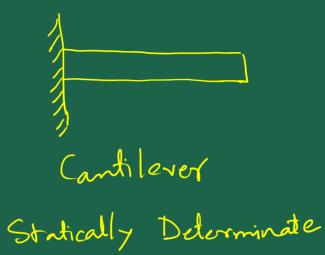
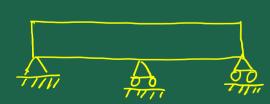
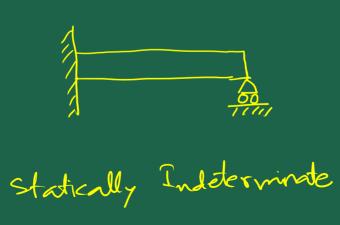
Bending of Beams

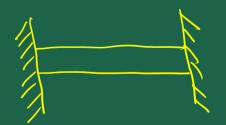


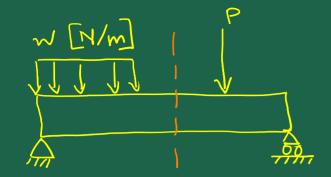












And Sheen force)

OR W Sheen force

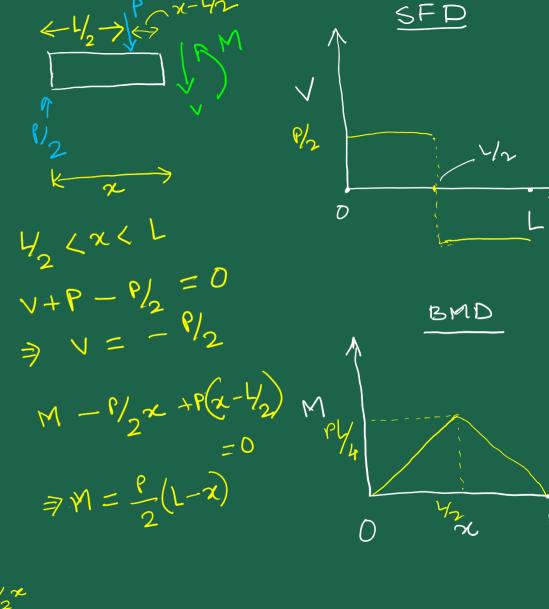
(Sheen force)

M Rv₂

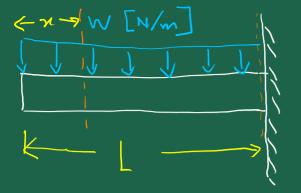
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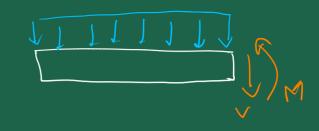
$$|V_{2}|$$

$$|V_{$$

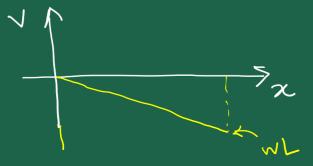


#2



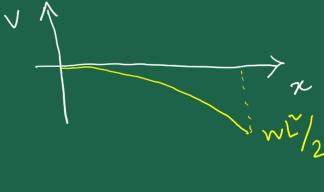


1 2 m

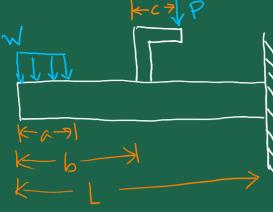


$$\Rightarrow \sum M = 0 \quad \text{(f)}$$

$$\Rightarrow \frac{\sqrt{2}}{2} + M = 0 \Rightarrow M = -\frac{\sqrt{2}}{2}$$



$$= \frac{1}{2} + \frac{$$





$$M = -w^2/2$$

For
$$a < x < b$$

$$V = -wa$$

$$M = -wa \left(x - \frac{a}{2}\right)$$

$$V + P + wa = 0 \Rightarrow V = -wa - P$$

$$M - cP + P(x-b) + wa(x-\frac{a}{2}) = 0$$

$$\frac{1}{2}M = CP - P(x-b) - WA(x-\frac{a}{2})$$

21/3 X W [N/m]

