

# Probability and Statistics

## MA20205

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# Probability

- Probability theory - Kolmogorov
- Probability theory  $\mapsto$  Mathematical statistics

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## Sample space

- ▶ Discrete sample space - countable sample points
  - ▶ Continuous sample space - uncountable sample points
- 
- Example: roll a pair of dice:

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## Sample space

- ▶ Discrete sample space - countable sample points
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- Example: roll a pair of dice:

$$S = \{(x, y) : 1 \leq x \leq 6, 1 \leq y \leq 6\}$$

- ▶ Events: sum of the outcomes is equal to 8

# Probability

## $\sigma$ -field

A set  $A \subseteq S$  is an event if  $A \in \mathcal{F} \subset \mathcal{P}(S)$ , power set of  $S$  such that

- $S \in \mathcal{F}$
- if  $A \in \mathcal{F}$  then  $A^c \in \mathcal{F}$
- if  $A_j \in \mathcal{F}, j \geq 1$  then  $\bigcup_{j=1}^{\infty} A_j \in \mathcal{F}$

**Question:** Why do we need the notion of  $\sigma$ -field?

# Probability

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## Probability measure (axiomatic definition)

Probability is function  $P : \mathcal{F} \rightarrow [0, 1]$  - it assigns nonnegative numbers to events such that

- $P(S) = 1$
- (addition rule)

$$P\left(\bigcup_{k=1}^{\infty} A_k\right) = \sum_{k=1}^{\infty} P(A_k)$$

if  $A_1, A_2, \dots, A_k, \dots$  are **disjoint** events of  $S$



# Probability

## Properties of probability

- $P(\emptyset) = 0$
- For any finite collection of **mutually exclusive** events:  $\{A_1, A_2, \dots, A_n\}$  with  $A_i \cap A_j = \emptyset$  if  $i \neq j$  then

$$P\left(\bigcup_{k=1}^n A_k\right) = \sum_{k=1}^n P(A_k)$$

- For a discrete sample space  $S = \{s_1, s_2, \dots\}$ ,

$$P(S) = \sum_{k=1}^{\infty} P(\{s_k\})$$

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**Question:** Does  $P(A) = 1$  imply  $A = S$ ?

# Probability

**Question:** Is the axiomatic definition a more general definition than the classical one?

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**Derive:** for equally likely sample points,

$$P(A) = \frac{\#A}{\#S}$$

# Probability

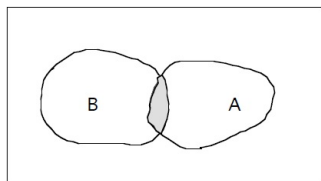
Some more properties of probability measure (use Venn diagram)

- $P(A^c) = 1 - P(A)$
- if  $A \subseteq B \subseteq S$  then  $P(A) \leq P(B)$
- $P(A \cup B) = P(A) + P(B) - P(A \cap B)$
- Let  $A_1 \subseteq A_2$ . Then

$$P(A_2 \setminus A_1) = P(A_2) - P(A_1)$$

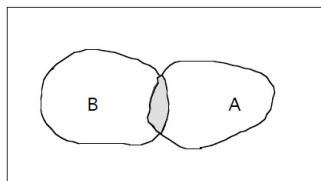
Problems: .....

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**Question:** For a finite sample space, how do we define probability of  $A$  given that  $B$  has happened?

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$$P(A \text{ given } B) = \frac{\text{number of elements of } A \cap B}{\text{number of elements of } B}$$

# Probability

## Conditional probability

For both discrete and continuous sample space:

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

provided  $P(B) > 0$ .



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## Conditional probability measure:

- $P(A|B) \geq 0$  for all event  $A$
- $P(B|B) = 1$
- (addition rule)

$$P\left(\bigcup_{k=1}^{\infty} A_k | B\right) = \sum_{k=1}^{\infty} P(A_k | B)$$

for mutually exclusive events  $A_1, A_2, \dots, A_k, \dots$

Problems...