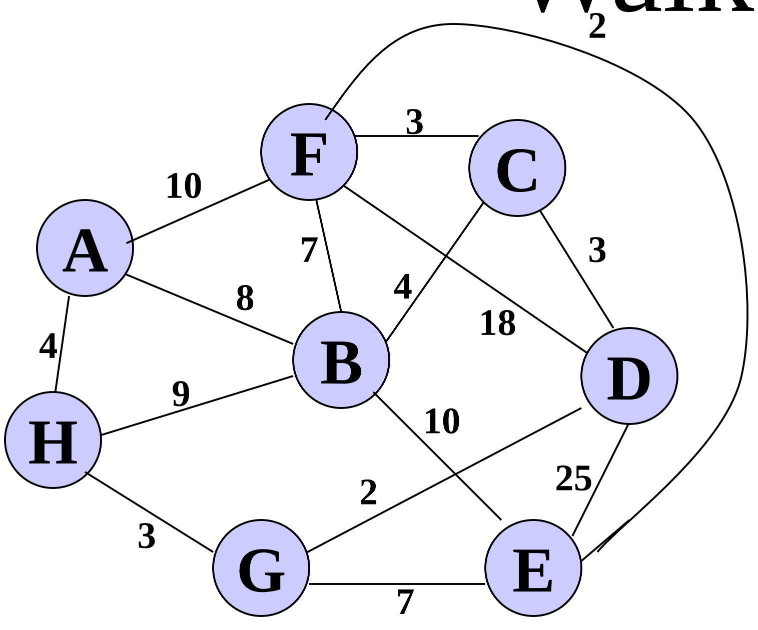
Definition

- A Minimum Spanning Tree (MST) is a subgraph of an undirected graph such that the subgraph spans (includes) all nodes, is connected, is acyclic, and has minimum total edge weight

Algorithm Characteristics

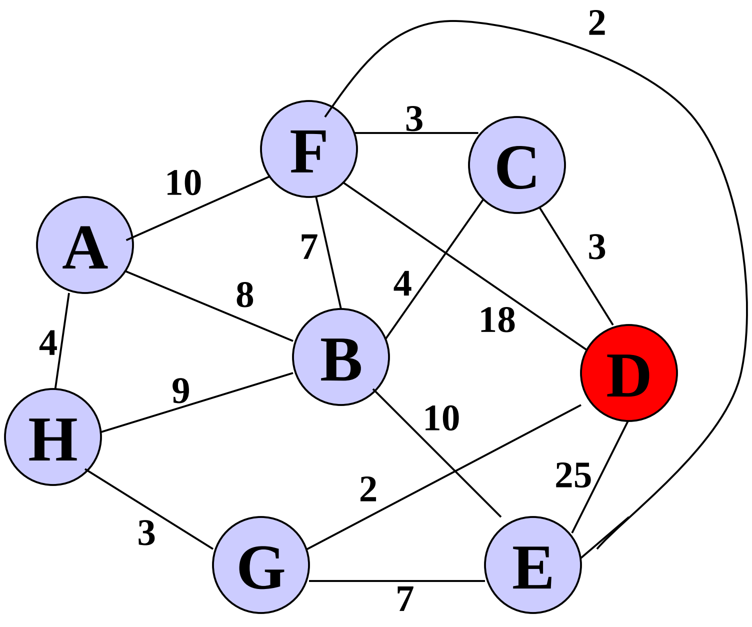
- Both Prim's and Kruskal's Algorithms work with undirected graphs
- Both work with weighted and unweighted graphs but are more interesting when edges are weighted
- Both are greedy algorithms that produce optimal solutions

