path*
  - Replacing  $M \cap E(P)$  by  $E(P) - M$  produces a new matching  $M'$  with one more edge than  $M$ .

# Symmetric Difference

- If  $G$  and  $H$  are graphs with vertex set  $V$ , then the *symmetric difference*  $G \Delta H$  is the graph with vertex set  $V$  whose edges are all those edges appearing in exactly one of  $G$  and  $H$ .
  - If  $M$  and  $M'$  are matchings, then
$$M \Delta M' = (M \cup M') - (M \cap M')$$

# Key result

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- A matching  $M$  in a graph  $G$  is a *maximum matching* in  $G$  iff  $G$  has no  $M$ -augmenting path.

# Bipartite Matching

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When  $G$  is a bipartite graph with bipartition  $X, Y$  we may ask whether  $G$  has a matching that saturates  $X$ .

- We call this a matching of  $X$  into  $Y$ .

# Results...

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- [Hall's Theorem: 1935]

If  $G$  is a bipartite graph with bipartition  $X, Y$ , then  $G$  has a matching of  $X$  into  $Y$  if and only if  $|N(S)| \geq |S|$  for all  $S \subseteq X$ .

- For  $k > 0$ , every  $k$ -regular bipartite graph has a perfect matching.

# Vertex Cover & Bipartite Matching

- A *vertex cover* of  $G$  is a set  $S$  of vertices such that  $S$  contains at least one endpoint of every edge of  $G$ .
  - The vertices in  $S$  *cover* the edges of  $G$ .
- If  $G$  is a bipartite graph, then the maximum size of a matching in  $G$  equals the minimum size of a vertex cover of  $G$ .

[König and Egerváry: 1931]



# Edge Cover

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- An *edge cover* of  $G$  is a set of edges that cover the vertices of  $G$ .
  - only graphs without isolated vertices have edge covers.

# Notation...

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- We will use the following notation for independence and covering problems

$\alpha(\mathbf{G})$  :            **maximum size of independent set**

$\alpha'(\mathbf{G})$  :            **maximum size of matching**

$\beta(\mathbf{G})$  :                **minimum size of vertex cover**

$\beta'(\mathbf{G})$  :                **minimum size of edge cover**

# Min-max Theorems

- In a graph  $G$ ,  $S \subseteq V(G)$  is an independent set if and only if  $S'$  is a vertex cover, and hence  $\alpha(G) + \beta(G) = n(G)$ .
- If  $G$  has no isolated vertices, then  $\alpha'(G) + \beta'(G) = n(G)$ .
- If  $G$  is a bipartite graph with no isolated vertices, then  $\alpha(G) = \beta'(G)$   
(max independent set = min edge cover)

# Augmenting Path Algorithm

## Input:

- A bipartite graph  $G$  with a bipartition  $X, Y$ , a matching  $M$  in  $G$ , and the set  $U$  of all  $M$ -unsaturated vertices in  $X$ .

## Idea:

- Explore  $M$ -alternating paths from  $U$ , letting  $S \subseteq X$  and  $T \subseteq Y$  be the sets of vertices reached.
- *Mark* vertices of  $S$  that have been explored for extending paths.
- For each  $x \in (S \cup T) - U$ , record the vertex before  $x$  on some  $M$ -alternating path from  $U$ .

# Augmenting Path Algorithm

Initialization: Set  $S=U$  and  $T=\phi$

Iteration:

- If  $S$  has no unmarked vertex, the stop and report  $T \cup (X-S)$  as a minimum cover and  $M$  as a maximum matching.
- Otherwise, select an unmarked  $x \in S$ .
- To explore  $x$ , consider each  $y \in N(x)$  such that  $xy \notin M$ . If  $y$  is unsaturated, terminate and trace back from  $y$  to report an  $M$ -augmenting path from  $U$  to  $y$ . Otherwise,  $y$  is matched to some  $w \in X$  by  $M$ . In this case, include  $y$  in  $T$  and  $w$  in  $S$ .
- After exploring all such edges incident to  $x$ , mark  $x$  and iterate.

# Augmenting Path Algorithm

- Repeated application of the Augmenting Path Algorithm to a bipartite graph produces a matching and vertex cover of the same size.
  - The complexity of the algorithm is  $O(n^3)$ .
  - Since matchings have at most  $n/2$  edges, we apply the augmenting path algorithm at most  $n/2$  times.
  - In each iteration, we search from a vertex of  $X$  at most once, before we mark it. Hence each iteration is  $O(e(G))$ , which is  $O(n^2)$ .

# Weighted Bipartite Matching

- A *transversal* of an  $n \times n$  matrix  $A$  consists of  $n$  positions – one in each row and each column.
  - Finding a transversal of  $A$  with maximum sum is the *assignment problem*.
  - This is the matrix formulation of the *maximum weighted matching problem*, where  $A$  is the matrix of weights  $w_{ij}$  assigned to the edges  $x_i y_j$  of  $K_{n,n}$  and we seek a perfect matching  $M$  with maximum total weight  $w(M)$ .

