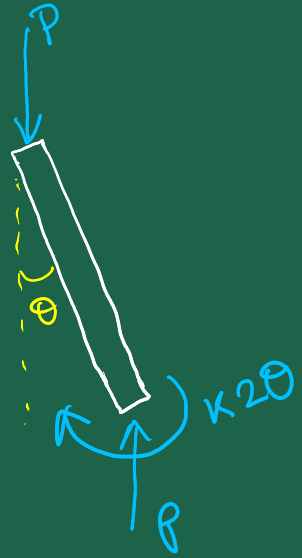
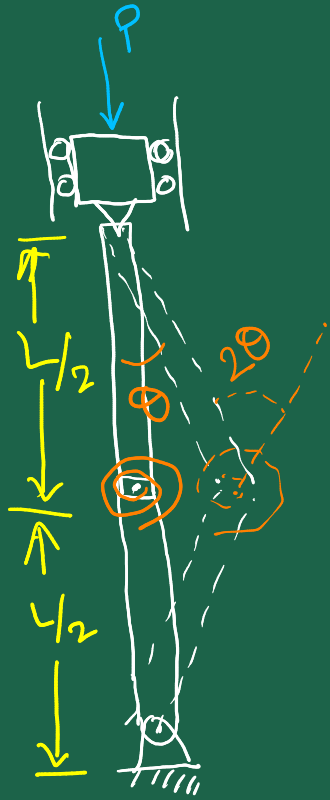


Buckling



$$P \frac{L}{2} \sin \theta - \kappa 2\theta = 0$$

$$\Rightarrow P \frac{L}{2} \sin \theta = \kappa 2\theta$$

θ small, $\sin \theta \approx \theta$

$$P \frac{L}{2} \theta = \kappa 2\theta$$

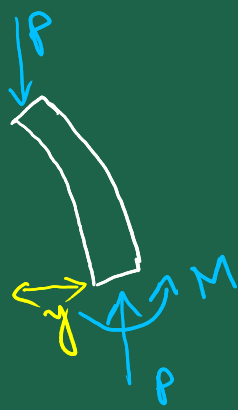
$$\Rightarrow P = \frac{4\kappa}{L} \rightarrow \text{Neutral eqn.}$$

$$P < \frac{4\kappa}{L} \rightarrow \text{stable}$$

$$P > \frac{4\kappa}{L} \rightarrow \text{unstable}$$



Vertical beam
Column



$$M = -Py$$

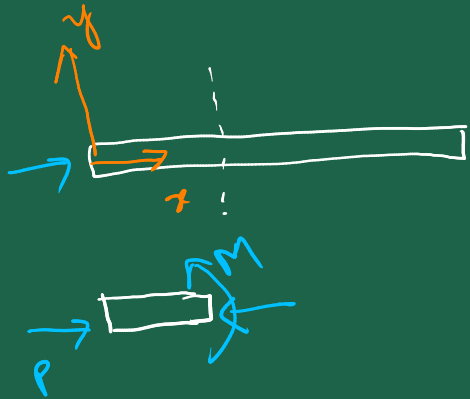
$$EI \frac{d^2 y}{dx^2} = M = -Py$$

$$\Rightarrow EI \frac{d^2 y}{dx^2} + Py = 0$$

$$\Rightarrow \frac{d^2 y}{dx^2} + \frac{P}{EI} y = 0$$

$$\text{Say } \frac{P}{EI} = k^2$$

$$\frac{d^2 y}{dx^2} + k^2 y = 0$$



$$\frac{d^2 y}{dx^2} + k^2 y = 0$$

Assume $y = e^{mx}$

$$m^2 e^{mx} + k^2 e^{mx} = 0$$

$$\Rightarrow m^2 + k^2 = 0$$

$$\Rightarrow m = \pm ki, \quad i = \sqrt{-1}$$

$$y = C_1 e^{m_1 x} + C_2 e^{m_2 x}$$

$$= C_1 e^{kix} + C_2 e^{-kix}$$

$$= C_1 (\cos kx + i \sin kx) + C_2 (\cos kx - i \sin kx)$$

$$= \underbrace{(C_1 + C_2)}_B \cos kx + \underbrace{(iC_1 - iC_2)}_A \sin kx = A \sin kx + B \cos kx$$

$$y = A \sin kx + B \cos kx$$

$$\text{@ } x=0, y=0 \Rightarrow B=0$$

$$\text{@ } x=L, y=0 \Rightarrow A \sin kL = 0$$

If $A=0$, $y=0$ (trivial)