Walk-Through



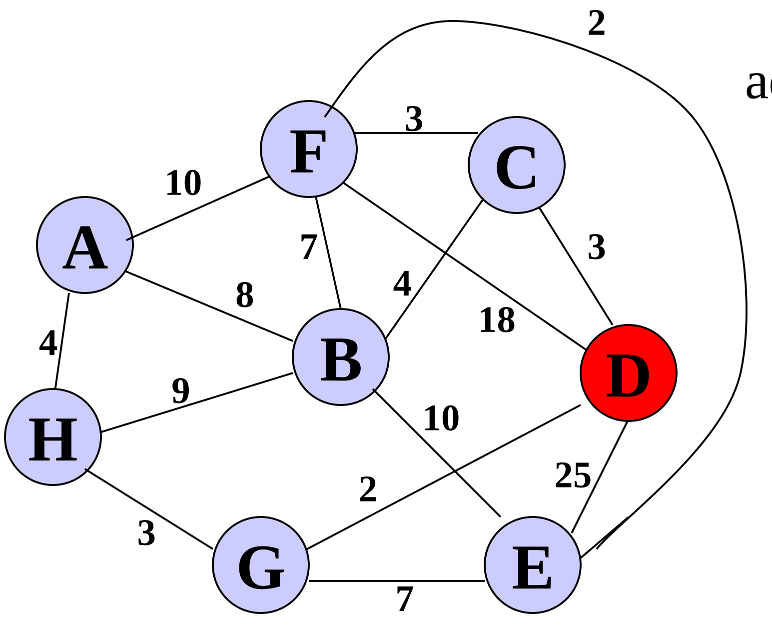
Initialize array

	K	d_v	p_v
A	F	∞	–
B	F	∞	–
C	F	∞	–
D	F	∞	–
E	F	∞	–
F	F	∞	–
G	F	∞	–
H	F	∞	–



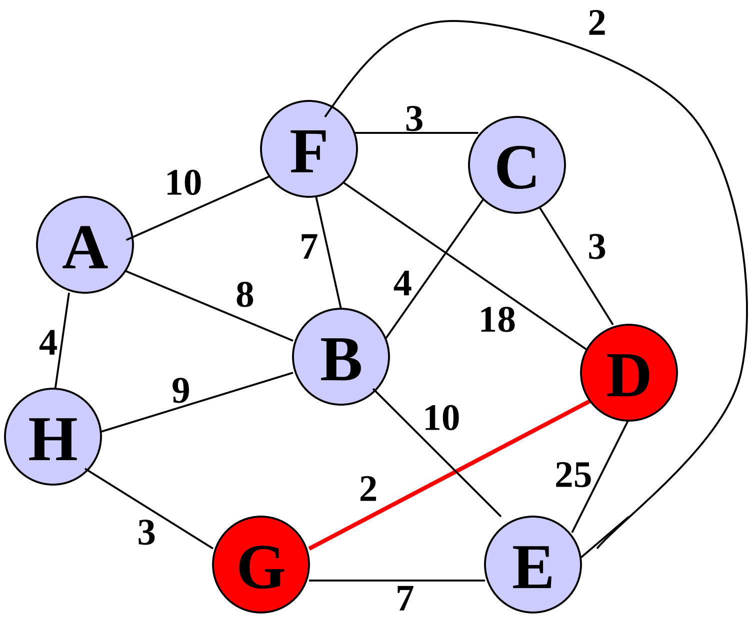
Start with any node, say D

	K	d_v	p_v
A			
B			
C			
D	T	0	–
E			
F			
G			
H			



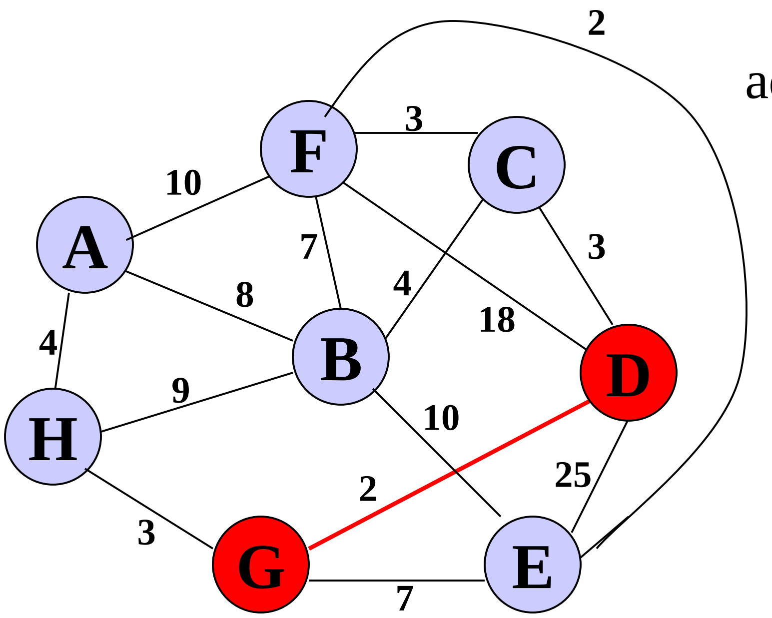
