

**GIAN course: Singular optimal control**

**Slide collection 4**

**Matrix Polynomials and ODE/DAE of higher order**

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## Subject of these notes

Matrix polynomial of degree  $d$  (with quadratic coefficients):

$$P(\lambda) = P_d \lambda^d + P_{d-1} \lambda^{d-1} + \dots + P_1 \lambda + P_0, \quad P_k \in \mathbb{C}^{n \times n}, \quad P_d \neq 0.$$

We investigate the solutions of the associated differential equation/DAE

$$P_d x^{(d)}(t) + P_{d-1} x^{(d-1)}(t) + \dots + P_1 \dot{x}(t) + P_0 x(t) = f(t).$$

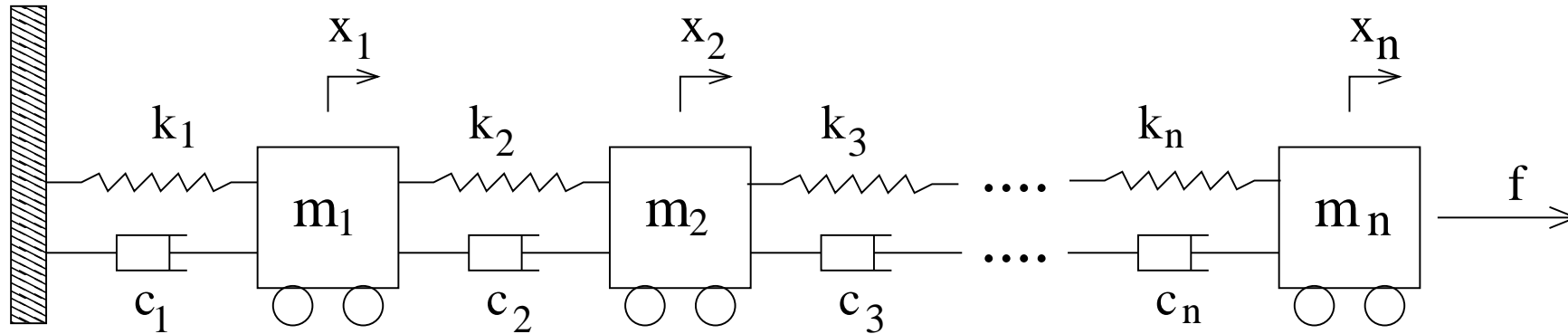
In short notation:

$$P \left( \frac{d}{dt} \right) x(t) = f(t),$$

where

$$P \left( \frac{d}{dt} \right) = P_d \left( \frac{d}{dt} \right)^d + P_{d-1} \left( \frac{d}{dt} \right)^{d-1} + \dots + P_1 \left( \frac{d}{dt} \right) + P_0.$$

## Example: mass-spring-damper chain



Equation of motion:

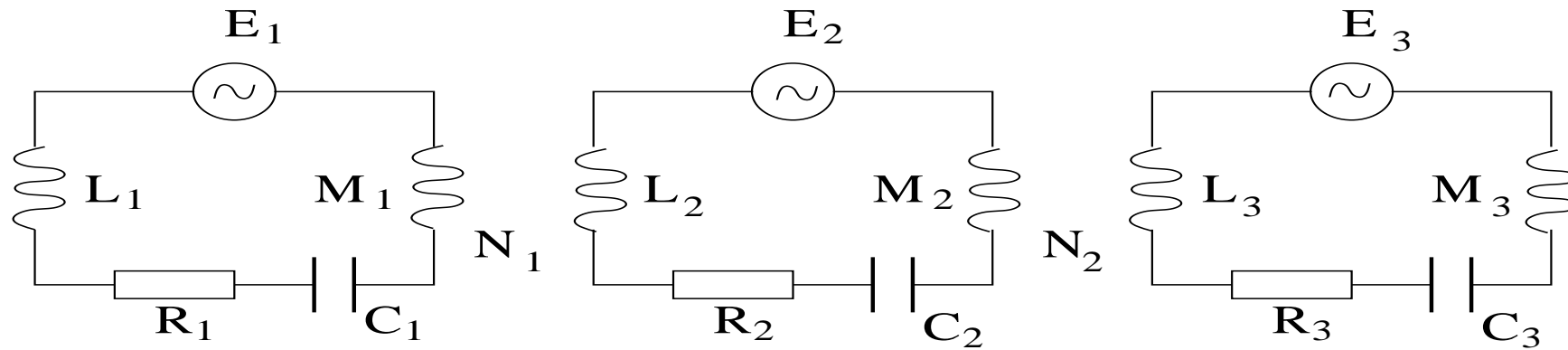
$$\begin{bmatrix} m_1 & & & & & \\ & m_2 & & & & \\ & & \dots & & & \\ & & & & & \\ & & & & & m_n \end{bmatrix} \begin{bmatrix} \ddot{x}_1 \\ \ddot{x}_2 \\ \vdots \\ \ddot{x}_n \end{bmatrix} + \begin{bmatrix} c_1 & -c_2 & & & & \\ -c_2 & c_2 + c_3 & -c_3 & & & \\ & \dots & \dots & \dots & & \\ & & & & -c_{n-1} & \\ & & & & -c_{n-1} & c_n \end{bmatrix} \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \vdots \\ \dot{x}_n \end{bmatrix} + \begin{bmatrix} k_1 & -k_2 & & & & \\ -k_2 & k_2 + k_3 & -k_3 & & & \\ & \dots & \dots & \dots & & \\ & & & & -k_{n-1} & \\ & & & & -k_{n-1} & k_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ f \end{bmatrix}$$

Short:

$$M \ddot{x} + C \dot{x} + K x = \hat{f}.$$

$M$ =mass matrix,  $C$ =damping matrix,  $K$ =stiffness matrix,  $\hat{f}$ =external force.