For non-trivial solutions (bent shape!)

$$\sin kL = 0 \quad (\text{with } A \neq 0)$$

$$\Rightarrow kL = n\pi, \quad n=0, 1, 2, 3$$

$$\Rightarrow k = \frac{n\pi}{L}$$

$$k = \frac{n\pi}{L} \quad (KL = \pi)$$

$$\Rightarrow k^2 = \frac{n^2\pi^2}{L^2}$$

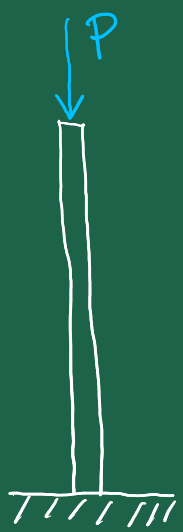
$$\Rightarrow \frac{P}{EI} = \frac{n^2\pi^2}{L^2}$$

$$\Rightarrow P = \frac{n^2\pi^2 EI}{L^2} \rightarrow \text{Critical values}$$

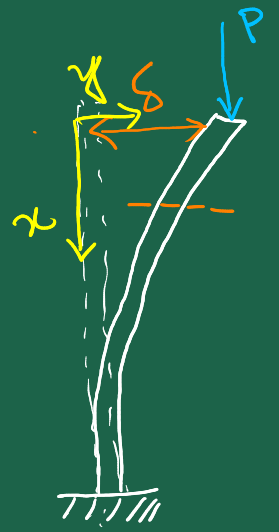
$$n=1 \rightarrow \boxed{P_{cr} = \frac{\pi^2 EI}{L^2}} \rightarrow \begin{array}{l} \text{Euler's load} \\ \text{Euler's critical buckling formula} \end{array}$$

(Remember that this is only for pinned-pinned end)

#2



$$L_{eff} = 2L$$



$$M = P(\delta - y)$$

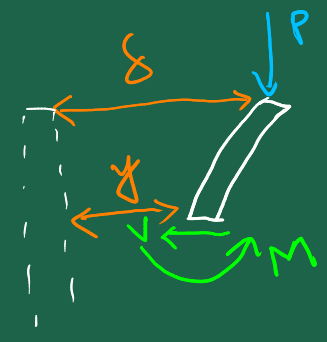
$$EI \frac{d^2 y}{dx^2} = M$$

$$\Rightarrow EI \frac{d^2 y}{dx^2} = P(\delta - y)$$

$$\Rightarrow \frac{d^2 y}{dx^2} + \frac{P}{EI} y = \frac{P}{EI} \delta$$

$$\Rightarrow \frac{d^2 y}{dx^2} + k^2 y = k^2 \delta$$

$$y = A \sin kx + B \cos kx + \delta$$



BLS

$$\textcircled{a} \quad x=L, \quad y=0$$

$$A \sin KL + B \cos KL + \delta = 0$$

$$\textcircled{b} \quad x=L, \quad \frac{dy}{dx} = 0$$

$$AK \cos KL - BK \sin KL = 0$$

$$\Rightarrow A = B \tan KL$$

$$\therefore \frac{B \sin^2 KL}{\cos KL} + B \cos KL + \delta = 0$$

$$\Rightarrow B + \delta \cos KL = 0 \Rightarrow B = -\delta \cos KL$$

$$\therefore A = -\delta \sin KL$$

$$y = -\delta \sin KL \sin Kx - \delta \cos KL \cos Kx + \delta$$
$$= -\delta \cos \left\{ \frac{\pi}{2} - K(L-x) \right\} + \delta$$

$$y = A \sin Kx + B \cos Kx + \delta$$

$$\frac{dy}{dx} = AK \cos Kx - BK \sin Kx$$

$$y = -\delta \cos\{k(L-x)\} + \delta$$

$$\text{@ } x=0, \quad y = \delta$$

$$\delta = -\delta \cos(kL) + \delta$$

$$\Rightarrow \delta \cos kL = 0$$

$$\Rightarrow \cos kL = 0$$

$$\Rightarrow kL = (2n-1)\frac{\pi}{2}, \quad n=1,2,3,\dots$$

$$k = (2n-1)\frac{\pi}{2L}$$

$$\kappa = (2n-1) \frac{\pi}{2L}$$

$$n=1$$

$$\kappa = \frac{\pi}{2L}$$

$$\kappa L = \frac{\pi}{2}$$

$$\Rightarrow \kappa^2 = \frac{\pi^2}{(2L)^2}$$

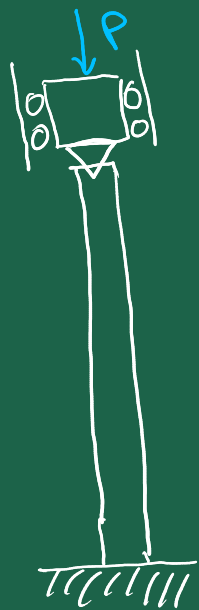
$$\Rightarrow P = \frac{\pi^2 EI}{\underbrace{(2L)^2}}$$