Update distances of adjacent, unselected nodes

	K	d_v	p_v
A			
B			
C		3	D
D	T	0	–
E		25	D
F		18	D
G		2	D
H			



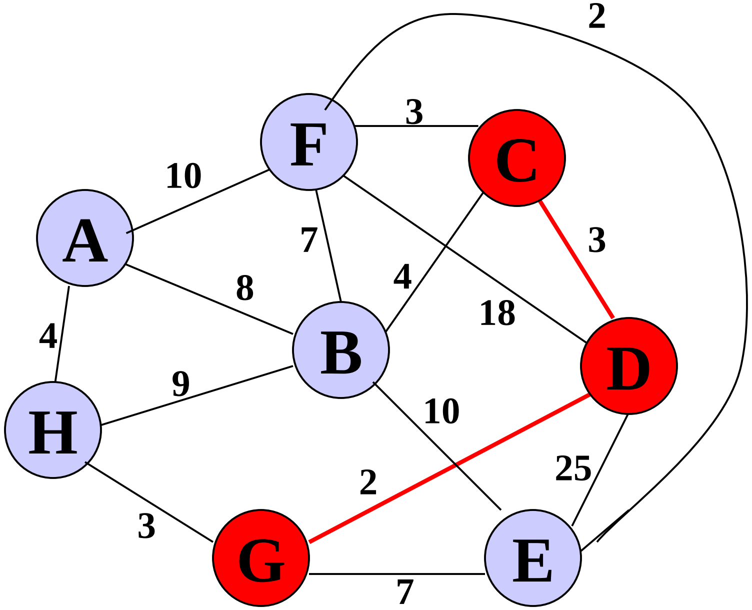
Select node with minimum distance

	K	d_v	p_v
A			
B			
C		3	D
D	T	0	–
E		25	D
F		18	D
G	T	2	D
H			



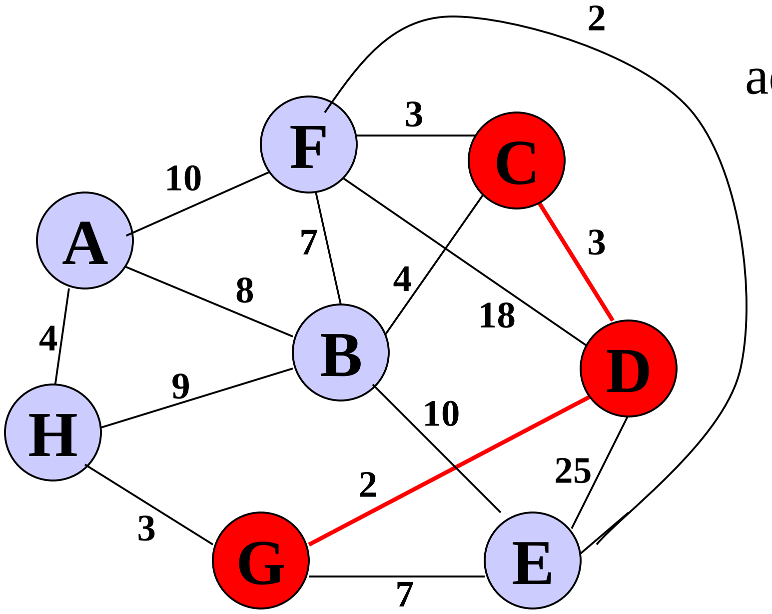
Update distances of adjacent, unselected nodes