Example: inductively coupled circuits (found in book by Veselic)



ODE for currents:

$$\begin{bmatrix} L_1 + M_1 & N_1 & & & \\ N_1 & L_2 + M_2 & N_2 & & \\ & \dots & \dots & \dots & \\ & & & N_{n-1} & L_n + M_n \end{bmatrix} \begin{bmatrix} \ddot{I}_1 \\ \ddot{I}_2 \\ \vdots \\ \ddot{I}_n \end{bmatrix} + \begin{bmatrix} R_1 & & & & \\ & R_2 & & & \\ & & \dots & & \\ & & & R_{n-1} & \\ & & & & R_n \end{bmatrix} \begin{bmatrix} \dot{I}_1 \\ \dot{I}_2 \\ \vdots \\ \dot{I}_n \end{bmatrix} + \begin{bmatrix} C_1^{-1} & & & & \\ & C_2^{-1} & & & \\ & & \dots & & \\ & & & C_{n-1}^{-1} & \\ & & & & C_n^{-1} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ \vdots \\ I_n \end{bmatrix} = \begin{bmatrix} \dot{E}_1 \\ \vdots \\ \dot{E}_{n-1} \\ \dot{E}_n \end{bmatrix}$$

Short:  $\mathcal{L}\ddot{I} + \mathcal{R}\dot{I} + \mathcal{K}I = \dot{E}$ .

$L_k, M_k$  inductance,  $N_k$  mutual inductance,  $R_k$  resistance,  $C_k$  capacity.

## The first companion form

The ODE/DAE

$$P_d x^{(d)} + P_{d-1} x^{(d-1)} + \dots + P_1 \dot{x} + P_0 x = f \quad (*)$$

is equivalent to the linear ODE/DAE

$$\begin{bmatrix} I & & & & \\ & I & & & \\ & & \dots & & \\ & & & I & \\ & & & & P_d \end{bmatrix} \frac{d}{dt} \begin{bmatrix} x \\ \dot{x} \\ \vdots \\ x^{(d-1)} \end{bmatrix} - \underbrace{\begin{bmatrix} 0 & I & & & \\ & & I & & \\ & & & \dots & \\ & & & & I \\ -P_0 & -P_1 & \dots & \dots & -P_{d-1} \end{bmatrix}}{=:C_P^b} \begin{bmatrix} x \\ \dot{x} \\ \vdots \\ x^{(d-1)} \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ f \end{bmatrix} \quad (**)$$

This is an ODE/DAE associated with the **companion pencil**

$$\lambda \underbrace{\begin{bmatrix} I & & & & \\ & \dots & & & \\ & & I & & \\ & & & & P_d \end{bmatrix} - \begin{bmatrix} 0 & I & & & \\ & & I & & \\ & & & \dots & \\ & & & & I \\ -P_0 & -P_1 & \dots & \dots & -P_{d-1} \end{bmatrix}}{C_P^b(\lambda)}$$

Precisely: if  $y(t) = \begin{bmatrix} y_0(t) \\ y_1(t) \\ \vdots \\ y_{d-1}(t) \end{bmatrix}$  solves  $C_P^b(\frac{d}{dt})y = [0 \dots 0 f^\top]^\top$  then  $x(t) := y_0(t)$  solves (\*).

## The first companion form

The ODE/DAE

$$P_d x^{(d)} + P_{d-1} x^{(d-1)} + \dots + P_1 \dot{x} + P_0 x = f \quad (*)$$

is equivalent to the linear ODE/DAE

$$\begin{bmatrix} I & & & & \\ & I & & & \\ & & \dots & & \\ & & & I & \\ & & & & P_d \end{bmatrix} \frac{d}{dt} \begin{bmatrix} x \\ \dot{x} \\ \vdots \\ x^{(d-1)} \end{bmatrix} - \underbrace{\begin{bmatrix} 0 & I & & & \\ & & I & & \\ & & & \dots & \\ & & & & I \\ -P_0 & -P_1 & \dots & \dots & -P_{d-1} \end{bmatrix}}{=:C^b(P)} \begin{bmatrix} x \\ \dot{x} \\ \vdots \\ x^{(d-1)} \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ f \end{bmatrix} \quad (**)$$

If  $P_d$  is nonsingular,

$$\frac{d}{dt} \begin{bmatrix} x \\ \dot{x} \\ \vdots \\ x^{(d-1)} \end{bmatrix} - \begin{bmatrix} 0 & I & & & \\ & & I & & \\ & & & \dots & \\ & & & & I \\ -\hat{P}_0 & -\hat{P}_1 & \dots & \dots & -\hat{P}_{d-1} \end{bmatrix} \begin{bmatrix} x \\ \dot{x} \\ \vdots \\ x^{(d-1)} \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \hat{f} \end{bmatrix}, \quad \text{where } \begin{cases} \hat{P}_k := P_d^{-1} P_k, \\ \hat{f} := P_d^{-1} f. \end{cases}$$

Thus,  $x$  solves (\*) if and only if

$$x(t) = \begin{bmatrix} I & 0 & \dots & 0 \end{bmatrix} \left( e^{C^b(\hat{P})(t-t_0)} \begin{bmatrix} x(t_0) \\ \dot{x}(t_0) \\ \vdots \\ x^{(d-1)}(t_0) \end{bmatrix} + \int_{t_0}^t e^{C^b(\hat{P})(t-s)} \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \hat{f}(s) \end{bmatrix} ds \right)$$

Remark: in (\*\*) the identity matrix can be replaced by any nonsingular matrix.

