

# **EE60039: Probability and Random Processes for Signals and Systems**

**Instructor: Prof. Ashish R. Hota**

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## Logistics:

- **Class Timing:** Monday: 12 noon - 12:55pm; Tuesday: 10am - 11:55am,
- **Venue:** NC 244
- **Instructor Email:** ashish.hota@ieee.org. Use EE60039 in Subject Line.
- **Course Website:** <http://www.facweb.iitkgp.ac.in/~ahota/prob.html>

## Syllabus:

**Module A: Introduction to Probability and Random Variables. 4 Weeks. Main Reference: Chapters 1-5 of Wasserman.**

1. Probability Space. Independence. Conditional Probability. [Chapter 1 of Hajek, Chapter 2-5 of Chan, Chapter 1 of Gallager]
2. Random Variables and Vectors. Discrete and Continuous Distributions. [Chapter 1 of Hajek, Chapter 2-5 of Chan, Chapter 1 of Gallager]
3. Expectation, Moments, Characteristic Functions. [Chapter 1 of Hajek, Chapter 2-5 of Chan, Chapter 1 of Gallager]
4. Inequalities and Bounds. [Chapter 1-2 of Hajek, Chapter 6 of Chan, Chapter 1 of Gallager]
5. Convergence of Random Variables. Law of Large Numbers, Central Limit Theorem. [Chapter 2 of Hajek, Chapter 6 of Chan, Chapter 1 of Gallager]

**Module B: Random Processes. 4 Weeks.**

1. Definition, Discrete-time and Continuous-time Random Processes [Chapter 4 of Hajek, Chapter 10 of Chan]
2. Stationarity, Power Spectral Density, Second order Theory [Chapter 4, 8 of Hajek, Chapter 10 of Chan]

3. Gaussian Process [Chapter 3 of Hajek, Chapter 3 of Gallager]
4. Markov Chain, Classification of States, Limiting Distributions [Chapter 4 of Gallager]

### **Module C: Basics of Bayesian Estimation. 4 Weeks.**

1. Maximum Likelihood, Maximum A Posteriori, Mean Square and Linear Mean Square Estimation [Chapter 5 of Hajek, Chapter 8 of Chan]
2. Conditional Expectation and Orthogonality [Chapter 3 of Hajek, Chapter 10 of Gallager]
3. Kalman Filters [Chapter 3 of Hajek]
4. Hidden Markov Models [Chapter 5 of Hajek]

### **Module D: Information, Entropy, and Divergence, 1 Week**

#### **Reference:**

The subject will closely follow the treatment in the following texts.

1. Larry Wasserman, **All of Statistics**, Springer Texts in Statistics, 2004. Available at: <https://link.springer.com/book/10.1007/978-0-387-21736-9>
2. Bruce Hajek, **Random Process For Engineers**, Cambridge University Press, 2015. Available at: <https://hajek.ece.illinois.edu/Papers/randomprocJuly14.pdf>
3. Robert G. Gallager, **Stochastic Processes: Theory for Applications**, Cambridge University Press, 2013.
4. Stanley H. Chan, **Introduction to Probability for Data Science**, Michigan Publishing, 2021. Available at: <https://probability4datascience.com/index.html>
5. Jason Speyer and Walter Chung, **Stochastic Processes, Estimation and Control**, SIAM, 2008.

#### **Evaluation Plan:**

1. Midsem: 30%
2. Endsem: 50%
3. Homework and Class Performance: 20%

# Probability Space

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Notations:

- $\mathbb{N}$  : set of natural numbers
- $\mathbb{R}$  : set of real numbers
- $\mathbb{Z}$ : set of integers
- $\mathbb{Q}$  : set of rational numbers
- $\mathbb{R}^+ = \{x \in \mathbb{R} \mid x \geq 0\}$  and  $\mathbb{Z}^+ = \{a \in \mathbb{Z} \mid a \geq 0\}$ .
- For a set  $X$ , we denote the set of all its subsets by  $\mathcal{P}(X)$

**Definition 1.** *Probability spaces are triplets of  $(\Omega, \mathcal{F}, \mathbb{P}(\cdot))$  consisting*

- *Sample space: A set  $\Omega$  that contains all possible outcomes.*
- *Events  $\mathcal{F}$ : This is a set consisting of **subsets** of  $\Omega$  satisfying:*
  - $\Omega \in \mathcal{F}$ ,*
  - Closed under complement:**  $E \in \mathcal{F}$  implies  $E^c \in \mathcal{F}$ , and*
  - Closed under countable union:** for any countably many subsets  $E_1, \dots, E_k, \dots \in \mathcal{F}$ , we have  $\bigcup_{k=1}^{\infty} E_k \in \mathcal{F}$ .*
- *Probability measure  $\mathbb{P}(\cdot)$ : is a function from  $\mathcal{F}$  to  $[0, 1]$  that satisfies:*
  - $\mathbb{P}(\Omega) = 1$ , and*
  - For countably many subsets  $\{E_k\}$  in  $\mathcal{F}$  that are mutually disjoint (i.e.,  $E_i \cap E_j = \emptyset$  for all  $i \neq j$ ), we have*

$$\mathbb{P}\left(\bigcup_{k=1}^{\infty} E_k\right) = \sum_{k=1}^{\infty} \mathbb{P}(E_k).$$

Note

- Any  $\mathcal{F}$  that satisfies the properties a,b, and c is called a  $\sigma$ -algebra over  $\Omega$ , and  $(\Omega, \mathcal{F})$  is called a *measurable space*.

## Examples

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- Toss of a coin:  $\Omega = \{H, T\}$
- Roll of a dice:  $\Omega = \{1, 2, 3, 4, 5, 6\}$
- Waiting time for the next bus:  $\Omega = \{t \geq 0\}$
- Each event is a subset of  $\Omega$ .
- Event is "yes/no questions that can be answered after the experiment is conducted and the outcome is known"
- Example of measurable space:  $\Omega = \{0, 1\}$ , and  $\mathcal{F} = \{\emptyset, \{1\}, \{2\}, \{1, 2\}\}$ .
- Example of measurable space: In general, power set  $\mathcal{P}(\Omega)$  is a  $\sigma$ -algebra for any  $\Omega$ .
- Example of measurable space:  $\{\emptyset, \Omega\}$  is a  $\sigma$ -algebra for any  $\Omega$ .
- What if  $\Omega$  is uncountable such as  $\mathbb{R}^n$ ? Fortunately, for  $\mathbb{R}^n$  there exists a  $\sigma$ -algebra that we can define meaningful measures (such as uniform) in  $\mathbb{R}^n$ , namely the *Borel*  $\sigma$ -algebra.
- Probability measure  $\mathbb{P}$  **measures the size of a set (an event)**.
- Example: Does the following define a probability space?  
 $\Omega_1 = \{1, 2, 3\}$ ,  $\mathcal{F}_1 = \{\emptyset, \Omega, \{1\}, \{2, 3\}\}$   
 $\mathbb{P}_1[\emptyset] = 0.5, \mathbb{P}_1[\{1\}] = 0.3$   
 $\mathbb{P}_1[\Omega] = 0.2, \mathbb{P}_1[\{2, 3\}] = 0.9$ .
- Countable Union: Example: (i)  $A_i = [-1, 1 - \frac{1}{i}]$ ,  $i = 1, 2, \dots$   
Specifically,  $A_1 = [-1, 0], A_2 = [-1, 0.5], \dots, A_{10} = [-1, 0.9]$   
 $\bigcup_{i=1}^{\infty} A_i = \{a \mid a \in A_i \text{ for some finite } i\} = [-1, 1]$ .
- Homework:  
 $B_n = [0, 1 - \frac{1}{n})$ ,  $\bigcap_{n=1}^{\infty} B_n = ?$   
 $C_n = [0, 1 + \frac{1}{n})$ ,  $\bigcap_{n=1}^{\infty} C_n = ?$

## Elementary Properties implied by probability axioms

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Let  $A, B \in \mathcal{F}$ . Then, the following properties are true.