	K	d_v	p_v
A			
B			
C		3	D
D	T	0	–
E		7	G
F		18	D
G	T	2	D
H		3	G



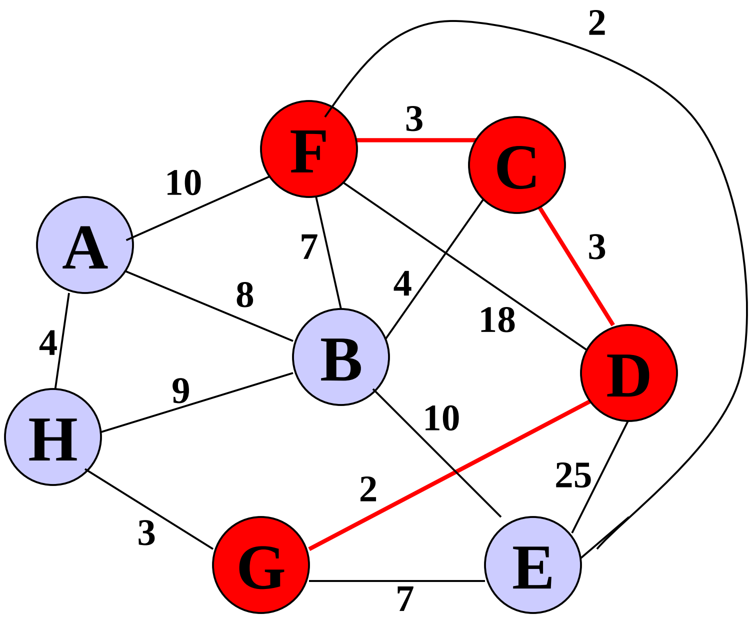
Select node with minimum distance

	K	d_v	p_v
A			
B			
C	T	3	D
D	T	0	–
E		7	G
F		18	D
G	T	2	D
H		3	G



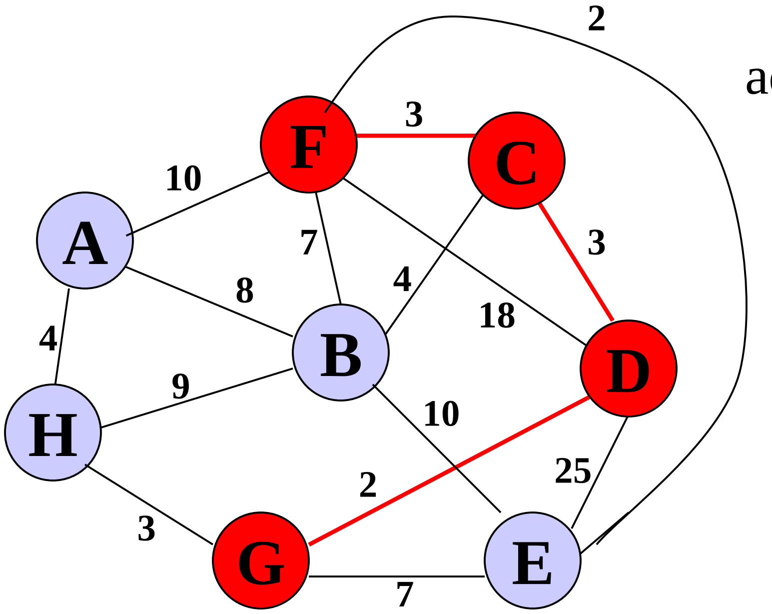
Update distances of adjacent, unselected nodes