## Horner polynomials (my terminology) and division by a linear scalar factor

The Horner polynomials associated with  $P(\lambda) = \sum_{k=0}^d P_k \lambda^k$  are defined as

$$\begin{aligned} H_{d-1}(\lambda) &:= P_d, \\ H_{d-2}(\lambda) &:= P_d \lambda + P_{d-1}, \\ H_{d-3}(\lambda) &:= P_d \lambda^2 + P_{d-1} \lambda + P_{d-2}, \\ &\vdots \\ H_1(\lambda) &:= P_d \lambda^{d-2} + P_{d-1} \lambda^{d-3} + P_{d-2} \lambda^{d-4} + \dots + P_2, \\ H_0(\lambda) &:= P_d \lambda^{d-1} + P_{d-1} \lambda^{d-2} + P_{d-2} \lambda^{d-3} + \dots + P_2 \lambda + P_1. \end{aligned}$$

Then it holds that (evaluation of  $P(\lambda)$  by Horner's method)

$$\begin{aligned} H_{d-1}(\lambda) &= P_d, \\ H_{k-1}(\lambda) &= H_k(\lambda) \lambda + P_k, \text{ for } k = d-1, \dots, 1, \\ P(\lambda) &= H_0(\lambda) \lambda + P_0. \end{aligned}$$

Furthermore, it is easily verified that for any  $\lambda_0 \in \mathbb{C}$ ,

$$P(\lambda) = \left( \sum_{k=0}^{d-1} H_k(\lambda_0) \lambda^k \right) (\lambda - \lambda_0) + P(\lambda_0).$$

## Digression: Horner polynomials and $(\lambda I - A)^{-1}$

Let  $\chi_A$  be the characteristic polynomial of  $A \in \mathbb{C}^{n \times n}$ . Then

$$\chi_A(\lambda) = \left( \sum_{k=0}^{n-1} H_k(\lambda_0) \lambda^k \right) (\lambda - \lambda_0) + \chi_A(\lambda_0),$$

where the  $H_k$  are the associated Horner polynomials. By Cayley Hamilton:

$$0 = \chi_A(A) = \left( \sum_{k=0}^{n-1} H_k(\lambda_0) A^k \right) (A - \lambda_0 I) + \chi_A(\lambda_0) I.$$

Thus,

$$(\lambda_0 I - A)^{-1} = \frac{1}{\chi_A(\lambda_0)} \left( \sum_{k=0}^{n-1} H_k(\lambda_0) A^k \right).$$



## The characteristic polynomial

The polynomial  $\chi_P(\lambda) = \det(P(\lambda))$  is called the characteristic polynomial of  $P(\lambda) = \sum_{k=0}^d P_k \lambda^k \in \mathbb{C}^{n \times n}[\lambda]$ .

Note that  $\text{degree}(\chi_P) \leq dn$  with equality if  $P_d$  is nonsingular.

**Lemma.**  $\chi_P$  equals the char. polynomial of the companion pencil of  $P$  up to sign.

**Proof.** for  $d = 4$ . The Horner polynomials  $H_k(\lambda)$  satisfy

$$H_2(\lambda) = P_4 \lambda + P_3, \quad H_1(\lambda) = H_2(\lambda) \lambda + P_2, \quad H_0(\lambda) = H_1(\lambda) \lambda + P_1, \quad P(\lambda) = H_0(\lambda) \lambda + P_0.$$

Thus,

$$\begin{aligned} & \overbrace{\begin{bmatrix} H_0(\lambda) & H_1(\lambda) & H_2(\lambda) & I \\ -I & 0 & 0 & 0 \\ 0 & -I & 0 & 0 \\ 0 & 0 & -I & 0 \end{bmatrix}}^{F(\lambda)} \left( \lambda \begin{bmatrix} I & & & \\ & I & & \\ & & I & \\ & & & P_4 \end{bmatrix} - \begin{bmatrix} 0 & I & & \\ -P_0 & -P_1 & -P_2 & -P_3 \end{bmatrix} \right) \\ &= \begin{bmatrix} H_0(\lambda) & H_1(\lambda) & H_2(\lambda) & I \\ -I & 0 & 0 & 0 \\ 0 & -I & 0 & 0 \\ 0 & 0 & -I & 0 \end{bmatrix} \begin{bmatrix} \lambda I & -I & & \\ & \lambda I & -I & \\ & & \lambda I & -I \\ P_0 & P_1 & P_2 & \lambda P_4 + P_3 \end{bmatrix} = \underbrace{\begin{bmatrix} P(\lambda) & & & \\ -\lambda I & I & & \\ & -\lambda I & I & \\ & & -\lambda I & I \end{bmatrix}}_{G(\lambda)} \end{aligned}$$

We have  $\det(F(\lambda)) = \pm 1$  (change first and fourth block row) and  $\det(G(\lambda)) = P(\lambda)$ .

## The second companion form

For a **monic** polynomial  $P(\lambda) = I \lambda^d + P_{d-1} \lambda^{d-1} + \dots + P_1 \lambda + P_0$  define an invertible coordinate transformation

$$(x, \dot{x}, \ddot{x}, \dots, x^{(d-1)}) \longmapsto (z_0, z_1, \dots, z_{d-1})$$

by

$$\begin{aligned} z_{d-1} &:= x &= H_{d-1}\left(\frac{d}{dt}\right)x \\ z_{d-2} &:= \dot{x} + P_{d-1}x &= H_{d-2}\left(\frac{d}{dt}\right)x \\ z_{d-3} &:= \ddot{x} + P_{d-1}\dot{x} + P_{d-2}x &= H_{d-3}\left(\frac{d}{dt}\right)x \\ &\vdots &\vdots \\ z_0 &:= x^{(d-1)} + P_{d-1}x^{(d-2)} + \dots + P_1x &= H_0\left(\frac{d}{dt}\right)x \end{aligned}$$

Then

$$\text{for } k = 1, \dots, d-1: \quad \dot{z}_k = z_{k-1} - P_k z_{d-1}, \quad \text{and} \quad \dot{z}_0 = P\left(\frac{d}{dt}\right)x - P_0 z_{d-1}.$$

Thus,

$$P\left(\frac{d}{dt}\right)x = f \quad \Leftrightarrow \quad \frac{d}{dt} \begin{bmatrix} z_0 \\ z_1 \\ \vdots \\ z_{d-1} \end{bmatrix} - \underbrace{\begin{bmatrix} 0 & & -P_0 \\ I & & -P_1 \\ & \dots & \vdots \\ & & I & -P_{d-1} \end{bmatrix}}_{=: C_P^\#} \begin{bmatrix} z_0 \\ z_1 \\ \vdots \\ z_{d-1} \end{bmatrix} = \begin{bmatrix} f \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad (*)$$

Thus, the solutions of (\*) satisfy

$$x(t) = [0 \quad \dots \quad 0 \quad I] \left( e^{C_P^\#(t-t_0)} \begin{bmatrix} z_1(t_0) \\ z_2(t_0) \\ \vdots \\ z_d(t_0) \end{bmatrix} + \int_{t_0}^t e^{C_P^\#(t-s)} \begin{bmatrix} f(s) \\ 0 \\ \vdots \\ 0 \end{bmatrix} ds \right)$$

with the **second companion matrix**  $C_P^\#$ .