1.  $A \subseteq B$ , then  $\mathbb{P}(A) \leq \mathbb{P}(B)$ .
2.  $\mathbb{P}(A^c) = 1 - \mathbb{P}(A)$ .
3.  $\mathbb{P}(A \cup B) = \mathbb{P}(A) + \mathbb{P}(B) - \mathbb{P}(A \cap B) \leq \mathbb{P}(A) + \mathbb{P}(B)$ .
4.  $\mathbb{P}\left(\bigcup_{i=1}^N A_i\right) \leq \sum_{i=1}^N \mathbb{P}(A_i)$  for every  $N$ , including  $N = \infty$ . (Union bound)

## Conditional Probability and Independence

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**Definition 2.** Consider a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ . Consider events  $A$  and  $B$  with  $\mathbb{P}(B) > 0$ . The **conditional probability of  $A$  given  $B$**  is

$$\mathbb{P}(A | B) := \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)}.$$

**Definition 3.** A countable collection of events  $\{A_1, A_2, \dots\}$  are said to be *mutually independent*, if any finite collection from the above,  $\{A'_1, A'_2 \dots A'_k\}$  satisfies

$$\mathbb{P}(A'_1 \cap A'_2 \dots \cap A'_k) = \mathbb{P}(A'_1) \cdot \mathbb{P}(A'_2) \dots \mathbb{P}(A'_k).$$

Notes:

- If  $A, B$  are independent,  $\mathbb{P}(B) > 0$ , then  
 $\mathbb{P}(A \cap B) = \mathbb{P}(A) \cdot \mathbb{P}(B) \Rightarrow \mathbb{P}(A | B) = \mathbb{P}(A)$ .  
Knowledge that event  $B$  is true gives you no further information about occurrence of  $A$ .
- Suppose  $A$  and  $B$  are disjoint can they be independent?  
No. Disjoint is the strongest form of dependence. Occurrence of one event rules out the occurrence of the other.

## Baye's Law

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**Proposition 1.** Let  $\Omega$  be the set of outcomes. Let  $\{A_1, A_2, \dots, A_k\}$  form a partition of  $\Omega$ , and let  $B$  be another event. Then,

- $\{A_1 \cap B, A_2 \cap B, \dots, A_k \cap B\}$  also form a partition of  $B$ .
- Law of Total Probability:

$$\mathbb{P}(B) = \sum_{i=1}^k \mathbb{P}(A_i \cap B) = \sum_{i=1}^k \mathbb{P}(B | A_i) \mathbb{P}(A_i).$$

- Baye's Law:

$$\mathbb{P}(A_i | B) = \frac{\mathbb{P}(A_i \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B | A_i) \mathbb{P}(A_i)}{\sum_{j=1}^k \mathbb{P}(B | A_j) \mathbb{P}(A_j)}.$$

Problem: Consider a disease that affects one out of every 1000 individuals. There is a test that detects the disease with 99% accuracy, that is, it classifies a healthy individual as having the disease with 1% chance, and a sick individual as healthy with 1% chance. Then,

1. What is the probability that a randomly chosen individual will test positive by the test?
2. Given that a person tests positive, what is the probability that he or she has the disease?

**Homework:** Repeat the above when detection accuracy is 99.9%, 99.99% and 99.999%.

# Random Variable

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**Definition 4.** Let  $(\Omega, \mathcal{F}, \mathbb{P}(\cdot))$  be a probability space. The mapping  $X : \Omega \rightarrow \mathbb{R}$  is called a random variable if the pre-image of any interval  $(-\infty, a]$  belongs to  $\mathcal{F}$ , i.e.

$$X^{-1}((-\infty, a]) \in \mathcal{F} \quad \text{for every } a \in \mathbb{R}, \quad (1)$$

where

$$X^{-1}(B) := \{\omega \in \Omega \mid X(\omega) \in B\}.$$

**Note:** Functions that satisfy this property are called measurable functions. Measurability is a property of the function  $X$  and the  $\sigma$ -algebra.

Example: Let  $\Omega = \{HH, TH, HT, TT\}$ . Consider two  $\sigma$ -algebras defined on  $\Omega$ .

- $\mathcal{F}_1 = \{\phi, \Omega, \{HH\}, \{HT, TH, TT\}\}$
- $\mathcal{F}_2 = \{\phi, \Omega, \{TT\}, \{HH, HT, TH\}\}$

Consider a function  $Y : \Omega \rightarrow \mathbb{R}$  such that  $Y(HH) = 1, Y(TH) = 1, Y(HT) = 1$  and  $Y(TT) = 0$ , i.e,  $Y = 1$  when at least one win toss is head, and 0, otherwise.

- Is  $Y$  a random variable with respect to  $\mathcal{F}_1$ ?
- Is  $Y$  a random variable with respect to  $\mathcal{F}_2$ ?

**A random variable is neither random, nor is it a variable.** The function  $X$  itself is deterministic. Randomness is due to uncertainty regarding which outcome  $\omega \in \Omega$  is true. Once the outcome  $\omega$  is determined, the value  $X(\omega)$  is also determined.



## (Important) Indicator Random Variable

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**Definition 5.** (*Indicator Function*) For a set  $E \subseteq \Omega$ , define the indicator function of  $E$  as

$$\mathbf{1}_E(\omega) = \begin{cases} 1 & \text{if } \omega \in E, \\ 0 & \text{if } \omega \notin E. \end{cases}$$

Show that  $\mathbf{1}_E(\omega)$  is a random-variable if and only if (iff)  $E \in \mathcal{F}$ .

Let us determine the pre-images for different  $a \in \mathbb{R}$ . We have three cases;

1. if  $a < 0$ ,  $\mathbf{1}_E^{-1}((-\infty, a]) = ?$ ,
2. if  $0 \leq a < 1$ , then  $\mathbf{1}_E^{-1}((-\infty, a]) = ?$ , and
3. if  $1 \leq a$ , then  $\mathbf{1}_E^{-1}((-\infty, a]) = ?$ .

What do we conclude from here?

# Probability Distribution of a Random Variable

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**Definition 6.** Consider a probability space  $(\Omega, \mathcal{F}, \mathbb{P}(\cdot))$  and a random variable  $X : \Omega \rightarrow \mathbb{R}$  defined on this space. The **probability distribution function** of  $X$  is a function  $F_X : \mathbb{R} \rightarrow [0, 1]$  defined as

$$F_X(\alpha) := \mathbb{P}(\{\omega : X(\omega) \leq \alpha\}) := \mathbb{P}(X^{-1}(-\infty, \alpha]) := \text{Prob}(X \leq \alpha).$$

Example: Let  $\Omega = \{H, T\}$ ,  $\mathcal{F} = 2^\Omega$ ,  $\mathbb{P}\{H\} = \mathbb{P}\{T\} = \frac{1}{2}$ . Consider two random variables.

- $Y_1(H) = 1, Y_1(T) = 0$ .
- $Y_2(H) = 0, Y_2(T) = 1$ .

Find the distribution functions  $F_{Y_1}$  and  $F_{Y_2}$ .

Properties of Distribution Function:

1.  $F_X$  is non-decreasing, i.e., if  $\alpha_1 \leq \alpha_2$ ,  $F_X(\alpha_1) \leq F_X(\alpha_2)$ .
2.  $\lim_{\alpha \rightarrow \infty} F_X(\alpha) = 1$ ,  $\lim_{\alpha \rightarrow -\infty} F_X(\alpha) = 0$ .
3.  $F_X$  is right continuous, i.e.,  $F_X(\alpha) = \lim_{\epsilon \rightarrow 0^+} F_X(\alpha + \epsilon)$ .

$F_X$  is called the **cumulative distribution function (CDF)**.