	K	d_v	p_v
A			
B		4	C
C	T	3	D
D	T	0	–
E		7	G
F		3	C
G	T	2	D
H		3	G



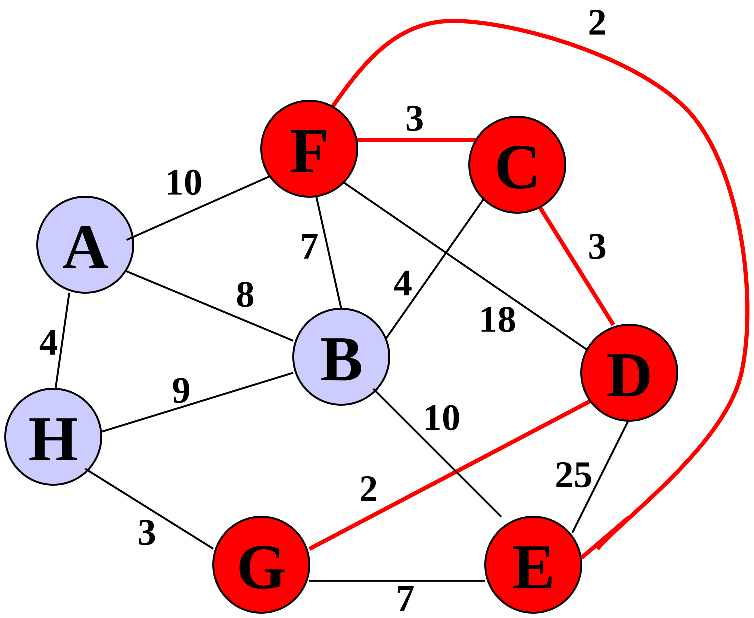
Select node with minimum distance

	K	d_v	p_v
A			
B		4	C
C	T	3	D
D	T	0	–
E		7	G
F	T	3	C
G	T	2	D
H		3	G



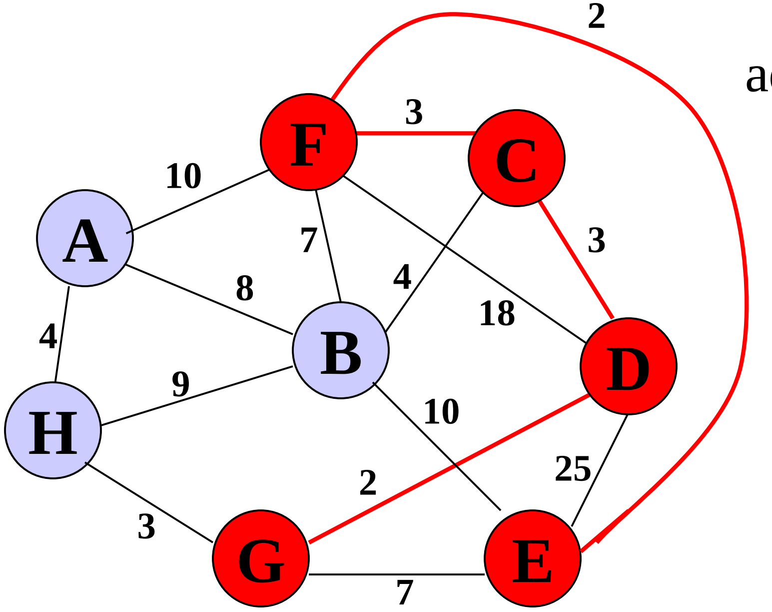
Update distances of
adjacent, unselected nodes