# Minimum Weighted Cover

- Given the weights  $\{w_{ij}\}$ , a *weighted cover* is a choice of labels  $\{u_i\}$  and  $\{v_j\}$  such that
$$u_i + v_j \geq w_{ij} \quad \text{for all } i,j.$$
- The *cost*  $c(u,v)$  of a cover  $u,v$  is  $\sum u_i + \sum v_j$ .
- The *minimum weighted cover problem* is the problem of finding a cover of minimum cost.



# Min Cover & Max Matching

- If  $M$  is a perfect matching in a weighted bipartite graph  $G$  and  $u, v$  is a cover, then  $c(u, v) \geq w(M)$ .
  - Furthermore,  $c(u, v) = w(M)$  if and only if  $M$  consists of edges  $x_i y_j$  such that  $u_i + v_j = w_{ij}$ . In this case,  $M$  is a maximum weight matching and  $u, v$  is a minimum weight cover.

# Hungarian Algorithm

**Input:** A matrix of weights on the edges of  $K_{n,n}$  with bipartition  $X, Y$ .

**Idea:** Maintain a cover  $u, v$ , iteratively reducing the cost of the cover until the equality subgraph  $G_{u,v}$  has a perfect matching.

**Initialization:** Let  $u, v$  be a feasible labeling, such as  $u_i = \max_j w_{ij}$  and  $v_j = 0$ , and find a maximum matching  $M$  in  $G_{u,v}$ .

# Hungarian Algorithm

## Iteration:

- If  $M$  is a perfect matching, stop and report  $M$  as a maximum weight matching.
- Otherwise, let  $U$  be the set of  $M$ -unsaturated vertices in  $X$ .
- Let  $S$  be the set of vertices in  $X$  and  $T$  the set of vertices in  $Y$  that are reachable by  $M$ -alternating paths from  $U$ . Let
$$\varepsilon = \min\{u_i + v_j - w_{ij} : x_i \in S, y_j \in Y - T\}$$
- Decrease  $u_i$  by  $\varepsilon$  for all  $x_i \in S$ , and increase  $v_j$  by  $\varepsilon$  for all  $y_j \in T$ . If the new equality subgraph  $G'$  contains an  $M$ -augmenting path, replace  $M$  by a maximum matching in  $G'$  and iterate. Otherwise, iterate without changing  $M$ .

# Hungarian Algorithm

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- The Hungarian Algorithm finds a maximum weight matching and a minimum cost cover.

# Stable Matchings

- Given  $n$  men and  $n$  women, we wish to establish  $n$  stable marriages.
  - If man  $x$  and woman  $a$  prefers each other over their existing partners, then they might leave their current partners and switch to each other.
  - In this case we say that the unmatched pair  $(x, a)$  is an unstable pair.
  - A perfect matching is a *stable matching* if it yields no unstable matched pair.

# Gale-Shapley Proposal Algorithm

**Input:** Preference rankings by each of  $n$  men and  $n$  women.

**Iteration:**

- Each man proposes to the highest woman on his preference list who has not previously rejected him.
- If each woman receives exactly one proposal, stop and use the resulting matching.
- Otherwise, every woman receiving more than one proposal rejects all of them except the one that is highest on her preference list.
- Every woman receiving a proposal says “*maybe*” to the most attractive proposal received.

*The algorithm produces a stable matching.*

# Matchings in General Graphs

- A *factor* of a graph  $G$  is a spanning sub-graph of  $G$ .
  - A  *$k$ -factor* is a spanning  *$k$ -regular* sub-graph.
  - An *odd component* of a graph is a component of odd order; the number of odd components of  $H$  is  $o(H)$ .
- [Tutte 1947]: A graph  $G$  has a 1-factor if and only if  $o(G - S) \leq |S|$  for every  $S \subseteq V(G)$ .
- [Peterson 1891]: Every 3-regular graph with no cut-edge has a 1-factor.

# Edmond's Blossom Algorithm

- Let  $M$  be a matching in a graph  $G$ , and let  $u$  be an  $M$ -unsaturated vertex.
- A *flower* is the union of two  $M$ -alternating paths from  $u$  that reach a vertex  $x$  on steps of opposite parity.
- The *stem* of the flower is the maximal common initial path.
- The *blossom* of the flower is the odd cycle obtained by deleting the stem.



# Edmond's Blossom Algorithm

**Input:** A graph  $G$ , a matching  $M$  in  $G$ , and an  $M$ -unsaturated vertex  $u$ .

**Initialization:**  $S = \{u\}$  and  $T = \{ \}$

**Iteration:**

- If  $S$  has no unmarked vertex, stop
- Otherwise, select an unmarked vertex  $v \in S$ . To explore from  $v$ , successively consider each  $y \in N(v)$  such that  $y \notin T$ .
- If  $y$  is unsaturated by  $M$ , then trace back from  $y$  to report an  $M$ -augmenting  $u, y$ -path.
- If  $y \in S$ , then a blossom has been found. Contract the blossom and continue the search from this vertex in the smaller graph.
- Otherwise,  $y$  is matched to some  $w$  by  $M$ . Include  $y$  in  $T$  (reached from  $v$ ), and include  $w$  in  $S$ .
- After exploring all such neighbors of  $v$ , mark  $v$  and iterate.