## Example

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Let  $\Omega = \{1, 2, 3\}$  and  $X : \Omega \rightarrow \mathbb{R}$  such that  $X(1) = 0.5, X(2) = 0.7, X(3) = 0.7$ .

- Find the smallest  $\sigma$ -algebra on  $\Omega$  such that  $X$  is a random variable.
- Let  $\mathbb{P}(\{1\}) = 0.3$ . Find the distribution  $F_X$ .

## Random Vectors and Random Processes

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- *Random Vectors:* Any mapping  $X : \Omega \rightarrow \mathbb{R}^n$  with  $X(\omega) = (X_1(\omega), X_2(\omega), \dots, X_n(\omega))$  is called a random vector if  $X_i$  is a random variable for all  $i = 1, \dots, n$ .
- *Random Process:* An infinitely indexed collection  $\{X_\alpha\}_{\alpha \in I}$  of random variables on  $(\Omega, \mathcal{F}, \mathbb{P})$  is called a random process.
- If the index set  $I$  is a discrete set (usually  $I = \mathbb{Z}^+$ ), the random process is called a discrete-time random process. When  $I = \mathbb{R}$  or  $I = \mathbb{R}^+$ , the random process is called a continuous-time random process.

More generally, a random variable  $X$  maps one probability space  $(\Omega_1, \mathcal{F}_1, \mathbb{P}_1)$  to another  $(\Omega_2, \mathcal{F}_2, \mathbb{P}_2)$  in a systematic manner such that

- $X : \Omega_1 \rightarrow \Omega_2$ ,
- for any event  $E_2 \in \mathcal{F}_2$ , its pre-image  $\{\omega \in \Omega_1 | X(\omega) \in E_2\} \in \mathcal{F}_1$ , and
- for any event  $E_2 \in \mathcal{F}_2$ ,  $\mathbb{P}_2(E_2) := \mathbb{P}_1(\{\omega \in \Omega_1 | X(\omega) \in E_2\})$  is called the *induced measure*.

For a real-valued random variable  $X : \Omega \rightarrow \mathbb{R}$ , the corresponding  $\sigma$ -algebra on  $\mathbb{R}$  is called the *Borel  $\sigma$ -algebra* and the induced measure gives rise to the distribution function.

## Discussion on Random Variables

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- When  $|\Omega|$  is finite, we can define the collection of events  $\mathcal{F} = 2^\Omega$ .
- However, then  $|\Omega|$  is (uncountably) infinite, there are several technical difficulties that arise in defining  $\mathcal{F} = 2^\Omega$ .
- When  $\Omega = \mathbb{R}$ , we use a specific  $\sigma$ -algebra as the set of events.

**Definition 7.** *The Borel  $\sigma$ - algebra, denoted  $\mathbb{B}(\mathbb{R})$ , is the smallest  $\sigma$ - algebra that contains all sets of the form  $(-\infty, \alpha]$  for every  $\alpha \in \mathbb{R}$ .*

- Define  $\mathcal{F} := \{(-\infty, \alpha] | \alpha \in \mathbb{R}\}$ . Is  $\mathcal{F}$  a  $\sigma$ - algebra ?
- $\mathbb{B}(\mathbb{R}) = \sigma\{\mathcal{F}\}$  is the  $\sigma$ - algebra generated by the sets contained in  $\mathcal{F}$ .
- Thus, a real-valued random variable  $X : \Omega \rightarrow \mathbb{R}$  is a mapping from an arbitrary probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  to  $(\mathbb{R}, \mathbb{B}(\mathbb{R}), \mathbb{P}_X)$  where the induced measure  $\mathbb{P}_X$  is characterized in terms of the distribution function  $F_X$ .

# Discrete Random Variable

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- A random variable is **discrete** when  $X$  takes a finite or countable number of values.
- Suppose  $X$  takes values in the set  $\{x_1, x_2, \dots, x_n\}$ . Then,

$$\mathbb{P}(X = x_1) = \mathbb{P}(\{\omega \in \Omega | X(\omega) = x_1\}) =: p_X(x_1), \dots$$

$$\mathbb{P}(X = x_n) = \mathbb{P}(\{\omega \in \Omega | X(\omega) = x_n\}) =: p_X(x_n).$$

where  $p_X$  is called the **probability mass function**.

- The quantities  $\{p_X(x_1), \dots, p_X(x_n)\}$  satisfy  $p_X(x_i) \geq 0$  and  $\sum_{i=1}^n p_X(x_i) = 1$ .
- The distribution function  $F_X$  is a stair case function.
- Example: Bernoulli Random variable ( $p$ ):  
 $X = 1$  with probability  $p$  and  $X = 0$  with probability  $1 - p$ .

- Binomial r.v ( $n, p$ ):

Outcome of  $n$  coin tosses where each coin toss comes Head with probability  $p$ .

$$\Omega = \{HH\dots H\dots T, \dots THHT\dots, TT\dots T\}$$

$X : \Omega \rightarrow \mathbb{R}$  gives the number of Heads in  $n$  coin tosses.

E.g.,  $X(HH\dots H) = n$ ,  $X(HTT\dots T) = 1$ , and so on.

Can we express a Binomial r.v in terms of a collection of Bernoulli r.v.s?

- Homework: write a program to plot the pmf and distribution of a Binomial r.v. for  $n = 25$  and  $p \in \{0, 0.2, 0.4, 0.6, 0.8, 1\}$ .

## Continuous Random Variable

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- A random variable  $X$  is continuous if there exists a function  $f_X : \mathbb{R} \rightarrow [0, \infty]$  such that for every  $\alpha \in \mathbb{R}$ , we have

$$F_X(\alpha) = \mathbb{P}(\{\omega \in \Omega | X(\omega) \leq \alpha\}) = \int_{-\infty}^{\alpha} f_X(x) dx.$$

- $f_X$ : is called the **probability density function (pdf)** of r.v.  $X$ .
- If  $F_X$  is differentiable at  $\alpha$ ,  $f_X(\alpha) = \left. \frac{dF_X(x)}{dx} \right|_{x=\alpha}$ .
- Example:  $X$  is uniformly distributed between  $[a, b]$ . The pdf is given by

$$f_X(\alpha) = \begin{cases} \frac{1}{b-a}, & \text{when } \alpha \in [a, b], \\ 0, & \text{otherwise.} \end{cases}$$

Determine the distribution function  $F_X$ .

- Example: Let  $X$  be a r.v which takes value 0 with probability 0.5. Otherwise, it is uniformly dist. between 0.5 to 1.
  1. Plot  $F_X(\alpha)$  for  $\alpha \in \mathbb{R}$ .
  2. Find  $f_X(x)$  such that  $\int_{-\infty}^{\alpha} f_X(x) dx = F_X(\alpha)$ .
- Exponential r.v. ( $\lambda > 0$ ): The pdf is given by

$$f_X(\alpha) = \begin{cases} \lambda e^{-\lambda\alpha}, & \text{when } \alpha \geq 0, \\ 0, & \text{otherwise.} \end{cases}$$

Determine the distribution function  $F_X$ .

- Gaussian r.v. ( $\mu, \sigma > 0$ ): The pdf  $f_X(\alpha) = \frac{1}{\sqrt{2\pi}\sigma} e^{\left(\frac{-(\alpha-\mu)^2}{2\sigma^2}\right)}$  for  $\alpha \in \mathbb{R}$ .

## Properties of probability density function

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For a continuous random variable  $X$ , its pdf satisfies the following properties.

1.  $f_X(x) \geq 0$ , for every  $x \in \mathbb{R}$ .
2.  $\int_{-\infty}^{\infty} f_X(x)dx = F_X(\infty) = 1$ .
3.  $f_X(x)$  is not a probability; it can take values larger than 1 at some points.
4.  $F_X(x + \epsilon) - F_X(x) = \int_{-\infty}^{x+\epsilon} f_X(x)dx - \int_{-\infty}^x f_X(x)dx = \int_x^{x+\epsilon} f_X(x)dx$ .
5.  $\mathbb{P}(a \leq X \leq b) = F_X(b) - F_X(a) = \int_a^b f_X(x)dx$ .

