Process (contd.)

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So far on processes

- What is a process?
- Structure of a process
- Process states
- Process control block
- Context switch

Process Representation in Linux

Represented by the C structure task_struct

pid t pid; /* process identifier */ long state; /* state of the process */ unsigned int time slice /* scheduling information */ struct task struct *parent; /* this process's parent */ struct list head children; /* this process's children */ struct files struct *files; /* list of open files */ struct mm struct *mm; /* address space of this pro */

Doubly linked list



Process scheduling

Process scheduling

- The process scheduler selects an available process for execution on the CPU
 - Dispatcher: The kernel process that assigns CPU to a process









Process scheduling

- Several scheduling queues exist in OS
 - A PCB is linked to one of the queues at any given tome
 - The PCBs in a queue are connected as a linked list











Characteristics of process queues

- Each I/O device has its own device queue
 - Each event also has its own queue
- Process scheduling can be represented as a queueing diagram
 - Queueing diagram represents queues, resources, flows
 - We will discuss actual scheduling algorithm later

Representation of process scheduling

Representation of process scheduling



Operations on processes

Process creation

- During execution a process may create several new processes
 - Each process has a unique process identifier (pid)
 - Other than the first process (init), all other processes are created by fork system call
 - Parent process create children processes, which, in turn create other processes, forming a tree of processes

Process creation (contd.)

- Address space
 - Child duplicate of parent
 - Child has a program loaded into it
- UNIX example
 - fork() : creates a new process
 - exec(): replace new process's memory with new code

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Process creation example

```
#include <sys/types.h>
#include <stdio.h>
#include <unistd.h>
int main()
pid_t pid;
   /* fork a child process */
   pid = fork();
                    Error condition
   if (pid < 0) {
      fprintf(stderr, "Fork Failed");
      return 1;
                             child process
   else if (pid == 0) {
      execlp("/bin/ls","ls",NULL);
   }
                 parent process
   else {
      /* parent will wait for the child to complete */
      wait(NULL);
      printf("Child Complete");
   }
   return 0;
```

Process termination

- A child process executes last statement
 - exit() call for deleting the process
 - return status data from child to parent via wait()
 - Deallocate the resources

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Child process

exit(2) // Exit with status code

Parent process pid_t pid; Int status;

pid = wait (&status) // pid of
terminated child

Process termination: Corner cases

- In some OS
 - All child must terminate when a process terminates
 - Cascading termination: All children, grandchildren etc. must be terminated
 - OS takes care of this cascade
- Combinations of exit() and wait()
 - If no parent is waiting then zombie process
 - If parent terminated without invoking wait then orphan process

Zombie and orphan process

- Zombie process
 - A process that has terminated, but who parent had not not yet called wait()
 - All processes move to this state when they terminate and remain there until parent calls wait()
 - Entry in process table removed only after calling wait()

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 - Entry in process table removed only after calling wait()
- Orphan process
 - parent terminated without invoking wait
 - Immediately "init" process assigned as parent
 - "init" periodically invokes wait()

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- Cooperating processes need IPC
 - shared memory
 - Message passing

- Ways to do IPC
 - way 1: shared memory shmget(), shmcat(), shmaddr(), shmat(), shmdt(), shmctl()
 - way 2: message passing (pipe) pipe(), read(), write(), close()
 - way 3: message passing (named pipe) mkfifo(), read(), write(), close()
 - way 4: Over network RPC or Remote Procedure Call, sockets

Shared memory system

Schematic for shared memory



char *myseg;

key_t key; int shmid;

key = 235; // some unique id

shmid = shmget(key, 250, IPC_CREAT | 0666);

myseg = shmat(shmid, NULL, 0);

shmdt(myseg);

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shmctl(shmid, IPC_RMID, NULL); // mark the segment to be destroyed

Producer consumer problem

- A producer process produces information that is consumed by the consumer process
 - Compiler produces assembly code consumed by assembler
 - Program produces lines to print, print spool consumes
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 - Bounded buffer
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 - Bounded buffer
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 - Bounded buffer : producer waits when buffer is full, consumer waits when buffer is empty

Producer consumer solution with bounded buffer

• Shared data: implemented as a circular array



Key ideas

- Circular buffer
 - Index in: the next position to write to
 - Index out: the next position to read from
- To check buffer full or empty:
 - Buffer empty: in==out
 - Buffer full: in+1 % BUFFER_SIZE == out
 - Why ? There is still one slot left ...

Pseudo code



```
while (true) {
    while (in == out)
        ; // do nothing -- nothing to consume
    // remove an item from the buffer
    itemToConsume = buffer[out];
    out = (out + 1) % BUFFER SIZE;
    return itemToComsume;
}
```

Solution is correct, but can only use BUFFER_SIZE-1 elements

Better utilization of buffer space

- Circular buffer
- Suppose that we want to use all buffer space:
 - an integer count: the number of filled buffers
 - Initially, count is set to 0.
 - incremented by producer after it produces a new buffer
 - decremented by consumer after it consumes a buffer.

Better utilization of buffer space: Pseudo code

Producer

while (true) {

/* produce an item and put in nextProduced */ while (count == BUFFER_SIZE) ; // do nothing buffer [in] = nextProduced; in = (in + 1) % BUFFER_SIZE; count++; Consumer while (true) { while (count == 0) ; // do nothing nextConsumed = buffer[out]; out = (out + 1) % BUFFER_SIZE; count--;

/* consume the item in
 nextConsumed */

Message passing system

Basics of message passing

• Mechanism for processes to communicate and to synchronize their actions

 Message system – processes communicate with each other without resorting to shared variables

- IPC facility provides two operations:
 - send(message)
 - receive(message)
- The *message* size is either fixed or variable

Communication model



Ways for message passing

- Pipes
- Named pipes
- Covered in last class
 - Also in the assignments

Finally for communication of two processes over network

- Sockets API
- Remote procedure call

Summary

- What is a process?
 - Structure of a process
 - Process states
 - Process control block
 - Context switch
- Why is process scheduling necessary?
 - Ready queues, event queues, queueing diagram
- How does two processes talk?
 - Shared memory, pipe, named pipe