$$\hookrightarrow L_{\text{eff}} = 2L$$

$$\tilde{\kappa} = \frac{P}{EI}$$

$$P_{\text{cr}} = \frac{\tilde{\kappa} EI}{L^2}$$

#3



$$EI \frac{d^2 y}{dx^2} = M$$

$$EI \frac{d^2 y}{dx^2} + P y = 0$$

$$\Rightarrow EI \frac{d^3 y}{dx^3} + P \frac{dy}{dx} = 0$$

$$\Rightarrow EI \frac{d^4 y}{dx^4} + P \frac{d^2 y}{dx^2} = 0$$

$$\Rightarrow \frac{d^4 y}{dx^4} + k^2 \frac{d^2 y}{dx^2} = 0 \quad \left[k^2 = \frac{P}{EI} \right]$$

$$y = e^{mx} \rightarrow m^4 + k^2 m^2 = 0$$

$$m^4 + \tilde{K} m^2 = 0$$

$$\Rightarrow m^2 (m^2 + \tilde{K}) = 0$$

$$\Rightarrow m = 0, 0, -iK, +iK$$

$$y = A \sin Kx + B \cos Kx + Cx + D$$

$$@ x = 0, \quad y = 0 \Rightarrow B + D = 0$$

$$@ x = 0, \quad M = 0$$

$$\frac{dy}{dx} = AK \cos Kx - BK \sin Kx + C$$

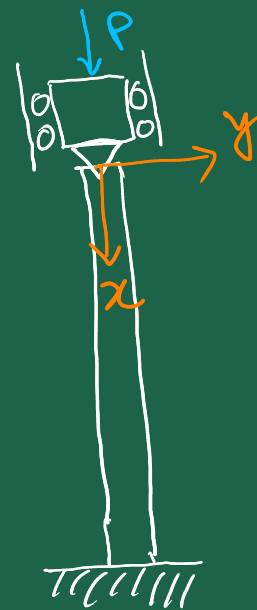
$$\frac{d^2 y}{dx^2} = -A\tilde{K} \sin Kx - B\tilde{K} \cos Kx$$

$$B = 0$$

$$0, -iK, iK$$

$$A \sin Kx + B \cos Kx$$

$$+ C$$



$$\textcircled{a} \quad x=L, \quad y=0$$

$$A \sin kL + B \cos kL + CL + D = 0$$

$$\textcircled{a} \quad x=L, \quad \frac{dy}{dx} = 0$$

$$\frac{dy}{dx} = A k \cos kx - B k \sin kx + C$$

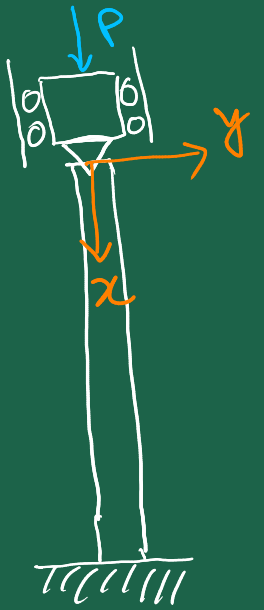
$$A k \cos kL - B k \sin kL + C = 0$$

$$A \sin kL + CL = 0 \Rightarrow A \sin kL = -CL \quad \text{--- } *1$$

$$A k \cos kL + C = 0 \Rightarrow A k \cos kL = -C \quad \text{--- } *2$$

$$*1 \div *2$$

$$\frac{\tan kL}{k} = L \Rightarrow \boxed{\tan kL = kL}$$



$$\tan KL = KL$$

$$KL = 4.4934$$

$$\frac{P}{EI} = \left(\frac{4.4934}{L} \right)^2$$

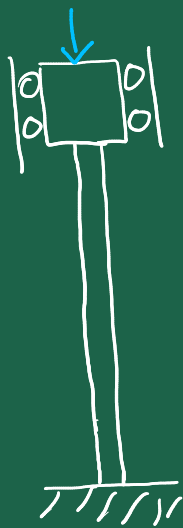
$$\Rightarrow P_{cr} = \frac{4.5^2 EI}{L^2}$$