**Note:** If the CDF of a r.v.  $X$  is continuous at some  $\alpha$ , then  $\mathbb{P}(X = \alpha) = 0$ .



## Expectation of a Random Variable

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- A r.v.  $X$  is called a *simple random variable* if it takes finite number of possible values, i.e.,

$$X(\omega) = \begin{cases} a_1, & \text{if } \omega \in A_1 \\ a_2, & \text{if } \omega \in A_2, \dots \\ a_n, & \text{if } \omega \in A_n. \end{cases}$$

For this simple r.v  $X$ , we define  $\mathbb{E}[X] := \sum_{i=1}^n a_i \mathbb{P}(A_i) \in \mathbb{R}$ .

- Indicator r.v for event  $A$  is a simple random variable with  $\mathbb{E}[\mathbf{1}_A] = \mathbb{P}(A)$ .
- For a non-negative random variable  $X$ ,
  - there exists a sequence of simple random variables  $\{X_1, X_2, \dots\}$  which converges to  $X$ .
  - the expectation of each simple r.v in the sequence  $\{\mathbb{E}[X_1], \mathbb{E}[X_2], \dots\}$  can be computed as above, and this sequence of real number is convergent,
  - $\mathbb{E}[X] := \lim_{n \rightarrow \infty} \mathbb{E}[X_n]$ .
- For discrete r.v:  $\mathbb{E}[X] = \sum_{i=1}^n x_i \mathbb{P}(X = x_i) = \sum_{i=1}^n x_i p_X(x_i)$ .
- For continuous r.v:  $\mathbb{E}[X] = \int_{-\infty}^{\infty} x f_X(x) dx$
- General notation:  $\mathbb{E}[X] = \int x dF_X(x) = \int_{\Omega} X(\omega) d\mathbb{P}(\omega)$ .
- Note:  $\mathbb{E}[X] \in \mathbb{R}$ , i.e., expectation of a random variable is a deterministic scalar without any randomness in it.

## Properties of Expectation

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**Definition 8.** For two random variables  $X$  and  $Y$ , we define

- $X = Y$  almost surely (a.s.) if  $P[\{\omega \in \Omega | X(\omega) = Y(\omega)\}] = 1$ .
- $X \leq Y$  almost surely (a.s.) if  $P[\{\omega \in \Omega | X(\omega) \leq Y(\omega)\}] = 1$ .

Properties of Expectation:

- Linearity: For two random variables  $X$ , and  $Y$ ,

$$\mathbb{E}[\alpha X + \beta Y] = \alpha \mathbb{E}[X] + \beta \mathbb{E}[Y] \quad \text{for any } \alpha, \beta \in \mathbb{R}.$$

Equivalently,  $\mathbb{E}[\alpha X] = \alpha \mathbb{E}[X]$ , &  $\mathbb{E}[X + Y] = \mathbb{E}[X] + \mathbb{E}[Y]$ .

- If  $X = Y$  a.s, then  $\mathbb{E}[X] = \mathbb{E}[Y]$ .
- If  $X \leq Y$  a.s, then  $\mathbb{E}[X] \leq \mathbb{E}[Y]$ .

## Function of random variables

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- Let  $X$  be a random variable. Then  $Y = g(X)$  is a random variable if the function  $g$  is *measurable*, i.e., for any  $\alpha \in \mathbb{R}$ , the inverse map  $Y^{-1}((-\infty, \alpha])$  belongs to the Borel  $\sigma$ -algebra over  $\mathbb{R}$ .
- All continuous functions are measurable. In fact, almost all functions we encounter satisfies this property.
- Example: If  $X$  is a random variable, so are  $\sin(X)$ ,  $\log(X)$ ,  $X^k$ , and so on.
- **Law of the unconscious statistician (LOTUS):** If  $Y = g(X)$ , then

$$\mathbb{E}[Y] = \int y dF_Y(y) = \int_{-\infty}^{\infty} g(x) dF_X(x).$$

There is no need to find the distribution of  $Y$ . Thus, for a continuous r.v.  $X$  with density  $f_X$ , we have

$$\begin{aligned}\mathbb{E}[X^2] &= \int_{-\infty}^{\infty} x^2 f_X(x) dx \\ \mathbb{E}[X^k] &= \int_{-\infty}^{\infty} x^k f_X(x) dx \\ \mathbb{E}[\sin(X)] &= \int_{-\infty}^{\infty} \sin(x) f_X(x) dx.\end{aligned}$$

- $\mathbb{E}[X^k]$  is called the  $k$ -th moment of  $X$ .
- **Variance** of a r.v.  $X$  is defined as  $\mathbb{E}[(X - \mathbb{E}[X])^2] = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$ .

# Characteristic Function

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Characteristic function of a r.v  $X$  is defined as

$$C_X(h) = \mathbb{E}[e^{ihX}], \quad \text{where } i = \sqrt{-1}.$$

- For a continuous r.v,  $C_X(h) = \int_{-\infty}^{\infty} e^{ihx} f_X(x) dx$ .
- $C_X(0) = \mathbb{E}[1] = 1$ .
- $\frac{dC_X(h)}{dh} = \int_{-\infty}^{\infty} (ix) e^{ihx} f_X(x) dx$ .
- $\left. \frac{dC_X(h)}{dh} \right|_{h=0} = \int_{-\infty}^{\infty} (ix) f_X(x) dx = i\mathbb{E}[X]$ .
- How about higher order derivatives?

## Random Vector

---

- A random vector  $X = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix}$  such that each  $X_i, 1 \leq i \leq n$  is a r.v..

- Joint distribution function (CDF)  $F_X : \mathbb{R}^n \rightarrow [0, 1]$  is defined as

$$\begin{aligned} F_X(c_1, c_2, \dots, c_n) &= \mathbb{P}\{\omega \in \Omega | X_1(\omega) \leq c_1, X_2(\omega) \leq c_2, \dots, X_n(\omega) \leq c_n\} \\ &= \mathbb{P}[\cap_{i=1}^n \{\omega \in \Omega | X_i(\omega) \leq c_i\}]. \end{aligned}$$

- The random variables  $X_1, X_2, \dots, X_n$  are jointly continuous if there exists a function  $f_X : \mathbb{R}^n \rightarrow \mathbb{R}_{\geq 0}$

$$F_X(c_1, c_2, \dots, c_n) = \int_{-\infty}^{c_1} \int_{-\infty}^{c_2} \dots \int_{-\infty}^{c_n} f_X(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n.$$

- Random vector  $X = [X_1, \dots, X_n]^\top$  is jointly discrete if each  $X_i$  is a joint discrete random variable. Joint pmf is defined as

$$p_X(c_1, c_2, \dots, c_n) = \mathbb{P}(\{\omega \in \Omega | X_i(\omega) = c_i, 1 \leq i \leq n\}).$$

- Joint Characteristic Function: For a continuous random vector  $X$ ,

$$\begin{aligned} C_X(h_1, h_2, \dots, h_n) &= \mathbb{E}[e^{i(h_1 X_1 + h_2 X_2 + \dots + h_n X_n)}] \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} e^{i(h_1 x_1 + h_2 x_2 + \dots + h_n x_n)} f_X(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n. \end{aligned}$$

- Expectation:  $\mathbb{E}[X] = \begin{bmatrix} \mathbb{E}[X_1] \\ \mathbb{E}[X_2] \\ \vdots \\ \mathbb{E}[X_n] \end{bmatrix} \in \mathbb{R}^n.$

## Computing Marginal Distributions

---

If joint distribution/ density/ mass function is given, we can compute the distribution/ density/ PMF of each individual constituent random variable.

