# Big Data Analysis (MA60306) 

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Lecture 10
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## Singular value decomposition

## SVD as transformation



## Eigenvalue decomposition

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Let $A \in \mathbb{R}^{n \times d}$ be a data matrix. Then

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M_{R}=A^{T} A \in \mathbb{R}^{d \times d} \text { and } M_{L}=A A^{T} \in \mathbb{R}^{n \times n}
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$\rightarrow$ Then

$$
M_{R} v_{j}=v_{j} \sigma_{i}^{2}
$$

i.e. the $j$ the right singular vector of $A$ is the $j$ th eigenvector of $M_{R}=A^{T} A$ corresponding to the eigenvalue $\lambda_{j}=\sigma_{j}^{2}$

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Power method - a simple iterative algorithm for computing the first eigenvector and eigenvalue

$$
\text { PowerMethod }\left(M=A^{T} A, q\right)
$$

Initialize $u^{(0)}$ as random unit vector
for $i=1$ to $q$ do

$$
\begin{aligned}
& \quad u^{(i)}:=M u^{(i-1)} \\
& \text { return } v=u^{(q)} /\left\|u^{(q)}\right\|
\end{aligned}
$$

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A_{1}:=A-A v_{1} v_{1}^{T} \text { (deflation), } M_{1}:=A_{1} A_{1}^{T}
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Recall: $\alpha_{j}=v_{j}^{T} u^{(0)}$, since it is random, it is possible to claim that with probability at least $1 / 2$ that for any $\alpha_{j}$ we have $\left|\alpha_{j}\right| \geq \frac{1}{2 \sqrt{n}}$

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$$
M^{q} v_{j}=M^{q-1}\left(\lambda_{j} v_{j}\right)=M^{q-2}\left(v_{j} \lambda_{j}\right) \lambda_{j}=\ldots=v_{j} \lambda_{j}^{q}
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Then

$$
v=M^{q} u^{(0)}=\sum_{j=1}^{d} \frac{\alpha_{j} \lambda_{j}^{q}}{\sqrt{\sum_{j=1}^{d}\left(\alpha_{j} \lambda_{j}^{q}\right)^{2}}} v_{j}
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Further

$$
\begin{aligned}
\left|v_{1}^{T} M^{q} u^{(0)}\right| & =\frac{\alpha_{1} \lambda_{1}^{q}}{\sqrt{\sum_{j=1}^{d}\left(\alpha_{j} \lambda_{j}^{q}\right)^{2}}} \\
& \geq \frac{\alpha_{1} \lambda_{1}^{q}}{\sqrt{\alpha_{1}^{2} \lambda_{1}^{2 q}+d \lambda_{2}^{2 q}}} \\
& \geq \frac{\alpha_{1} \lambda_{1}^{q}}{\alpha_{1} \lambda_{1}^{q}+\sqrt{d} \lambda_{2}^{q}}=1-\frac{\lambda_{2}^{q} \sqrt{d}}{\alpha_{1} \lambda_{1}^{q}+\sqrt{d} \lambda_{2}^{q}} \\
& \geq 1-2 d\left(\frac{\lambda_{2}}{\lambda_{1}}\right)^{q}
\end{aligned}
$$

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$\rightarrow$ Given a data point $\boldsymbol{a}_{j} \in \mathbb{R}^{d}$ and a vector $\boldsymbol{v} \in \mathbb{R}^{d}$, the projection of $\boldsymbol{a}_{j}$ onto $\boldsymbol{v}$ is

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\pi_{\boldsymbol{v}}\left(\boldsymbol{a}_{j}\right)=\left\langle\boldsymbol{v}, \boldsymbol{a}_{j}\right\rangle \boldsymbol{v}=\left(\boldsymbol{a}_{j}^{T} \boldsymbol{v}\right) \boldsymbol{v}
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$\rightarrow$ Example: for a data point $\boldsymbol{p} \in \mathbb{R}^{3}$ and a a two dimensional subspace $V$ with basis $\left\{\boldsymbol{v}_{1}, \boldsymbol{v}_{2}\right\}$,

$$
\pi_{V}(\boldsymbol{p})=\alpha_{1}(\boldsymbol{p}) \boldsymbol{v}_{1}+\alpha_{2}(\boldsymbol{p}) \boldsymbol{v}_{2}
$$

where $\alpha_{1}(\boldsymbol{p})=\boldsymbol{p}^{T} \boldsymbol{v}_{1}$ and $\alpha_{2}(\boldsymbol{p})=\boldsymbol{p}^{T} \boldsymbol{v}_{2}$

## Principal component analysis



## Principal component analysis


$\rightarrow$ The goal is to find the best fitting subspace $V^{*}$ such that the sum of squared errors (SSE)

$$
\operatorname{SSE}(A, V)=\sum_{\mathbf{a}_{j} \in A}\left\|\boldsymbol{a}_{j}-\pi_{V}\left(\mathbf{a}_{j}\right)\right\|^{2}
$$

is minimized and the desired $k$-dimensional subspace is

$$
V^{*}=\arg \min _{V} \operatorname{SSE}(A, V)
$$

## Principal component analysis

$\rightarrow$ Using SVD: Let $A$ has rank $r$ and $\boldsymbol{v}_{1}, \ldots, \boldsymbol{v}_{r}$ are right singular vectors of $A$ with singular values $\sigma_{j}^{2}=\left\|A \boldsymbol{v}_{j}\right\|_{2}^{2}$. Then setting $B=\left\{\boldsymbol{v}_{1}, \ldots, \boldsymbol{v}_{k}\right\}, k \leq r$, for any data point $\boldsymbol{a}$,

$$
\left\|\boldsymbol{a}-\pi_{B}(\boldsymbol{a})\right\|^{2}=\left\|\sum_{j=1}^{d}\left(\boldsymbol{a}^{T} \boldsymbol{v}_{j}\right) v_{j}-\sum_{j=1}^{k}\left(\boldsymbol{a}^{T} \boldsymbol{v}_{j}\right) v_{j}\right\|^{2}=\sum_{j=k+1}^{d}\left(\boldsymbol{a}^{T} \boldsymbol{v}_{j}\right)^{2}
$$

So the projection error of the subspace $V_{B}$, spanned by $B$ is that part of $A$ in the last $(d-k)$ right singular vectors.

## Principal component analysis

$\rightarrow$ Projection error for the given data points:

$$
\sum_{i=1}^{n}\left\|\boldsymbol{a}_{i}-\pi_{B}\left(\boldsymbol{a}_{i}\right)\right\|^{2}=\sum_{i=1}^{n}\left(\sum_{j=k+1}^{d}\left(\boldsymbol{a}_{i}^{T} \boldsymbol{v}_{j}\right)^{2}\right)
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& =\sum_{j=k+1}^{d}\left(\sum_{i=1}^{n}\left(\boldsymbol{a}_{i}^{T} \mathbf{v}_{j}\right)^{2}\right)=\sum_{k+1}^{d}\left\|A \boldsymbol{v}_{j}\right\|^{2}=\sum_{j=k+1}^{d} \sigma_{j}^{2} \\
& =\operatorname{SSE}(A, B)=\sum_{a_{i} \in A}\left\|\mathbf{a}_{i}-\pi_{B}\left(\boldsymbol{a}_{i}\right)\right\|^{2}=\left\|A-\pi_{B}(A)\right\|_{F}^{2}
\end{aligned}
$$