	K	d_v	p_v
A		10	F
B		4	C
C	T	3	D
D	T	0	–
E		2	F
F	T	3	C
G	T	2	D
H		3	G



Select node with
minimum distance

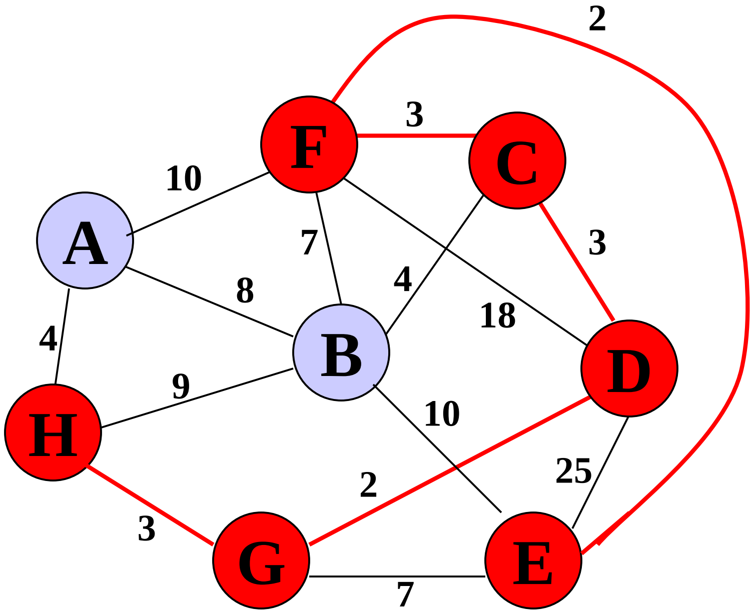
	K	d_v	p_v
A		10	F
B		4	C
C	T	3	D
D	T	0	–
E	T	2	F
F	T	3	C
G	T	2	D
H		3	G



Update distances of adjacent, unselected nodes

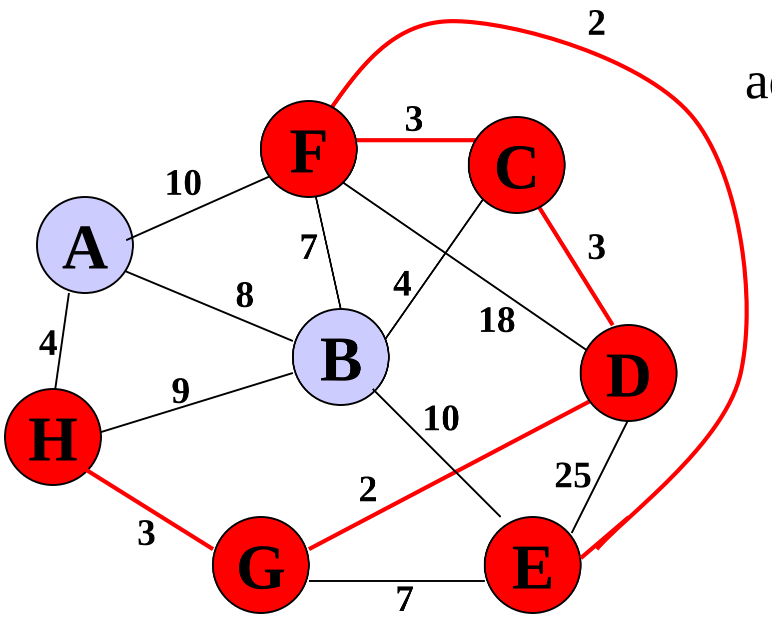
	K	d_v	p_v
A		10	F
B		4	C
C	T	3	D
D	T	0	–
E	T	2	F
F	T	3	C
G	T	2	D
H		3	G