## Similarity of companion matrices

It is straightforward to verify that

$$\underbrace{\begin{bmatrix} P_1 & P_2 & \dots & P_{n-1} & I \\ P_2 & & & I & \\ \vdots & & & & \\ P_{n-1} & I & & & \\ I & & & & \end{bmatrix}}_T \underbrace{\begin{bmatrix} 0 & I & & & \\ & & I & & \\ & & & \ddots & \\ -P_0 & -P_1 & \dots & \dots & -P_{n-1} \end{bmatrix}}_{C_P^b} = \underbrace{\begin{bmatrix} 0 & & & -P_0 \\ I & & & -P_1 \\ & \ddots & & \vdots \\ & & I & -P_{n-1} \end{bmatrix}}_{C_P^\#} \underbrace{\begin{bmatrix} P_1 & P_2 & \dots & P_{n-1} & I \\ P_2 & & & I & \\ \vdots & & & & \\ P_{n-1} & I & & & \\ I & & & & \end{bmatrix}}_T$$

Thus,

$$C_P^\# = T C_P^b T^{-1}.$$

Note:  $T$  is an upper triangular Hankel matrix.

## Jordan canonical form of companion matrices of scalar polynomials

The identity  $p(\lambda) = \lambda^n + p_{n-1} \lambda^{n-1} + \dots + p_1 \lambda + p_0$  can be rewritten as

$$-p_{n-1} \lambda^{n-1} - \dots - p_1 \lambda - p_0 = \lambda^n - p(\lambda).$$

Thus,

$$\underbrace{\begin{bmatrix} 0 & 1 & & & \\ & & 1 & & \\ & & & \ddots & \\ & & & & 1 \\ -p_0 & -p_1 & \dots & \dots & -p_{n-1} \end{bmatrix}}_{C_p^b} \underbrace{\begin{bmatrix} 1 \\ \lambda \\ \vdots \\ \lambda^{n-1} \end{bmatrix}}_{=:v_0(\lambda)} = \lambda \begin{bmatrix} 1 \\ \lambda \\ \vdots \\ \lambda^{n-1} \end{bmatrix} - \begin{bmatrix} 0 \\ \vdots \\ 0 \\ p(\lambda) \end{bmatrix} \quad (*)$$

$v_0(\lambda)$  is an eigenvector of  $C_p^b$  iff  $p(\lambda) = 0$ .

Suppose now, that  $\lambda$  is a zero of  $p$  of multiplicity  $m > 1$ . Then

$$0 = p(\lambda) = p'(\lambda) = \dots = p^{(m-1)}(\lambda).$$

Differentiating (\*) yields

$$C_p^b \left( \frac{d}{d\lambda} \right)^j v_0(\lambda) = \left( \frac{d}{d\lambda} \right)^j (\lambda v_0(\lambda)), \quad j = 0, \dots, m-1.$$

Notation:

$$v_j(\lambda) := \frac{1}{j!} \left( \frac{d}{d\lambda} \right)^j v_0(\lambda) \Rightarrow \frac{1}{j!} \left( \frac{d}{d\lambda} \right)^j (\lambda v_0(\lambda)) = \lambda v_j(\lambda) + v_{j-1}(\lambda), \quad j = 1, \dots, m-1$$

$$\Rightarrow C_p^b v_j(\lambda) = \lambda v_j(\lambda) + v_{j-1}(\lambda)$$

$$\Rightarrow v_0(\lambda), \dots, v_{m-1}(\lambda) \text{ is a Jordan chain for } C_p^b$$

## Jordan canonical form of companion matrices of scalar polynomials

Example: Suppose

$$p(\lambda) = \lambda^4 + p_3 \lambda^3 + p_2 \lambda^2 + p_1 \lambda + p_0 = (\lambda - \lambda_1)(\lambda - \lambda_2)^3, \quad \lambda_1 \neq \lambda_2.$$

The Jordan chain to the zero  $\lambda_2$  is

$$v_0(\lambda_2) = \begin{bmatrix} 1 \\ \lambda_2 \\ \lambda_2^2 \\ \lambda_2^3 \end{bmatrix}, \quad v_1(\lambda_2) = v'_0(\lambda_2) = \begin{bmatrix} 0 \\ 1 \\ 2\lambda_2 \\ 3\lambda_2^2 \end{bmatrix}, \quad v_2(\lambda_2) = \frac{1}{2} v''_0(\lambda_2) = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 3\lambda_2 \end{bmatrix}.$$

Let

$$V = \begin{bmatrix} 1 & 1 & 0 & 0 \\ \lambda_1 & \lambda_2 & 1 & 0 \\ \lambda_1^2 & \lambda_2^2 & 2\lambda_2 & 1 \\ \lambda_1^3 & \lambda_2^3 & 3\lambda_2^2 & 3\lambda_2 \end{bmatrix}, \quad J = \begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & 1 & \\ & & & \lambda_2 \end{bmatrix}.$$

Then

$$C_p^b = V J V^{-1}, \quad C_P^\# = T V J (T V)^{-1} \quad (\text{since } C_P^\# = T C_p^b T^{-1}).$$

$V$  is a **confluent Vandemonde matrix**.