- Joint distribution  $F_X(c_1, c_2, \dots, c_n) = \mathbb{P}[\cap_{i=1}^n \{\omega | X_i(\omega) \leq c_i\}]$ .
- Marginal distribution of the second constituent random variable

$$\begin{aligned}
 F_{X_2}(c_2) &= \mathbb{P}[\{\omega \in \Omega | X_2(\omega) \leq c_2\}] \\
 &= \mathbb{P}[\cap_{i=1, i \neq 2}^n \{\omega | X_i(\omega) \leq \infty\} \cap \{\omega \in \Omega | X_2(\omega) \leq c_2\}] \\
 &= \lim_{c_1 \rightarrow \infty} \lim_{c_3 \rightarrow \infty} \dots \lim_{c_n \rightarrow \infty} F_X(c_1, c_2, \dots, c_n)
 \end{aligned}$$

- Suppose joint density  $f_X(c_1, c_2, \dots, c_n)$  is given, Find  $f_{X_2}(c_2)$ . Recall that

$$\begin{aligned}
 F_X(c_1, c_2, \dots, c_n) &= \int_{x_1=-\infty}^{c_1} \int_{x_2=-\infty}^{c_2} \dots \int_{x_n=-\infty}^{c_n} f_X(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n \\
 F_{X_2}(c_2) &= \lim_{c_i \rightarrow \infty, i \neq 2} F_X(c_1, c_2, \dots, c_n) \\
 &= \int_{x_1=-\infty}^{\infty} \int_{x_2=-\infty}^{c_2} \dots \int_{x_n=-\infty}^{\infty} f_X(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n \\
 &= \int_{x_2=-\infty}^{c_2} \left[ \int_{x_1=-\infty}^{\infty} \dots \int_{x_n=-\infty}^{\infty} f_X(x_1 \dots x_n) dx_1 dx_3 \dots dx_n \right] dx_2 \\
 &=: \int_{x_2=-\infty}^{c_2} f_{X_2}(x_2) dx_2
 \end{aligned}$$

## Example

---

Consider a random vector  $\begin{bmatrix} X \\ Y \end{bmatrix}$  with joint density

$$f_{XY}(x, y) = \begin{cases} x + cy^2, & x \in [0, 1], y \in [0, 1] \\ 0, & \text{otherwise.} \end{cases}$$

- Find the value of  $c$ .
- Find marginal densities  $f_X(x)$  and  $f_Y(y)$ .
- Find the cumulative distribution function  $F_{XY}(c_1, c_2)$ .
- Compute  $\mathbb{P}[0 \leq X \leq \frac{1}{2}, 0 \leq Y \leq \frac{1}{2}]$  using the density and the cumulative distribution function.

# Independence of Random Variables

---

A collection of random variables  $\{X_1, X_2, \dots, X_n\}$  are said to be mutually independent if for any collection of Borel subsets (events on  $\mathbb{R}$ )  $\{A_1, A_2, \dots, A_n\}$  the underlying events  $\{\omega \in \Omega | X_1(\omega) \in A_1\}, \{\omega \in \Omega | X_2(\omega) \in A_2\} \dots$  are mutually independent.

We have the following equivalent conditions that are easier to verify.

- Joint CDF satisfies the following property.

$$\begin{aligned} F_X(c_1, c_2, \dots, c_n) &= \mathbb{P}[\cap_{i=1}^n \{\omega | X_i(\omega) \leq c_i\}] \\ &= \prod_{i=1}^n \mathbb{P}[\{\omega | X_i(\omega) \leq c_i\}] \\ &= F_{X_1}(c_1) \times F_{X_2}(c_2) \times \dots \times F_{X_n}(c_n) \end{aligned}$$

- For a discrete set of random variables, independence is equivalent to joint pmf satisfying

$$p_X(c_1, \dots, c_n) = p_{X_1}(c_1) \times \dots \times p_{X_n}(c_n).$$

- For a continuous set of random variables, independence is equivalent to joint pdf satisfying

$$f_X(c_1, \dots, c_n) = f_{X_1}(c_1) \times \dots \times f_{X_n}(c_n).$$

- Joint characteristic function satisfies

$$C_X(h_1, \dots, h_n) = C_{X_1}(h_1) \times \dots \times C_{X_n}(h_n) \quad \forall \{h_1, h_2, \dots, h_n\}.$$

Only checking  $C_X(h, h, \dots, h) = C_{X_1}(h) \times \dots \times C_{X_n}(h)$  is not enough to conclude that  $X_i$ 's are independent.

- $\mathbb{E}[X_1 X_2 \dots X_n] = \mathbb{E}[X_1] \times \dots \times \mathbb{E}[X_n]$ .
- More generally, for any collection of bounded continuous functions  $\{g_1, g_2, \dots, g_n\}$ ,  $\mathbb{E}[g_1(X_1)g_2(X_2) \dots g_n(X_n)] = \mathbb{E}[g_1(X_1)] \times \dots \times \mathbb{E}[g_n(X_n)]$ .



## Practice Problems

---

Let  $X$  and  $Y$  have joint density

$$f_{XY}(x, y) = \begin{cases} 2e^{-(x+2y)}, & \text{if } x > 0, y > 0, \\ 0, & \text{otherwise.} \end{cases}$$

Determine whether  $X$  and  $Y$  are independent.

Consider a random variable  $X$  with cumulative distribution function given by:

$$F_X(x) = \begin{cases} 1 - 3^{-\lfloor x \rfloor}, & x \geq 0, \\ 0, & \text{otherwise,} \end{cases}$$

where  $\lfloor x \rfloor$  is the floor of  $x$ , i.e., the largest integer smaller than or equal to  $x$ . Is  $X$  a discrete or continuous random variable? Compute  $\mathbb{P}[X = 2]$  and  $\mathbb{P}[X > 2]$ .

Let  $X$  and  $Y$  be two independent random variables, each having uniform distribution over the range  $[0, 1]$ . Let  $Z = \max(X, Y)$  and  $W = \min(X, Y)$ .

1. Determine the CDF and expectation of  $Z$ .
2. Determine the CDF and expectation of  $W$ .
3. Determine the covariance  $\text{cov}(Z, W)$ .

## Correlation and Covariance

---

Correlation between two random variables  $X$  and  $Y$  is defined as  $\mathbb{E}[XY]$ .

Let  $X$  and  $Y$  be discrete random variables that take values as  $X \in \{x_1, x_2, \dots, x_n\}$  and  $Y \in \{y_1, y_2, \dots, y_m\}$ . Let the joint pmf be  $p_{ij} = \mathbb{P}(X = x_i, Y = y_j)$ . Then,

$$\mathbb{E}[XY] = \sum_{i=1}^n \sum_{j=1}^m x_i y_j p_{ij} = x^T P y, \quad \text{where,}$$
$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, \quad y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}, \quad P = \begin{bmatrix} p_{11} & p_{12} & \cdots & p_{1m} \\ p_{21} & p_{22} & \cdots & p_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ p_{n1} & p_{n2} & \cdots & p_{nm} \end{bmatrix}.$$

Covariance between two random variables  $X$  and  $Y$  is

$$\begin{aligned} \text{cov}(X, Y) &= \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])] \\ &= \mathbb{E}[XY - X\mathbb{E}[Y] - Y\mathbb{E}[X] + \mathbb{E}[X]\mathbb{E}[Y]] \\ &= \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y] \end{aligned}$$

Correlation Coefficient

$$\rho_{X,Y} = \frac{\text{cov}(X, Y)}{\sqrt{\text{var}(X)}\sqrt{\text{var}(Y)}}, \quad -1 \leq \rho_{XY} \leq 1.$$

Inner product interpretation

$$x^T y = \sum_{i=1}^n x_i y_i = \|x\| \|y\| \cos \theta \implies \cos \theta = \frac{x^T y}{\|x\| \|y\|}.$$

If  $Y = aX + b$ , then determine  $\rho_{X,Y}$ .