Table entries unchanged



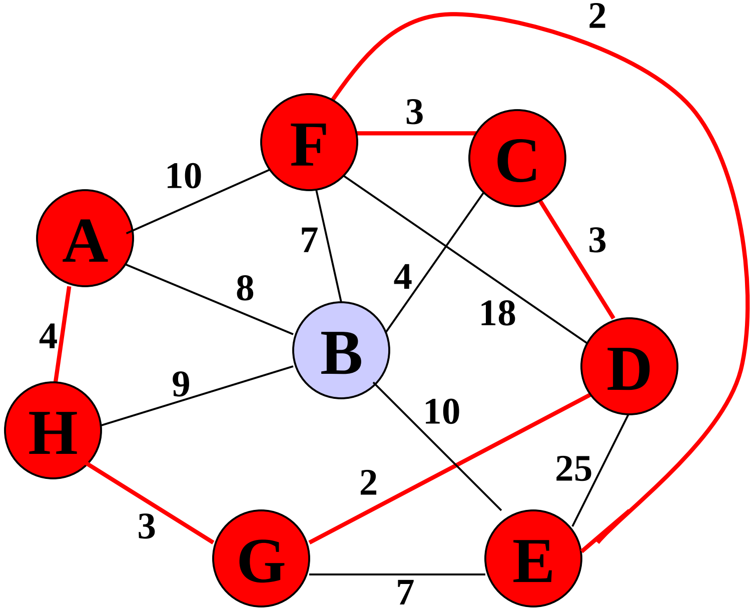
Select node with minimum distance

	K	d_v	p_v
A		10	F
B		4	C
C	T	3	D
D	T	0	–
E	T	2	F
F	T	3	C
G	T	2	D
H	T	3	G



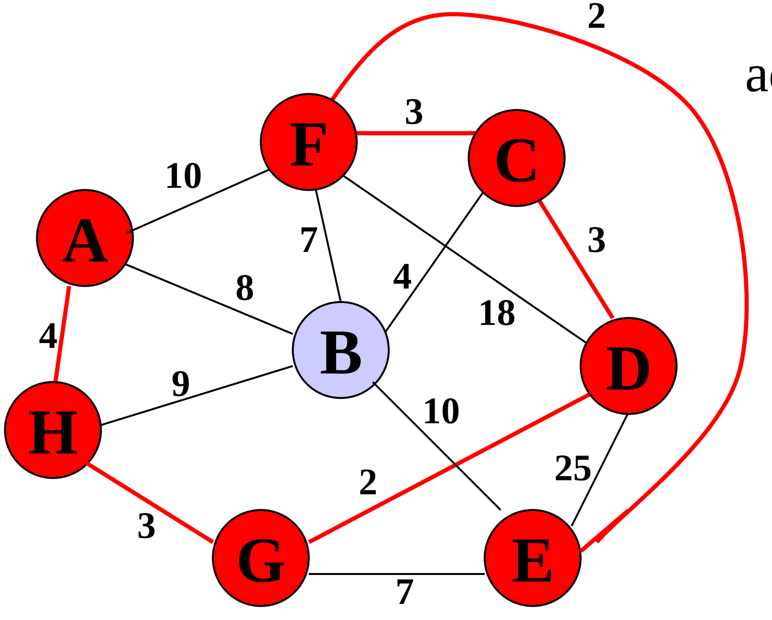
Update distances of adjacent, unselected nodes

	K	d_v	p_v
A		4	H
B		4	C
C	T	3	D
D	T	0	–
E	T	2	F
F	T	3	C
G	T	2	D
H	T	3	G



Select node with minimum distance

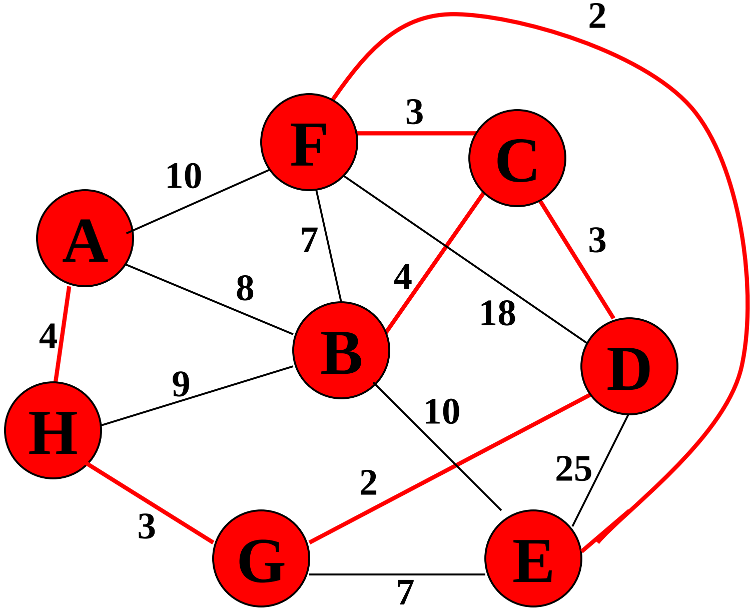
	K	d_v	p_v
A	T	4	H
B		4	C
C	T	3	D
D	T	0	–
E	T	2	F
F	T	3	C
G	T	2	D
H	T	3	G