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$$\sum M_A = 0$$

$$-\int_{x}^{L}\left(\frac{w}{L}x\right)dx + R_{g}L = 0$$

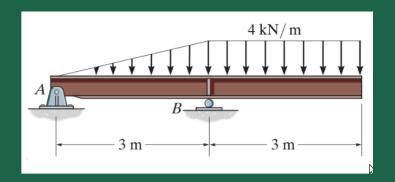
$$\frac{0}{3} = \frac{1}{2} = \frac{1}{3} = \frac{1}{3} = \frac{1}{3}$$

$$\Rightarrow$$
 R_BL = $\left(\frac{WL}{2}\right)\left(\frac{2L}{3}\right)$

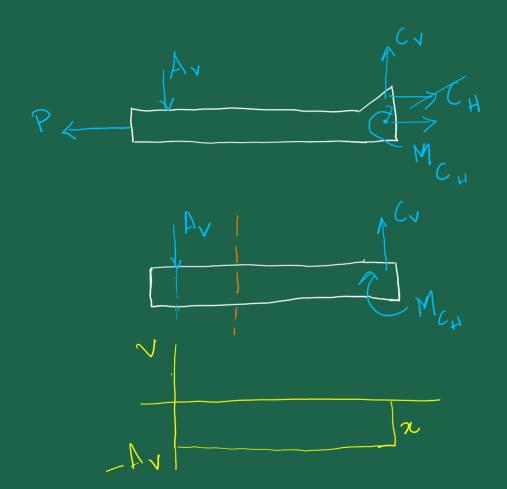
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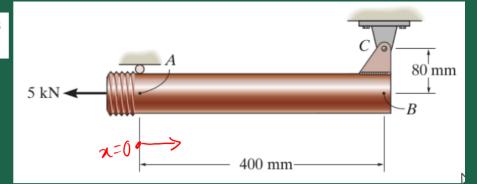
at any post x: Wx

3. Draw the shear and moment diagrams for the overhanging beam.

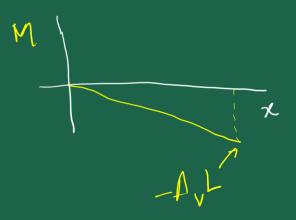


1. Draw the shear force and bending moment diagrams for the pipe. The end screw is subjected to a horizontal force of 5 kN.





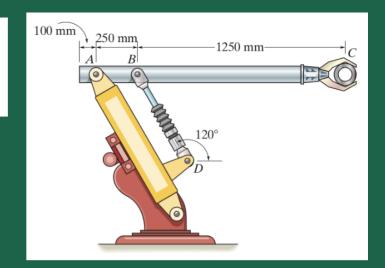
 $\begin{array}{c} A \\ V \\ V \\ + A \\ = 0 \\ \Rightarrow V \\ = - A \\ V \end{array}$