## Remainder: Companion matrices and the Matrix exponential

**Proposition.** Suppose

$$\begin{bmatrix} \dot{\phi}_0 \\ \dot{\phi}_1 \\ \vdots \\ \dot{\phi}_{n-1} \end{bmatrix} = \underbrace{\begin{bmatrix} 0 & & & -p_0 \\ 1 & & & -p_1 \\ & \dots & & \vdots \\ & & 1 & -p_{n-1} \end{bmatrix}}_{C_p^\#} \underbrace{\begin{bmatrix} \phi_0 \\ \phi_1 \\ \vdots \\ \phi_{n-1} \end{bmatrix}}_{\phi}, \quad \begin{bmatrix} \phi_0(0) \\ \phi_1(0) \\ \vdots \\ \phi_{n-1}(0) \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}.$$

Then

$$p\left(\frac{d}{dt}\right)\phi_k = 0, \quad (*) \quad \text{and} \quad \phi_k^{(j)}(0) = \delta_{jk} \quad (**).$$

Thus, by our earlier results

$$p(A) = 0 \quad \Rightarrow \quad e^{At} = \sum_{k=0}^{n-1} \phi_k(t) A^k.$$

Note that the vector  $\phi$  is the first column of  $\exp(C_a^\# t)$ .

Proof. (\*) follows from  $p\left(\frac{d}{dt}\right)e^{C^\# t} = p(C^\#)e^{C^\# t} = 0$ . (\*\*) is exercise.

## Deflating pairs and standard pairs

Suppose the matrices  $L$  (quadratic) and  $V$  (may be rectangular) satisfy

$$0 = P_d V L^d + P_{d-1} V L^{d-1} + \dots + P_1 V L + P_0 V.$$

Then  $(V, L)$  is called a **deflating pair** for  $P$ . We have

(1) for any vector  $\xi$  of compatible size:  $x(t) := V e^{L(t-t_0)} \xi \Rightarrow P\left(\frac{d}{dt}\right)x = 0.$

$$(2) \quad \begin{bmatrix} 0 & I & & & \\ & & I & & \\ & & & \ddots & \\ & & & & I \\ -P_0 & -P_1 & \dots & \dots & -P_{d-1} \end{bmatrix} \underbrace{\begin{bmatrix} V \\ V L \\ \vdots \\ V L^{d-1} \end{bmatrix}}_{=:V_L} = \begin{bmatrix} V \\ V L \\ \vdots \\ P_d V L^{d-1} \end{bmatrix} L.$$

If  $V_L$  is nonsingular (which implies  $V \in \mathbb{C}^{n \times nd}$ ,  $L \in \mathbb{C}^{nd \times nd}$ )

then  $(V, L)$  is called a **standard pair** for  $P$ .

Let  $(V, L)$  be a standard pair and suppose that  $P_d$  is nonsingular. Then  $P\left(\frac{d}{dt}\right)x = f$  if and only if

$$x(t) = V \left( e^{L(t-t_0)} \xi + \int_{t_0}^t e^{L(t-s)} B f(s) ds \right), \quad B := V_L^{-1} \begin{bmatrix} 0 \\ \vdots \\ 0 \\ P_d^{-1} \end{bmatrix}, \quad \xi = V_L^{-1} \begin{bmatrix} x(t_0) \\ \dot{x}(t_0) \\ \vdots \\ x^{(d-1)}(t_0) \end{bmatrix}.$$

## Additivity of deflating pairs

If  $(V_1, L_1)$  and  $(V_2, L_2)$  are deflating pairs for  $P$   
then  $([V_1, V_2], \text{diag}(L_1, L_2))$  is a deflating pair for  $P$ .

**Proof.** The identities

$$0 = P_d V_1 L_1^d + P_{d-1} V_1 L_1^{d-1} + \dots + P_1 V_1 L_1 + P_0 V_1,$$

$$0 = P_d V_2 L_2^d + P_{d-1} V_2 L_2^{d-1} + \dots + P_1 V_2 L_2 + P_0 V_2$$

are equivalent to

$$0 = P_d [V_1, V_2] \begin{bmatrix} L_1 & 0 \\ 0 & L_2 \end{bmatrix}^d + P_{d-1} [V_1, V_2] \begin{bmatrix} L_1 & 0 \\ 0 & L_2 \end{bmatrix}^{d-1} + \dots + P_1 [V_1, V_2] \begin{bmatrix} L_1 & 0 \\ 0 & L_2 \end{bmatrix} + P_0 [V_1, V_2].$$

□



## Regularity, eigenvalues and eigenvectors

- The matrix Polynomial  $P(\lambda) = \sum_{k=0}^d P_k \lambda^k \in \mathbb{C}^{n \times n}[\lambda]$  is said to be **regular**, if its **characteristic polynomial**

$$\chi(\lambda) := \det(P(\lambda))$$

is not the zero polynomial. In this case its degree is  $\leq dn$ .

- $(v, \lambda)$  is called an **eigenpair** to the polynomial  $P$  with **eigenvector**  $v \in \mathbb{C}^n \setminus \{0\}$  and **eigenvalue**  $\lambda \in \mathbb{C}$  if

$$P(\lambda)v = 0.$$

(1) The eigenvalues of  $P$  are the zeros of  $\chi(\lambda)$ .

(2)  $(v, \lambda)$  is an eigenpair if and only if

$$\begin{bmatrix} 0 & I & & & \\ & & I & & \\ & & & \ddots & \\ & & & & I \\ -P_0 & -P_1 & \dots & \dots & -P_{d-1} \end{bmatrix} \underbrace{\begin{bmatrix} v \\ v\lambda \\ \vdots \\ v\lambda^{d-1} \end{bmatrix}}_{=:q(v,\lambda)} = \begin{bmatrix} v \\ v\lambda \\ \vdots \\ P_d v \lambda^{d-1} \end{bmatrix} \lambda$$

(3) If  $P(\lambda_i)v_i = 0$ ,  $i = 1, \dots, m$  then

$$V = [v_1, \dots, v_m], \quad L = \text{diag}(\lambda_1, \dots, \lambda_m)$$

form a deflating pair for  $P$ .

(4) Eigenvectors  $v_i$  to different eigenvalues  $\lambda_i$  are not necessarily linearly independent. However, the vectors  $q(v_i, \lambda_i)$  are linearly independent if  $P_d$  is nonsingular.