## Properties of Covariance

---

Covariance satisfies the following properties.

- $\text{cov}(X, X) = \text{var}(X)$ .
- $\text{cov}(X, Y) = \text{cov}(Y, X)$ .
- $\text{cov}(aX, Y) = a\text{cov}(X, Y)$ .
- $\text{cov}(X + c, Y) = \text{cov}(X, Y)$ .
- $\text{cov}(X + Z, Y) = \text{cov}(X, Y) + \text{cov}(Z, Y)$ .
- More generally,

$$\text{cov}\left(\sum_{i=1}^n a_i X_i, \sum_{j=1}^m b_j Y_j\right) = \sum_{i=1}^n \sum_{j=1}^m b_j a_i \text{cov}(X_i, Y_j).$$

Two random variables  $X$  and  $Y$  are said to be **uncorrelated** if  $\text{cov}(X, Y) = 0$ . If  $X$  and  $Y$  are independent, then they are uncorrelated. However, the converse is not true.

## Covariance Matrix of a Random Vector

---

For a random vector  $X = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix}$ , the covariance matrix contains the covariance of each pair of constituent random variables.

$$\begin{aligned} \text{cov}(X, X) = \text{cov}(X) &= \begin{bmatrix} \text{cov}(X_1) & \text{cov}(X_1, X_2) & \dots & \text{cov}(X_1, X_n) \\ & & & \vdots \\ & & & \text{cov}(X_n, X_1) & \text{cov}(X_n, X_2) & \dots & \text{cov}(X_n, X_n) \end{bmatrix} \in \mathbb{R}^{n \times n} \\ &= \mathbb{E} \begin{bmatrix} X_1 - \mathbb{E}[X_1] & (X_1 - \mathbb{E}[X_1]) & (X_2 - \mathbb{E}[X_2]) & \dots & (X_n - \mathbb{E}[X_n]) \\ X_2 - \mathbb{E}[X_2] & & & & \\ \vdots & & & & \\ X_n - \mathbb{E}[X_n] & & & & \end{bmatrix} \\ &= \mathbb{E}[(X - \mathbb{E}[X]) (X - \mathbb{E}[X])^\top]. \end{aligned}$$

For two random vectors  $X = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix}$ , and  $Y = \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_m \end{bmatrix}$ , the (cross)-covariance matrix is given by

$$\begin{aligned} \text{cov}(X, Y) &= \begin{bmatrix} \text{cov}(X_1, Y_1) & \text{cov}(X_1, Y_2) & \dots & \text{cov}(X_1, Y_m) \\ & & & \vdots \\ & & & \text{cov}(X_n, Y_1) & \text{cov}(X_n, Y_2) & \dots & \text{cov}(X_n, Y_m) \end{bmatrix} \in \mathbb{R}^{n \times m} \\ &= \mathbb{E}[(X - \mathbb{E}[X]) (Y - \mathbb{E}[Y])^\top]. \end{aligned}$$

## Sum of IID Random Variables

---

- In many applications, we need to repeat the experiment to generate more samples. The outcome of every experiment is random and the experiments are independent.
- Let  $X_i$  be the random variable that represents the outcome of  $i$ -th experiment.
- The collection  $\{X_i\}_{i=1,2,\dots,N}$  is said to be independent and identically distributed (IID) if each  $X_i$  has the same distribution and the random variables in the collection are mutually independent.
- Suppose  $\mathbb{E}[X_i] = \mu$  and  $\text{var}(X_i) = \sigma^2$ . Let  $S = \sum_{i=1}^n X_i$ . Determine the expectation and variance of  $S$ .
- Determine the characteristic function of  $S$  from the characteristic function of  $X_i$ .

## Solution

---

Let  $S = \sum_{i=1}^n X_i$  and  $\bar{S} := \frac{1}{n} \sum_{i=1}^n X_i$ .

$$\mathbb{E}[S] = \mathbb{E}\left[\sum_{i=1}^n X_i\right] = \sum_{i=1}^n \mathbb{E}[X_i] = n\mu.$$

$$\mathbb{E}[\bar{S}] = \mu.$$

The variance of the sum is given by

$$\begin{aligned}\text{var}(S) &= \text{var}\left(\sum_{i=1}^n X_i\right) = \mathbb{E}[(S - \mathbb{E}[S])^2] \\ &= \mathbb{E}\left[\left(\sum_{i=1}^n X_i - n\mu\right)^2\right] \\ &= \mathbb{E}\left[\left(\sum_{i=1}^n (X_i - \mu)\right)^2\right] \\ &= \mathbb{E}\left[\sum_{i=1}^n (X_i - \mu)^2 + \underbrace{\sum_{i \neq j} (X_i - \mu)(X_j - \mu)}\right] \\ &= n\sigma^2,\end{aligned}$$

since when two r.v.s  $X_i$  and  $X_j$  are independent,

$$\mathbb{E}[(X_i - \mathbb{E}[X_i])(X_j - \mathbb{E}[X_j])] = \mathbb{E}[(X_i - \mathbb{E}[X_i])] \times \mathbb{E}[X_j - \mathbb{E}[X_j]] = 0.$$

$$\text{Now: } \text{var}(\bar{S}) = \left(\frac{1}{n}\right)^2 \text{var}(S) = \frac{\sigma^2}{n}$$

More generally, if  $\text{var}(X) = \sigma^2$ , then  $\text{var}(cX) = c^2\sigma^2$ .

## Gaussian Random Variable

---

A Gaussian random variable  $X$  is characterized by two parameters: mean ( $\mu$ ) and variance  $\sigma^2$ , and is denoted  $\mathcal{N}(\mu, \sigma^2)$ . The distribution is defined below.

- If  $\sigma = 0$ , then  $\mathbb{P}[X = \mu] = 1$  and  $\mathbb{P}[X \neq \mu] = 0$ .
- If  $\sigma > 0$ , it is a continuous random variable with density and CDF

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}, \quad \Psi(c) = \int_{-\infty}^c f_X(x) dx.$$

Consequently,

$$\int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} = 1.$$

The characteristic function of  $X \sim \mathcal{N}(\mu, \sigma^2)$  is given by

$$\Phi_X(h) = e^{i\mu h - \frac{h^2\sigma^2}{2}}.$$

Most derivations involving Gaussian random variables and vectors leverage characteristic function.

Suppose  $X_1, X_2, \dots, X_n$  be a collection of Gaussian random variables and are independent. Then, show that  $Z := \sum_{i=1}^n a_i X_i$  is a Gaussian random variable.

## Jointly Gaussian Random Variables

---

**Definition 9.** A collection of random variables  $(X_t)_{t \in T}$  is called jointly Gaussian if every finite linear combination is Gaussian. In particular,  $X$  is a Gaussian random vector if its constituent random variables are jointly Gaussian.

Two random vectors  $X = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix}$  and  $Y = \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_m \end{bmatrix}$  are jointly Gaussian if the collection  $\{X_1, \dots, X_n, Y_1, \dots, Y_m\}$  is jointly Gaussian.

A Gaussian random vector  $X = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix}$  is characterized by two quantities:

mean:  $\mu_X = \mathbb{E}[X] = \begin{bmatrix} \mathbb{E}[X_1] \\ \mathbb{E}[X_2] \\ \vdots \\ \mathbb{E}[X_n] \end{bmatrix} \in \mathbb{R}^n$  and

covariance matrix:  $C_X \in \mathbb{R}^{n \times n}$  with  $(C_X)_{i,j} = \text{cov}(X_i, X_j)$ .

Show that the joint characteristic function of Gaussian random vector  $X$  is given by

$$\Phi_X(h) = e^{ih^\top \mu_X - \frac{h^\top C_X h}{2}}.$$



## Properties of Gaussian Random Vectors

---

If  $X_1, X_2, \dots, X_n$  are jointly Gaussian, then each  $X_i$  is Gaussian.

