Learning:Neural Networks

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Neural Networks

 A neural network consists of a set of nodes (neurons/units) connected by links
Each link has a numeric weight

Each unit has:

- a set of input links from other units,
- ◆ a set of output links to other units,

a current activation level, and

 an activation function to compute the activation level in the next time step.

Basic definitions



Basic definitions

The total weighted input is the sum of the input activations times their respective weights:



In each step, we compute: $a_i \leftarrow g(in_i) = g(\sum_i W_{j,i}a_j)$

Learning in Single Layer Networks



W_{i.i}

 O_i

 If the output for a output unit is O, and the correct output should be T, then the error is given by:
Err = T – O

•The weight adjustment rule is: $W_j \leftarrow W_j + \alpha \ge I_j \ge Err$ where α is a constant called the learning rate

l_i

Learning in Single Layer Networks

- This method is unable to learn all types of functions
 - can learn only linearly separable functions
- Used in competitive learning

Two-layer Feed-Forward Network



Back-Propagation Learning

• $Err_i = (T_i - O_i)$ is the error at the output node

The weight update rule for the link from unit j to output unit i is:

 $W_{j,i} \leftarrow W_{j,i} + \alpha \ge a_j \ge Err_i \ge g'(in_i)$ where g' is the derivative of the activation function g.

Back-Propagation Learning

Let $\Delta_i = \operatorname{Err}_i g'(\operatorname{in}_i)$. Then we have:

$$W_{j,i} \leftarrow W_{j,i} + \alpha \times a_j \times \Delta_i$$

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Error Back-Propagation

- For updating the connections between the inputs and the hidden units, we need to define a quantity analogous to the error term for the output nodes
 - ◆ Hidden node j is responsible for some fraction of the error ∆_i each of the output nodes to which it connects

Error Back-Propagation

 So, the Δ_i values are divided according to the strength of the connection between the hidden node and the output node, and propagated back to provide the Δ_j values for the hidden layer

$\Delta_{j} = g'(in_{j})\sum_{i} W_{j,i}\Delta_{i}$

Error Back-Propagation

The weight update rule for weights between the inputs and the hidden layer is:

$$\mathsf{W}_{\mathsf{k},\mathsf{j}} \leftarrow \mathsf{W}_{\mathsf{k},\mathsf{j}} + \alpha \times \mathsf{I}_{\mathsf{k}} \times \Delta_{\mathsf{j}}$$

The theory

The total error is given by:

 $\mathsf{E} = \frac{1}{2} \sum_{i} (\mathsf{T}_{i} - \mathsf{O}_{i})^{2} = \frac{1}{2} \sum_{i} \left(\mathsf{T}_{i} - \mathsf{g}\left(\sum_{i} \mathsf{W}_{j,i} \mathsf{a}_{j}\right)\right)^{2}$ $= \frac{1}{2} \sum_{i} \left(\mathsf{T}_{i} - \mathsf{g} \left(\sum_{j} \mathsf{W}_{j,i} \left(\sum_{k} \mathsf{W}_{k,j} \mathsf{I}_{k} \right) \right) \right)^{2}$

The theory

Only one of the terms in the summation over i and j depends on a particular W_{j,i}, so all other terms are treated as constants with respect to W_{j,i}

$$\frac{\partial E}{\partial W_{j,i}} = -a_j (T_i - O_i) g' \left(\sum_j W_{j,i} a_j \right) = -a_j (T_i - O_i) g'(in_i) = -a_j \Delta_i$$

Similarly:
$$\frac{\partial E}{\partial W_{k,j}} = -I_k \Delta_j$$