## Jordan chains I (finite eigenvalues)

Let  $v_0, \dots, v_{\ell-1} \in \mathbb{C}^n$ ,  $v_0 \neq 0$ , be a finite sequence of vectors. Let  $P(\lambda) = \sum_{k=0}^d P_k \lambda^k$ .

Then the following statements are equivalent for  $\lambda_0 \in \mathbb{C}$ . (proof by direct computation)

$$(i) \begin{bmatrix} P(\lambda_0) & & & & \\ P'(\lambda_0) & P(\lambda_0) & & & \\ \vdots & & \ddots & & \\ \frac{P^{(\ell-1)}(\lambda_0)}{(\ell-1)!} & \dots & P'(\lambda_0) & P(\lambda_0) & \end{bmatrix} \begin{bmatrix} v_0 \\ v_1 \\ \vdots \\ v_{\ell-1} \end{bmatrix} = 0 \quad \text{i.e.} \quad \sum_{k=0}^m \frac{P^{(m-k)}(\lambda_0)}{(m-k)!} v_k = 0, \quad m = 0, \dots, \ell-1.$$

$$(ii) \text{ The matrices } V = [v_0, \dots, v_{\ell-1}] \text{ and } J = \begin{bmatrix} \lambda_0 & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ & & & \lambda_0 \end{bmatrix} \text{ form a deflating pair,}$$

i.e.  $0 = P_d V J^d + P_{d-1} V J^{d-1} + \dots + P_1 V J + P_0 V$ .

$$(iii) \text{ The vector polynomial } v(\lambda) := \sum_{k=0}^{\ell-1} (\lambda - \lambda_0)^k v_k \text{ (root polynomial) satisfies}$$

$$P(\lambda) v(\lambda) = u(\lambda) (\lambda - \lambda_0)^\ell \text{ for a vector polynomial } u(\lambda).$$

$$(iv) \text{ The functions } x_m(t) = e^{\lambda_0(t-t_0)} \left( \frac{(t-t_0)^m}{m!} v_0 + \frac{(t-t_0)^{m-1}}{(m-1)!} v_1 + \dots + (t-t_0) v_{m-1} + v_m \right),$$

$m = 0, \dots, \ell-1$ , satisfy  $P\left(\frac{d}{dt}\right) x_m(t) = 0$ .

If these conditions are satisfied then the sequence  $0 \neq v_0, \dots, v_{\ell-1}$  is said to be a **Jordan chain** of length  $\ell$  to the finite eigenvalue  $\lambda_0$  of  $P(\lambda)$ .

**A computation.** We show  $(i) \Leftrightarrow (iv)$  from the former slide. W.l.o.g.  $t_0 = 0$ .

$$\text{Let } c_m := \sum_{k=0}^m \frac{P^{(m-k)}(\lambda_0)}{(m-k)!} v_k = \sum_{j=0}^m \frac{P^{(j)}(\lambda_0)}{j!} v_{m-j}.$$

For any smooth function  $f(t)$ :  $\left(\frac{d}{dt} - \lambda_0\right) (e^{\lambda_0 t} f(t)) = e^{\lambda_0 t} \frac{df}{dt}(t)$ .

Thus, Taylor expansion of the polynomial  $P$  at  $\lambda_0$  yields

$$P\left(\frac{d}{dt}\right) (e^{\lambda_0 t} f(t)) = \sum_{j=0}^{\infty} \frac{P^{(j)}(\lambda_0)}{j!} \left(\frac{d}{dt} - \lambda_0\right)^j (e^{\lambda_0 t} f(t)) = e^{\lambda_0 t} \sum_{j=0}^{\infty} \frac{P^{(j)}(\lambda_0)}{j!} \frac{d^j f}{dt^j}(t)$$

The sum is indeed finite. Now, for a vector polynomial  $f$ ,

$$f(t) := \sum_{k=0}^m v_{m-k} \frac{t^k}{k!} \quad \Rightarrow \quad \frac{d^j f}{dt^j}(t) = \sum_{k=j}^m v_{m-k} \frac{t^{k-j}}{(k-j)!} = \sum_{s=0}^{m-j} v_{m-j-s} \frac{t^s}{s!}.$$

Thus,

$$P\left(\frac{d}{dt}\right) (e^{\lambda_0 t} f(t)) = e^{\lambda_0 t} \sum_{j=0}^{\infty} \frac{P^{(j)}(\lambda_0)}{j!} \sum_{s=0}^{m-j} v_{m-j-s} \frac{t^s}{s!} = e^{\lambda_0 t} \sum_{s=0}^m \underbrace{\left( \sum_{j=0}^{m-s} \frac{P^{(j)}(\lambda_0)}{j!} v_{(m-s)-j} \right)}_{c_{m-s}} \frac{t^s}{s!}.$$

Thus,  $P\left(\frac{d}{dt}\right) (e^{\lambda_0 t} f(t)) = 0 \quad \Leftrightarrow \quad c_s = 0, \text{ for } s = 0, \dots, m. \quad \square$

If  $v(\lambda) := \sum_{k=0}^{\ell-1} (\lambda - \lambda_0)^k v_k$  then  $P(\lambda) v(\lambda) = \sum_s c_s (\lambda - \lambda_0)^s$ . Hence,  $(i) \Leftrightarrow (iii)$ .

## Canonical set of Jordan chains and local Smith form

For a regular  $P(\lambda) \in \mathbb{C}^{n \times n}[\lambda]$  consider its **local Smith form** at the eigenvalue  $\lambda_0$ :

$$P(\lambda) \underbrace{[v_1(\lambda) \ v_2(\lambda) \ \dots \ v_n(\lambda)]}_{V(\lambda)} = \underbrace{[u_1(\lambda) \ u_2(\lambda) \ \dots \ u_n(\lambda)]}_{U(\lambda)} \begin{bmatrix} (\lambda - \lambda_0)^{\ell_1} & & \\ & \dots & \\ & & (\lambda - \lambda_0)^{\ell_n} \end{bmatrix}.$$

with  $V(\lambda), U(\lambda) \in \mathbb{C}^{n \times n}[\lambda]$ ,  $\det(V(\lambda)) \neq 0 \neq \det(U(\lambda))$  and partial multiplicities  $\ell_i$ .