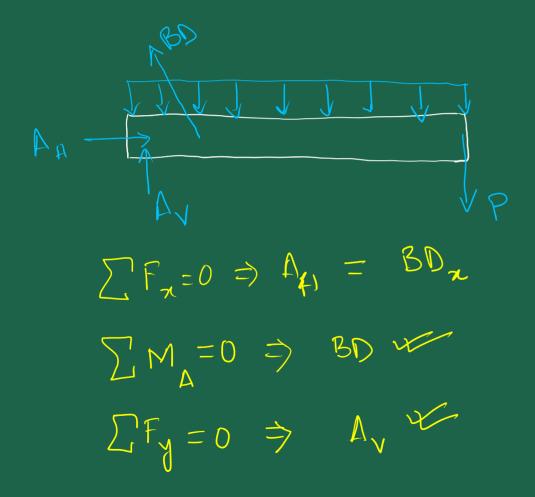


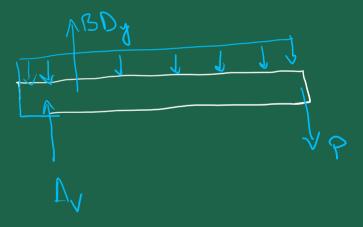
$$\sum F_{y} = O (\uparrow +)$$

$$-V - A_{v} = 0 \Rightarrow V = -A_{v}$$

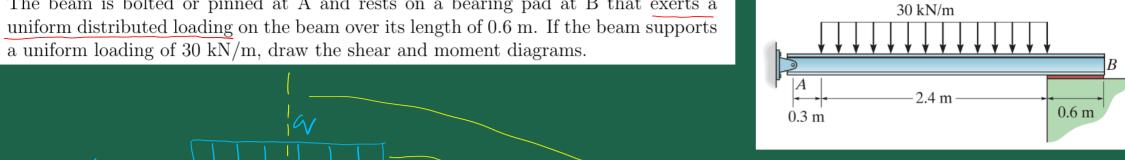
2. The industrial robot is held in the stationary position shown. Draw the shear force and bending moment diagrams of the arm ABC if it is pin connected at A and connected to a hydraulic cylinder (two-force member) BD. Assume the arm and grip have a uniform weight of 0.3 N/mm and support the load of 200 N at C.

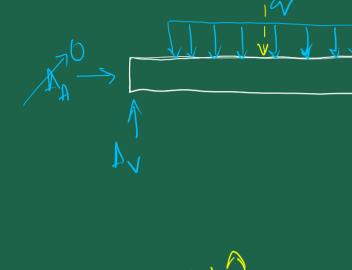




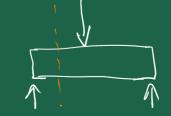


4. The beam is bolted or pinned at A and rests on a bearing pad at B that exerts a a uniform loading of 30 kN/m, draw the shear and moment diagrams.



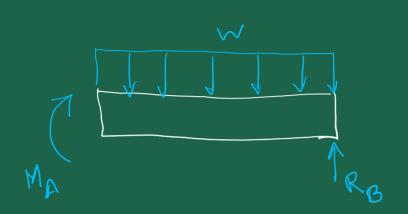


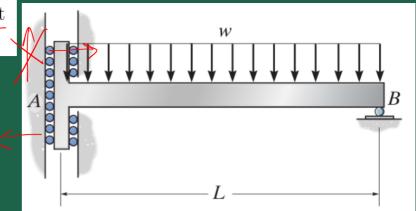
$$\frac{\sum_{M_{A}=0}^{N_{A}=0}}{\sum_{T_{A}=0}^{N_{A}=0}} \times \frac{\sum_{T_{A}=0}^{N_{A}=0}}{\sum_{T_{A}=0}^{N_{A}=0}} \times \frac{\sum_{T_{A}=0}^{N_{A}=0}}{\sum_{T_{A}=0}^{N_{A}=$$

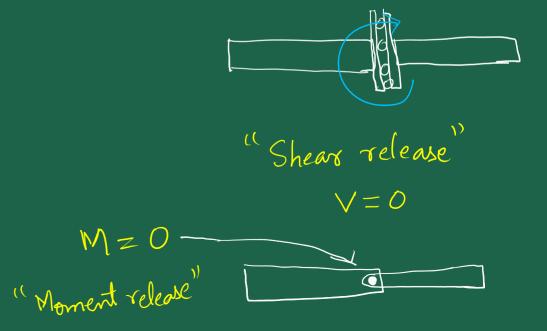




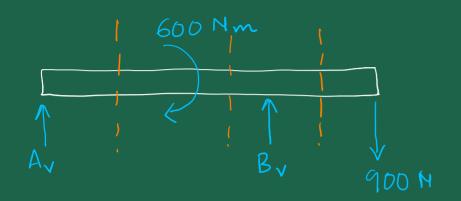
5. Draw the shear and moment diagrams for the beam when the support at A allows it to slide freely along the vertical guide and hence it cannot support a vertical force.







6. The shaft is supported by a smooth thrust bearing at A and a smooth journal bearing at B. Draw the shear and moment diagrams for the shaft.