Update distances of adjacent, unselected nodes

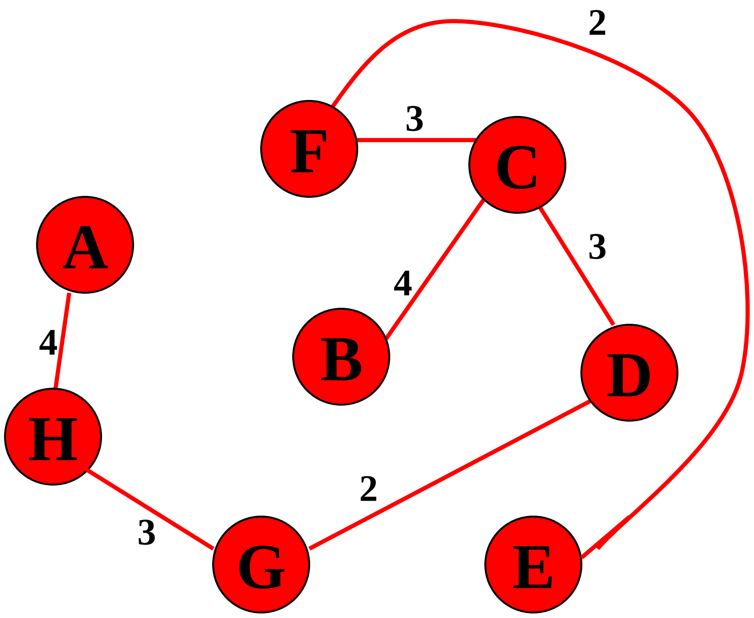
	K	d_v	p_v
A	T	4	H
B		4	C
C	T	3	D
D	T	0	–
E	T	2	F
F	T	3	C
G	T	2	D
H	T	3	G

Table entries unchanged



Select node with minimum distance

	K	d_v	p_v
A	T	4	H
B	T	4	C
C	T	3	D
D	T	0	–
E	T	2	F
F	T	3	C
G	T	2	D
H	T	3	G



Cost of Minimum Spanning Tree = $\Sigma\, d_v$ = **21**

	K	d_v	p_v
A	T	4	H
B	T	4	C
C	T	3	D
D	T	0	–
E	T	2	F
F	T	3	C
G	T	2	D
H	T	3	G

Done

PRIM(V, E, w, r)

Total time: $O(V\lg V + E\lg V) = O(E\lg V)$

```
Q ← ∅
for each u ∈ V
    do key[u] ← ∞
       π[u] ← NIL
       INSERT(Q, u)
DECREASE-KEY(Q, r, 0)        ▶ key[r] ← 0
while Q ≠ ∅
      do u ← EXTRACT-MIN(Q)
         for each v ∈ Adj[u]
             do if v ∈ Q and w(u, v) < key[v]
                  then π[v] ← u
                       DECREASE-KEY(Q, v, w(u, v))
```

- Lines "Q ← ∅" through "INSERT(Q, u)": $O(V)$ if Q is implemented as a min-heap
- DECREASE-KEY(Q, r, 0): $O(\lg V)$
- while Q ≠ ∅: Executed |V| times
- EXTRACT-MIN(Q): Takes $O(\lg V)$
  - Min-heap operations: $O(V\lg V)$
- for each v ∈ Adj[u]: Executed O(E) times total
- do if v ∈ Q and w(u, v) < key[v]: Constant
- DECREASE-KEY(Q, v, w(u, v)): Takes $O(\lg V)$
  - $O(E\lg V)$