The vector polynomials  $v_i(\lambda), u_i(\lambda)$  satisfy  $P(\lambda) v_i(\lambda) = u_i(\lambda) (\lambda - \lambda_0)^{\ell_i}$ .

Thus, if  $\ell_i > 0$  then  $v_i(\lambda) = \sum v_{i,k} (\lambda - \lambda_0)^k$  is a root polynomial for  $P$ , and its coefficients

$$V_i = [v_{i,0} \ v_{i,1} \ \dots \ v_{i,\ell_i-1}]$$

form a Jordan chain to the eigenvalue  $\lambda_0$ . The collection of all these chains

$$V = [\dots V_i \dots], \quad \ell_i > 0$$

is said to be a **canonical set** of Jordan chains to the eigenvalue  $\lambda_0$ . Let

$$J = \text{diag}(\dots J_i(\lambda_0) \dots), \quad \ell_i > 0$$

be a Jordan matrix with Jordan blocks  $J_i(\lambda_0)$  of size  $\ell_i$ . Then

$$0 = P_d V J^d + P_{d-1} V J^{d-1} + \dots + P_1 V J + P_0 V \quad (\text{deflating pair}).$$

## Homogenization, reverse polynomial and eigenvalue $\infty$

Consider the matrix polynomial  $P(\lambda) = \sum_{k=0}^d P_k \lambda^k \in \mathbb{C}^{n \times n}[\lambda]$ .

By setting  $\lambda = \alpha/\beta$  and multiplying with  $\beta^d$  we obtain the homogenization of  $P$ :

$$P_h(\alpha, \beta) := \beta^d P\left(\frac{\alpha}{\beta}\right) = \beta^d \sum_{k=0}^d P_k \left(\frac{\alpha}{\beta}\right)^k = \sum_{k=0}^d P_k \alpha^k \beta^{d-k}.$$

Observe that

$$P(\lambda) = P_h(\lambda, 1).$$

The **reverse of  $P$**  is defined as

$$P_r(\lambda) := P_h(1, \lambda) = \sum_{k=0}^d P_k \lambda^{d-k} = \sum_{k=0}^d P_{d-k} \lambda^k.$$

Analogously the char. polynomial  $\chi(\lambda) = \det(P(\lambda))$  is made homogeneous and reversed:

$$\chi_h(\alpha, \beta) := \beta^{nd} \chi\left(\frac{\alpha}{\beta}\right), \quad \chi_r(\lambda) = \chi_h(1, \lambda).$$

**Definition of infinite eigenvalue.** Let  $m > 0$ .

$P$  has eigenvalue  $\infty$  of alg. multiplicity  $m$   $\Leftrightarrow$   $P_r$  has eigenvalue 0 of alg. multiplicity  $m$   
 $\Leftrightarrow$  0 is a zero of multiplicity  $m$  of  $\chi_r$   
 $\Leftrightarrow$   $\chi$  has degree  $nd - m$ .

## Jordan chains II (infinite eigenvalue)

Let  $v_0, \dots, v_{\ell-1} \in \mathbb{C}^n$ ,  $v_0 \neq 0$ , be a finite sequence of vectors.

$$\text{Let } P(\lambda) = \sum_{k=0}^d P_k \lambda^k \text{ and } N = \begin{bmatrix} 0 & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ & & & 0 \end{bmatrix}.$$

Then the following statements are equivalent.

(i)  $V = [v_0, v_1, \dots, v_{\ell-1}]$  is a Jordan chain to the eigenvalue 0 of the reverse poly.  $P_r$ .

(ii)  $0 = P_d V + P_{d-1} V N + \dots + P_1 V N^{d-1} + P_0 V N^d$ .

$$(iii) \quad \begin{bmatrix} 0 & I & & & \\ & & I & & \\ & & & \ddots & \\ & & & & I \\ -P_0 & -P_1 & \dots & \dots & -P_{d-1} \end{bmatrix} \underbrace{\begin{bmatrix} V N^{d-1} \\ V N^{d-2} \\ \vdots \\ V \end{bmatrix}}_{=: V_N} N = \begin{bmatrix} V N^{d-1} \\ V N^{d-2} \\ \vdots \\ P_d V \end{bmatrix}.$$

**Definition:** Any pair  $(V, N)$  with nilpotent  $N$  satisfying (2) is called a deflating pair to the eigenvalue  $\infty$ .

## Structure of Quasi-Weierstrass form of the companion pencil

Consider the Quasi-Weierstrass form of the companion pencil  $C_P^b(\lambda)$  of the regular matrix polynomial  $P(\lambda) \in \mathbb{C}^{n \times n}[\lambda]$ ,

$$\underbrace{\left( \lambda \begin{bmatrix} I & & & \\ & \ddots & & \\ & & I & \\ & & & P_d \end{bmatrix} - \begin{bmatrix} 0 & I & & \\ & & I & \\ & & & \ddots \\ -P_0 & -P_1 & \dots & \dots & -P_{d-1} \end{bmatrix} \right)}_{C_P^b(\lambda)} [V_F, V_\infty] = [U_F, U_\infty] \left( \lambda \begin{bmatrix} I & 0 \\ 0 & N \end{bmatrix} - \begin{bmatrix} L & 0 \\ 0 & I \end{bmatrix} \right)$$

Then

$$V_F = \begin{bmatrix} V \\ V L \\ \vdots \\ V L^{d-1} \end{bmatrix}, \quad V_\infty = \begin{bmatrix} \hat{V} N^{d-1} \\ \hat{V} N^{d-2} \\ \vdots \\ \hat{V} \end{bmatrix},$$

and

$$\begin{aligned} 0 &= P_d V L^d + P_{d-1} V L^{d-1} + \dots + P_1 V L + P_0 V, \\ 0 &= P_d \hat{V} + P_{d-1} \hat{V} N + \dots + P_1 \hat{V} N^{d-1} + P_0 \hat{V} N^d. \end{aligned}$$

for some  $V, \hat{V} \in \mathbb{C}^{n \times dn}$ .