If each of  $X_1, X_2, \dots, X_n$  are individually Gaussian and independent, then the collection is jointly Gaussian.

If  $X$  is a Gaussian random vector, and  $Y = AX + b$  where  $A$  is a given matrix and  $b$  is a given vector of suitable dimensions, then show that  $Y$  is a Gaussian random vector, and find its mean and covariance.

If a collection of jointly Gaussian random variables are uncorrelated, then they are independent.

Let  $X$  be a Gaussian random vector and  $V$  be another Gaussian random vector uncorrelated with  $X$ . Let  $Y = AX + V$  where  $A$  is a given matrix. Find the mean and covariance of  $Y$ . Is  $Y$  Gaussian? Does the answer change when  $\mathbb{E}[V] = 0$ .

## Inequalities and Bounds

---

Union bound: If  $A_1, A_2, \dots, A_n$  are events,  $\mathbb{P}(\cup_{i=1}^n A_i) \leq \sum_{i=1}^n \mathbb{P}(A_i)$   
(Equality holds when  $A_i$  are disjoint)

Markov's Inequality: Let  $X$  be a non negative r.v. Then, for any  $\epsilon > 0$ ,

$$\mathbb{P}(X \geq \epsilon) \leq \frac{\mathbb{E}[X]}{\epsilon}.$$

Note: This bound is useful for large values of  $\epsilon$ . In particular, if  $\epsilon < \frac{1}{\mathbb{E}[X]}$ , then  $\frac{\mathbb{E}[X]}{\epsilon} > 1$  which is trivial.

Main idea:  $Y \leq X \Rightarrow \mathbb{E}[Y] \leq \mathbb{E}[X]$ . Define

$$Y = \begin{cases} \epsilon, & \text{when } X \geq \epsilon, \\ 0, & \text{otherwise.} \end{cases}$$

Is  $Y \leq X$ ?,  $\mathbb{E}[Y] = ?$

Chebyshev's Inequality: For any random variable  $X$ , with  $\mathbb{E}[X] = \mu$ , and any  $\epsilon > 0$ ,

$$\mathbb{P}[|X - \mu| \geq \epsilon] \leq \frac{\text{var}(X)}{\epsilon^2}.$$

Proof: Apply Markov's inequality to  $Y = (X - \mu)^2$

Application:  $\lim_{n \rightarrow \infty} \mathbb{P}[|\bar{S} - \mu| \geq \epsilon] \leq \frac{\text{var}(\bar{S})}{\epsilon^2} = \frac{\sigma^2}{n\epsilon^2} = 0$ .

## Inequalities and Bounds

---

Hoeffding Inequality: Let  $X_1, X_2, \dots, X_n$  be independent random variables with  $X_i \in [a_i, b_i]$ . Let  $S_n = \sum_{i=1}^n X_i$ . Then,

$$\mathbb{P}[S_n - \mathbb{E}[S_n] \geq \epsilon] \leq e^{-\frac{2\epsilon^2}{\sum_{i=1}^n (b_i - a_i)^2}},$$
$$\mathbb{P}[S_n - \mathbb{E}[S_n] \leq -\epsilon] \leq e^{-\frac{2\epsilon^2}{\sum_{i=1}^n (b_i - a_i)^2}}.$$

If  $X_i$ 's are i.i.d. with  $a_i = 0, b_i = 1$ , then

$$\mathbb{P}\left[\left|\frac{S_n}{n} - \mathbb{E}[X_1]\right| \geq \epsilon\right] \leq 2e^{-2\epsilon^2 n}.$$

Discuss: Confidence interval using Hoeffding and Chebyshev.

Cauchy Schwartz Inequality: For two random variables  $X$  and  $Y$ ,

$$(\mathbb{E}[XY])^2 \leq \mathbb{E}[X^2]\mathbb{E}[Y^2]$$

Proof: Define  $Z = (sX + Y)^2 \geq 0$ . Then, for every  $s \in \mathbb{R}$ ,

$$\begin{aligned}\mathbb{E}[Z] &\geq 0 \\ \implies \mathbb{E}[s^2 X^2 + 2sXY + Y^2] &\geq 0 \\ \implies s^2 \mathbb{E}[X^2] + 2s\mathbb{E}[XY] + \mathbb{E}[Y^2] &\geq 0\end{aligned}$$

Define:  $h(s) := s^2 \mathbb{E}[X^2] + 2s\mathbb{E}[XY] + \mathbb{E}[Y^2]$ . Since  $h(s) \geq 0$  for all  $s \in \mathbb{R}$ , it does not have distinct real roots. From  $b^2 - 4ac \leq 0$  formula for quadratic functions, we obtain the inequality.

Corollary: Correlation coefficient lies in  $[-1, 1]$ .

## Chernoff Bound

---

Note that  $\mathbb{P}(X \geq \epsilon) = \mathbb{P}(e^{tX} \geq e^{t\epsilon})$  for any  $t > 0$  since  $x \geq y \Leftrightarrow e^x \geq e^y$ .  
From Markov's inequality, we have

$$\begin{aligned}\mathbb{P}(X \geq \epsilon) &= \mathbb{P}(e^{tX} \geq e^{t\epsilon}) \\ &\leq \frac{\mathbb{E}[e^{tX}]}{e^{t\epsilon}} \quad \text{for every } t > 0 \\ &\leq \min_{t>0} [e^{-t\epsilon} \mathbb{E}[e^{tX}]] \\ &= \min_{t>0} [e^{-t\epsilon} m_X(t)] \\ &= \min_{t>0} [e^{\log(m_X(t)) - t\epsilon}] \\ &= e^{-\left[\max_{t>0} (t\epsilon - \log(m_X(t)))\right]},\end{aligned}$$

where  $\mathbb{E}[e^{tX}] = m_X(t)$  is called the *moment generating function* of  $X$ .

Let  $X \sim$  Binomial r.v (n,p) with probability mass function given by  $\mathbb{P}(X = k) = \binom{n}{k} p^k (1-p)^{n-k}$ , with  $k = \{0, 1, 2, \dots, n\}$ . Find upper bounds on  $\mathbb{P}(X \geq q)$  using Markov, Chebyshev and Chernoff bounds.

Homework: Plot the true probability and the bounds.

## Distribution of sum of two random variables

---

Let  $X_1$  and  $X_2$  be two continuous random variables,

Let us try to find distribution and density of  $\underline{X_1 + X_2}$  when

- $X_1, X_2$  are arbitrary
- $X_1, X_2$  are independent
- $X_1, X_2$  are IID.

## Convergence of Sequences

---

**Definition 10.** A sequence of real numbers  $(x_n)_{n \in \mathbb{N}} := (x_1, x_2, \dots, x_n, \dots)$  with each  $x_i \in \mathbb{R}$ , is said to converge to  $x^* \in \mathbb{R}$  if of every  $\epsilon > 0$ , there exists  $n_\epsilon$  such that  $|x_n - x^*| < \epsilon$  for every  $n \geq n_\epsilon$ . Then, we write  $\lim_{n \rightarrow \infty} x_n = x^*$ .

Note: The above definition requires us to first conjecture a limit point  $x^*$ , which may not always be trivial.

**Definition 11.** A sequence  $(x_n)_{n \in \mathbb{N}}$  is a Cauchy sequence if

$$\lim_{n, m \rightarrow \infty} |x_n - x_m| = 0.$$

Proposition: If a sequence  $(x_n)_{n \in \mathbb{N}}$  is a Cauchy sequence, then it converges to some finite limit.

Example: Let  $x_n = \frac{1}{n}$ , i.e., the sequence  $(x_n)_{n \in \mathbb{N}} = (1, \frac{1}{2}, \frac{1}{3}, \dots)$ . What is a possible value of  $x^*$ ? Is this sequence a Cauchy sequence?