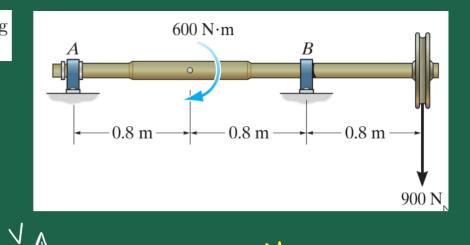


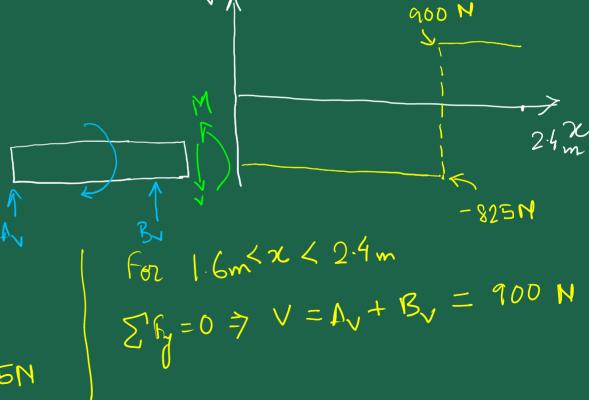
$$\sum_{M_A=0}^{M_A=0} \Rightarrow B_V = 1725N$$

$$\sum_{W_A=0}^{M_A=0} \Rightarrow A_V = -825N$$



$$\sum F_y = 0 \Rightarrow V - A_v = 0 \Rightarrow V = A_v = -825N$$





For 0< x < 0.8m () ZM=0 => M = Ayx (@x=0.8m, M=-660Nm) For 0.8m Lx 2 1.6 m + 2 M=0 > -A,x-600 +M=0 -660 Km > M = 600 + Ayx (@x=0.8m, M=-60 Nm) (@x=1.6m, M=-720 Nm) For 1.6m < x < 2.4m

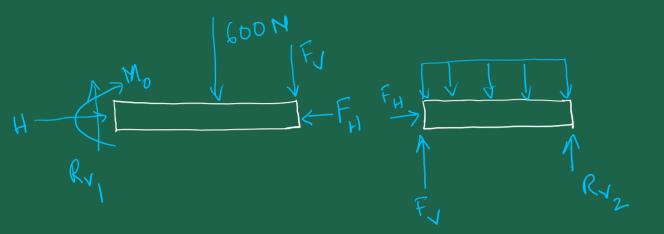
 $J = 0 = M - A_{vx} - B_{v}(x - 1.6m) - 600 Mm = 0$

@ 2=1.6m, M=-720Nm

(a x=24m, Mz0

4

8. The compound beam is fixed at A, pin connected at B, and supported by a roller at C. Draw the shear and moment diagrams for the beam.



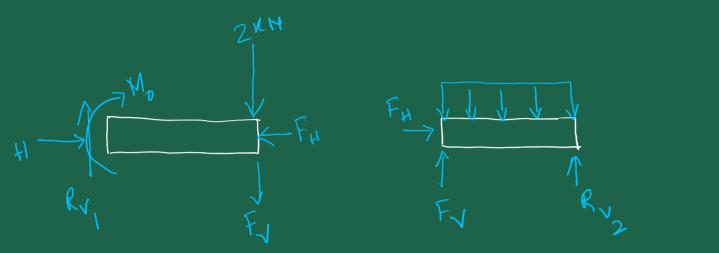


 $400 \,\mathrm{N/m}$

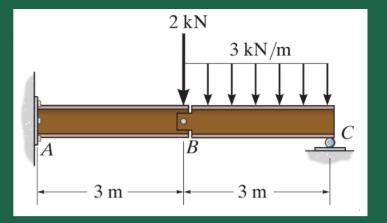
600 N



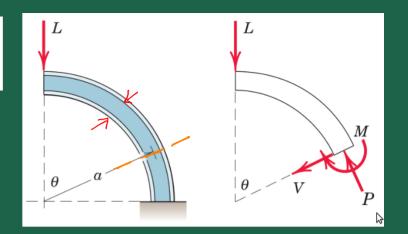
9. The compound beam is fixed at A, pin connected at B, and supported by a roller at C. Draw the shear and moment diagrams for the beam.







11. A curved cantilever beam has the form of a quarter circular arc. Determine the expressions of the shear force V and the bending moment M as functions of θ . The depth of the beam is much smaller than the arc radius.



Relations between load, shear, and bending moment