If  $L$  and  $N$  are in Jordan form then the columns of  $V$  and  $\hat{V}$  form Jordan chains of  $P$ .

## Solution formula for monic polynomials (same as in scalar case)

Let  $\Phi_0, \dots, \Phi_{d-1} : \mathbb{R} \rightarrow \mathbb{C}^{n \times n}$  be the solutions of the homogeneous initial value problem

$$\Phi_k^{(d)}(t) + P_{d-1} \Phi_k^{(d-1)}(t) + \dots + P_1 \dot{\Phi}_k(t) + P_0 \Phi_k(t) = 0, \quad \Phi_k^{(j)}(0) = \delta_{jk} I, \quad j = 0, \dots, d-1$$

(Bohl functions). Then

$$x : \mathbb{R} \rightarrow \mathbb{C}^{n \times n}, \quad x(t) = \sum_{k=0}^{d-1} \Phi_k(t - t_0) x_k + \int_{t_0}^t \Phi_{d-1}(t - s) f(s) ds$$

is the unique solution of the initial value problem

$$x^{(d)}(t) + P_{d-1} x^{(d-1)}(t) + \dots + P_1 \dot{x}(t) + P_0 x(t) = f(t), \quad x^{(k)}(t_0) = x_k.$$

The basis solutions  $\Phi_k$  can be computed in the following way.

Step 1. Perform partial fraction expansion:

$$P(\lambda)^{-1} = \sum_{k=1}^r \sum_{j=1}^{m_k} \frac{A_{kj}}{(\lambda - \lambda_k)^j} \Rightarrow \Phi_{d-1}(t) := \sum_{k=1}^r e^{\lambda_k t} \sum_{j=1}^{m_k} A_{kj} \frac{t^{j-1}}{(j-1)!}.$$

Step 2. Set

$$\begin{aligned} \Phi_{d-2} &:= P_{d-1} \Phi_{d-1} + \dot{\Phi}_{d-1}, \\ \Phi_{d-3} &:= P_{d-2} \Phi_{d-1} + \dot{\Phi}_{d-2}, \\ &\vdots \\ \Phi_0 &:= P_1 \Phi_{d-1} + \dot{\Phi}_1. \end{aligned}$$



## Remarks on ODE of second order

The ODE/DAE of second order

$$M \ddot{x} + C \dot{x} + K x = f,$$

is equivalent to

$$(1) \quad \begin{bmatrix} \tilde{I} & 0 \\ 0 & M \end{bmatrix} \frac{d}{dt} \begin{bmatrix} x \\ \dot{x} \end{bmatrix} = \begin{bmatrix} 0 & \tilde{I} \\ -K & -C \end{bmatrix} \begin{bmatrix} x \\ \dot{x} \end{bmatrix} + \begin{bmatrix} 0 \\ f \end{bmatrix} \quad \tilde{I} \text{ nonsingular.}$$

$$(2) \quad \begin{bmatrix} C & M \\ \tilde{I} & 0 \end{bmatrix} \frac{d}{dt} \begin{bmatrix} x \\ \dot{x} \end{bmatrix} = \begin{bmatrix} -K & 0 \\ 0 & \tilde{I} \end{bmatrix} \begin{bmatrix} x \\ \dot{x} \end{bmatrix} + \begin{bmatrix} f \\ 0 \end{bmatrix} \quad \tilde{I} \text{ nonsingular,}$$

$$(3) \quad \begin{bmatrix} M & C \\ 0 & M \end{bmatrix} \frac{d}{dt} \begin{bmatrix} \dot{x} \\ x \end{bmatrix} = \begin{bmatrix} 0 & -K \\ M & 0 \end{bmatrix} \begin{bmatrix} \dot{x} \\ x \end{bmatrix} + \begin{bmatrix} f \\ 0 \end{bmatrix},$$

$$(4) \quad \begin{bmatrix} 0 & K \\ -M & 0 \end{bmatrix} \frac{d}{dt} \begin{bmatrix} \dot{x} \\ x \end{bmatrix} = \begin{bmatrix} K & 0 \\ C & K \end{bmatrix} \begin{bmatrix} \dot{x} \\ x \end{bmatrix} + \begin{bmatrix} 0 \\ f \end{bmatrix}.$$

Many other equivalent formulations are possible. See next pages.

## Remarks on ODE of second order

Consider again

$$M \ddot{x} + C \dot{x} + K x = f, \quad (*)$$

If  $M, C, K$  are Hermitian positive semidefinite the associated **energy** is defined as

$$w(x, \dot{x}) = \frac{1}{2}(\dot{x}^* M \dot{x} + x^* K x).$$

It follows that

$$\frac{d}{dt} w(x, \dot{x}) = -\dot{x}^* C \dot{x} + \Re(f^* \dot{x}) \leq \Re(f^* \dot{x})$$

(This is a **dissipation inequality**. storage:  $w(x, \dot{x})$ . supply:  $\Re(f^* \dot{x})$ )

Veselic: If  $M$  and  $K$  are both positive definite factorize  $K = L_1^* L_1$ ,  $M = L_2^* L_2$  and define

$$y := \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} L_1 x \\ L_2 \dot{x} \end{bmatrix}, \quad \Omega := L_2^{-1} L_1, \quad D := L_2^{-1} C L_2^{-*}, \quad A := \begin{bmatrix} 0 & \Omega^* \\ -\Omega & -D \end{bmatrix}.$$

Then (\*) is equivalent to

$$\dot{y} = A y + \begin{bmatrix} 0 \\ L_2^{-1} f \end{bmatrix},$$

and we have

$$w(x, \dot{x}) = \frac{1}{2} \|y\|_2^2, \quad f = 0 \Rightarrow \frac{d}{dt} \|y\|_2^2 = -y_2^* D y_2 \leq 0, \quad \|e^{A t}\|_2 \leq 1.$$

## Literature

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