$$= \frac{\pi^2 EI}{\left(\frac{L}{4.5} \right)^2}$$

$$L_{eff} = \frac{\pi L}{4.5}$$



~~h~~



Both ends clamped

(Part of TS 9)

$$P_{cr} = \frac{\pi^2 EI}{L_{eff}^2} = \frac{\pi^2 EI}{(\kappa L)^2}$$

#1

$$P_{cr} = \frac{\pi^2 EI}{L^2}$$

$$\frac{P_{cr}}{A} = \sigma_{cr} = \frac{\pi^2 EI}{L^2 A}$$

$$I = A r^2 \rightarrow \text{radius of gyration}$$

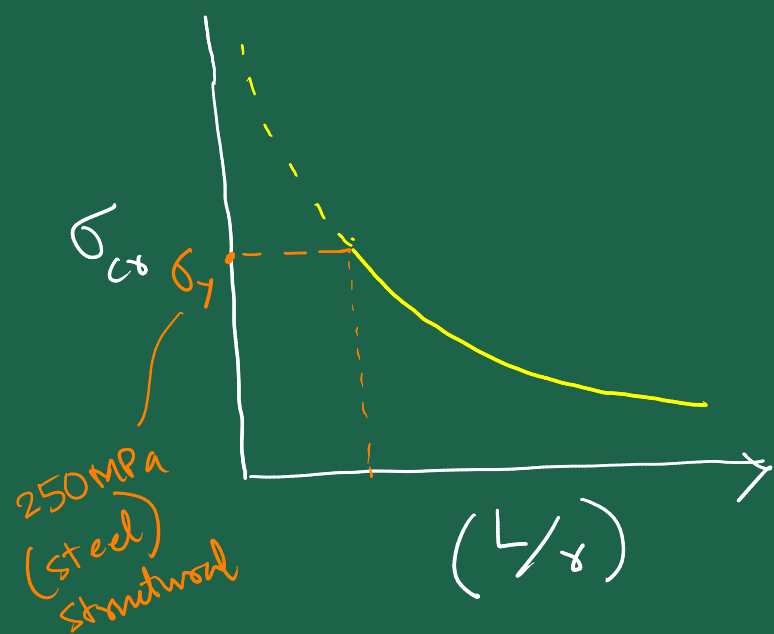
$$\sigma_{cr} = \frac{\pi^2 E \cancel{A} r^2}{L^2 \cancel{A}} = \frac{\pi^2 E r^2}{L^2} = \frac{\pi^2 E}{(L/r)^2}$$

$\frac{L}{r}$: slenderness ratio



$$I = \frac{1}{12} b h^3$$

$$[I] = m^4$$

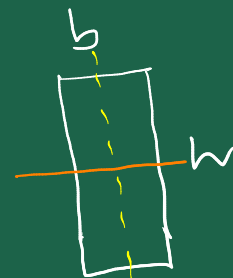
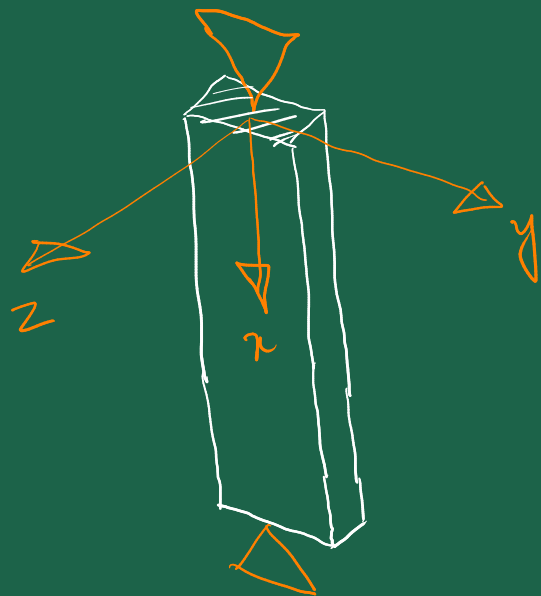


#1

$$P_{cr} = \frac{\pi^2 EI}{L^2}$$

For actual P_{cr} ,

consider the I_{min}



$$I_z = \frac{1}{12} b h^3$$

$$I_y = \frac{1}{12} h b^3$$

$$I_z > I_y$$