Convergence of Random Variables:

Consider a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  with  $\Omega = [0, 1]$ , and  $\mathbb{P}[[a, b]] = \mathbb{P}[(a, b)] = b - a$  (uniform distribution). Let  $(X_n)_{n \in \mathbb{N}}$  is a sequence of random variables defined on  $(\Omega, \mathcal{F}, \mathbb{P})$  with

$$X_n(\omega) = \omega^n, \quad \omega \in [0, 1].$$

What do we mean by convergence of this sequence?

## Almost Sure Convergence

---

**Definition 12** (Almost Sure Convergence). *A sequence of random variables  $(X_n)_{n \in \mathbb{N}}$  converges almost surely to a random variable  $X^*$  if*

$$\mathbb{P}[\{\omega : \lim_{n \rightarrow \infty} X_n(\omega) = X^*(\omega)\}] = 1.$$

*Equivalently,  $\mathbb{P}[\{\omega : \lim_{n \rightarrow \infty} X_n(\omega) \neq X^*(\omega)\}] = 0.$*

Note: For a given outcome  $\omega$ ,  $(X_n(\omega))$  is a sequence of real numbers.

Example: Does the sequence with  $X_n(\omega) = \omega^n$ ,  $\omega \in [0, 1]$  converge almost surely to some  $X^*$ ?

Example: Consider a sequence of random variables defined as:

$$\begin{aligned} X_1(\omega) &= 1, & \omega &\in [0, 1], \\ X_2(\omega) &= 1, & \omega &\in [0, 0.5], \\ X_3(\omega) &= 1, & \omega &\in [0.5, 1], \\ X_4(\omega) &= 1, & \omega &\in [0, 0.25], \\ X_5(\omega) &= 1, & \omega &\in [0.25, 0.5], \\ X_6(\omega) &= 1, & \omega &\in [0, 0.75], \quad \text{and so on.} \end{aligned}$$

Does this sequence converge almost surely to some  $X^*$ ?

Let us determine the following quantities.

$$\mathbb{P}(X_n \neq 0) = ?$$

$$\mathbb{E}[X_n] = ?$$

Both the above quantities define a sequence of real numbers. Do those sequence converge?

## Convergence in Probability and in Mean Square Sense

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**Definition 13.** A sequence of random variables  $(X_n)_{n \in \mathbb{N}}$  converges to a r.v.  $X^*$  in probability, denoted  $X_n \xrightarrow{P} X^*$ , if

$$\lim_{n \rightarrow \infty} \mathbb{P}[|X_n - X^*| \geq \epsilon] = 0 \quad \text{for every } \epsilon > 0.$$

**Definition 14.** A sequence of random variables  $(X_n)_{n \in \mathbb{N}}$ , with  $\mathbb{E}[X_n^2] < \infty \quad \forall n$ , converges to  $X^*$  in mean square sense if

$$\lim_{n \rightarrow \infty} \mathbb{E}[(X_n - X^*)^2] = 0.$$

This is denoted by  $X_n \xrightarrow{m.s} X^*$ .

Example: Consider the following two sequence of random variables:

$$X_n(\omega) = \begin{cases} 1, & \omega \in [0, \frac{1}{n}] \\ 0, & \text{otherwise.} \end{cases}$$
$$Y_n(\omega) = \begin{cases} n, & \omega \in [0, \frac{1}{n}] \\ 0, & \text{otherwise.} \end{cases}$$

Determine if the above sequences converge almost surely, in probability and in mean-square sense.



## Convergence in Distribution

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**Definition 15.** A sequence of random variables  $(X_n)_{n \in \mathbb{N}}$  converges in distribution to r.v.  $X^*$  if either of the following are true.

- $\lim_{n \rightarrow \infty} F_{X_n}(x) = F_{X^*}(x)$  at all points of continuity of  $F_{X^*}$ .
- $\lim_{n \rightarrow \infty} \mathbb{E}[e^{ihX_n}] = \mathbb{E}[e^{ihX^*}]$  for all  $h \in \mathbb{R}$ .
- $\mathbb{E}[g(X_n)] \rightarrow \mathbb{E}[g(X^*)]$  for every bounded continuous function  $g$ .

### Example

Let  $X$  be a r.v with CDF

$$F_X(\alpha) = \begin{cases} \frac{\alpha}{\theta}, & \alpha \in [0, \theta], \\ 1, & \alpha \geq \theta, \\ 0, & \alpha \leq 0. \end{cases}$$

Let  $X_1, X_2, \dots, X_n$  be i.i.d with distribution  $F_X$ . Define a sequence

$$Y_k = \max_{i \in \{1, 2, \dots, k\}} X_i.$$

Show that the sequence  $(Y_n)_{n \in \mathbb{N}}$  converges in distribution to a random variable  $Y^*$  whose distribution is given by

$$F_{Y^*}(\alpha) = \begin{cases} 1, & \alpha \geq \theta \\ 0, & \text{otherwise.} \end{cases}$$

- Convergence in probability implies convergence in distribution.
- Mean-square convergence implies convergence in probability.
- Almost sure convergence implies convergence in probability.

## Cauchy Criterion

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Let  $(X_n)_{n \in \mathbb{N}}$  be a sequence of r.v defined on  $(\Omega, \mathcal{F}, \mathbb{P})$ . Then,

- $X_n$  converges almost surely to some random variable if

$$\mathbb{P}\left[\left\{\omega : \lim_{m,n \rightarrow \infty} |X_m(\omega) - X_n(\omega)| = 0\right\}\right] = 1.$$

- $X_n$  converges in probability to some r.v if

$$\lim_{m,n \rightarrow \infty} \mathbb{P}[|X_m - X_n| > \epsilon] = 0.$$

- $X_n$  converges in m.s sense to some r.v if

$$\lim_{n,m \rightarrow \infty} \mathbb{E}[(X_m - X_n)^2] = 0.$$

## Limit Theorems

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**Theorem 1** (Law of Large Numbers). *Let  $X_1, X_2, \dots$  be a sequence of random variables. Each  $X_i$  has mean  $\mu_X$ , i.e.,  $\mathbb{E}[X_i] = \mu_X$ . Define  $S_n := \sum_{i=1}^n X_i$ . Then,*

- $\frac{S_n}{n} \xrightarrow{m.s} \mu_X$  if  $\text{var}(X_i) \leq C \quad \forall i \in \mathbb{N}$  and  $\text{cov}(X_i, X_j) = 0 \quad \forall i \neq j$ .
- If  $X_1, X_2, \dots$  i.i.d, then  $\frac{S_n}{n} \xrightarrow{p} \mu_X$  (Weak law of large numbers)
- If  $X_1, X_2, \dots$  i.i.d, then  $\frac{S_n}{n} \xrightarrow{a.s} \mu_X$  (Strong law of large numbers).

Note: What about the random variable  $\frac{S_n}{n} - \mu_X$ ? What is its mean and variance?

**Theorem 2** (Central Limit Theorem). *Let each  $X_i$  be i.i.d, with  $\mathbb{E}[X_i] = \mu_X$  and  $\text{var}(X_i) = \sigma^2$ . Let  $\mathcal{N}(\mu, \sigma^2)$  denote Gaussian distribution with mean  $\mu$  and variance  $\sigma^2$ . Then,*

- $\left(\frac{S_n - \mu_X n}{\sqrt{n}}\right) \rightarrow^d \mathcal{N}(0, \sigma^2),$
- $\sqrt{n} \left(\frac{\frac{S_n}{n} - \mu_X}{\sigma}\right) \rightarrow^d \mathcal{N}(0, 1),$
- $\sqrt{n} \frac{S_n}{n} = \frac{S_n}{\sqrt{n}} \rightarrow^d \mathcal{N}(\mu_X, \sigma^2).$